

# Matrix-Vector Products

**The Punch Line:** We can use even more compact notation than vector equations by introducing matrices. This will allow us to study systems of linear equations by studying matrices.

**Warm-Up:** Write the following systems of linear equations as vector equations:

(a) The system with variables  $z_1$  and  $z_2$

$$\begin{aligned}z_1 + 2z_2 &= 6 \\ 2z_1 - 5z_2 &= 3.\end{aligned}$$

(b) The system with variables  $x$ ,  $y$ , and  $z$

$$\begin{aligned}x &= x_0 \\ y &= y_0 \\ z &= z_0.\end{aligned}$$

(c) The system with variables  $x_1$ ,  $x_2$ , and  $x_3$

$$\begin{aligned}x_1 + x_2 + x_3 &= 3 \\ x_1 - 2x_2 + x_3 &= 0 \\ x_1 - x_3 &= 0.\end{aligned}$$

$$(a) \quad z_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + z_2 \begin{bmatrix} 2 \\ -5 \end{bmatrix} = \begin{bmatrix} 6 \\ 3 \end{bmatrix}$$

$$(b) \quad x \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + y \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + z \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} x_0 \\ y_0 \\ z_0 \end{bmatrix}$$

$$(c) \quad x_1 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + x_2 \begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix}$$

**The Technique:** The linear combination  $x_1\vec{a}_1 + x_2\vec{a}_2 + \cdots + x_n\vec{a}_n$  is represented by the matrix-vector product

$$A\vec{x} = \begin{bmatrix} \vec{a}_1 & \vec{a}_2 & \cdots & \vec{a}_n \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}.$$

This means that to compute a matrix-vector product, we can just write it back out as a linear combination of the columns of the matrix. This means that matrix-vector products only work when there are precisely as many columns in the matrix as there are entries in the vector.

**1** Compute the following matrix-vector products:

(a)  $\begin{bmatrix} 1 & 2 \\ 2 & -5 \end{bmatrix} \begin{bmatrix} 4 \\ 1 \end{bmatrix}$

(c)  $\begin{bmatrix} 1 & 1 \\ 1 & -1 \\ 2 & 0 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \end{bmatrix}$

(b)  $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$

(d)  $\begin{bmatrix} 1 & 2 & 3 \\ 1 & 4 & 9 \end{bmatrix} \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix}$

(a) We write this as

$$\begin{aligned} \begin{bmatrix} 1 & 2 \\ 2 & -5 \end{bmatrix} \begin{bmatrix} 4 \\ 1 \end{bmatrix} &= 4 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 1 \begin{bmatrix} 2 \\ -5 \end{bmatrix} \\ &= \begin{bmatrix} 4(1) + 1(2) \\ 4(2) + 1(-5) \end{bmatrix} \\ &= \begin{bmatrix} 6 \\ 3 \end{bmatrix}. \end{aligned}$$

(b) This is  $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$ .

(c) This is  $\begin{bmatrix} 4 \\ 2 \\ 6 \end{bmatrix}$ .

(d) This is  $\begin{bmatrix} 5 \\ 17 \end{bmatrix}$ .

**Applications:** The matrix equation  $A\vec{x} = \vec{b}$  can be rephrased as the assertion that  $\vec{b}$  is in the span of the columns of  $A$ . This gives us a geometric interpretation of systems of linear equations when we write them in matrix form—an equation being true means a particular vector,  $\vec{b}$ , is in the span of the collection of vectors  $\{\vec{a}_1, \vec{a}_2, \dots, \vec{a}_n\}$  that make up the matrix  $A$ . In this case, the vector  $\vec{x}$  is the collection of weights in a linear combination that proves  $\vec{b}$  is in the span of the columns of  $A$ .

2 If possible, find at least one solution to each of these matrix equations (if not, explain why it is impossible):

(a) 
$$\begin{bmatrix} 1 & 2 \\ 2 & -5 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} = \begin{bmatrix} 6 \\ 3 \end{bmatrix}$$

(c) 
$$\begin{bmatrix} 1 & 1 \\ 1 & -1 \\ 2 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

(b) 
$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 0 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix}$$

(d) 
$$\begin{bmatrix} 1 & 2 & 3 \\ 1 & 4 & 9 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

(a) We have seen that  $\begin{bmatrix} 4 \\ 1 \end{bmatrix}$  is a solution. To verify (and find any others), we write the augmented matrix  $\begin{bmatrix} 1 & 2 & 6 \\ 2 & -5 & 3 \end{bmatrix}$ .

This has Reduced Echelon Form  $\begin{bmatrix} 1 & 0 & 4 \\ 0 & 1 & 1 \end{bmatrix}$ . From this, we can see that  $\begin{bmatrix} 4 \\ 1 \end{bmatrix}$  is the unique solution (and, if we hadn't already done the multiplication from the previous problem, we have derived it from just the equations).

(b) We start with the augmented matrix  $\begin{bmatrix} 1 & 1 & 1 & 3 \\ 1 & -2 & 1 & 0 \\ 1 & 0 & -1 & 0 \end{bmatrix}$ . This has REF  $\begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix}$ , so we see the unique

solution is  $\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ .

(c) The augmented matrix here is  $\begin{bmatrix} 1 & 1 & b_1 \\ 1 & -1 & b_2 \\ 2 & 0 & b_3 \end{bmatrix}$ . We work just with the left columns of the augmented matrix,

and find that in REF, it looks like  $\begin{bmatrix} 1 & 0 & * \\ 0 & 1 & * \\ 0 & 0 & * \end{bmatrix}$ . This only works for some values that we could put into the  $*$ s,

but not in general. This means that this matrix equation is inconsistent for (most)  $\vec{b}$  (and, therefore, that the columns of the matrix do not span  $\mathbb{R}^3$ ).

(d) Here, the REF of the augmented matrix is  $\begin{bmatrix} 1 & 0 & -3 & 0 \\ 0 & 1 & 3 & 0 \end{bmatrix}$ . We have a free variable in this, so there are infinitely many solutions. We can choose a value for  $x_3$  to get a particular solution—choosing  $x_3 = 0$  gives

the solution  $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ , while choosing  $x_3 = 1$  yields  $\begin{bmatrix} 3 \\ -3 \\ 1 \end{bmatrix}$ . In fact, the set of all solutions can be represented as

$$\vec{x} = t \begin{bmatrix} 3 \\ -3 \\ 1 \end{bmatrix},$$
 which forms a line (more on this in the next section of the book).

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**Under the Hood:** Given any vector  $\vec{b}$ , the equation  $A\vec{x} = \vec{b}$  means that  $\vec{b}$  is in the span of the columns of  $A$ . This means that the span of the columns of  $A$  is related to the set of all possible matrix equations that could be solved with  $A\vec{x}$  as the left hand side—there's one for each  $\vec{b}$  in the span!