

Subspaces of \mathbb{R}^n

The Punch Line: Some parts of \mathbb{R}^n behave exactly like copies of \mathbb{R}^m (where m is smaller than n) that are sitting inside of the larger space.

Warm-Up

- (a) In \mathbb{R}^3 , if you add two vectors in the $y = 0$ plane, is the result guaranteed to be in the $y = 0$ plane?
 - (b) Is the answer the same or different for the $y = 1$ plane?
 - (c) In \mathbb{R}^2 if you take two vectors with x component greater than 1 and add them, is the result guaranteed to have an x component greater than 1?
 - (d) In \mathbb{R}^2 , if you have a vector with x component greater than 1 and take a scalar multiple of it, is the result guaranteed to have an x component greater than 1?
 - (e) In \mathbb{R}^2 , if you have two vectors that each lie on one of the axes, is their sum guaranteed to lie on an axis?
 - (f) In \mathbb{R}^2 , if a vector lies on one of the axes and you take a scalar multiple of it, is the result guaranteed to be on one of the axes?
- (a) Yes—since the y component of each vector is zero, the y component of their sum is $0 + 0 = 0$, so the sum is in the $y = 0$ plane.
- (b) No—in fact, it never does, as the y component of each vector is 1, so the y component of their sum is $1 + 1 = 2$, so the sum is on the $y = 2$ plane rather than the $y = 1$ plane.
- (c) Yes—the x component of the sum will be the sum of the x components, and the sum of two numbers greater than one is greater than one.
- (d) No—the vector $\begin{bmatrix} 2 \\ 0 \end{bmatrix}$ has x component greater than 1, but $\frac{1}{4} \begin{bmatrix} 2 \\ 0 \end{bmatrix} = \begin{bmatrix} 1/2 \\ 0 \end{bmatrix}$ does not.
- (e) No—the vectors $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ lie on the x and y axes, respectively, but their sum is on neither axis.
- (f) Yes—scaling just changes the length, not the direction, of a vector, so one that started on an axis will stay on that same axis after scaling.

The Definition: A *subspace* of \mathbb{R}^n is a subset¹ H that satisfies the following three properties:

- i) H contains the vector $\vec{0}$
- ii) If the vectors \vec{u} and \vec{v} are both in H , then so is $\vec{u} + \vec{v}$
- iii) If the vector \vec{u} is in H , then for any real number c the vector $c\vec{u}$ is in H

If we want to test if a subset H is a subspace, we just have to see if these properties hold for it.

1 Are these things subspaces?

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|------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| (a) The subset $\{\vec{0}\}$ in any \mathbb{R}^n | (f) The set of solutions to the matrix equation $A\vec{x} = \vec{0}$ |
| (b) The $y = 0$ plane in \mathbb{R}^3 | (g) The set of solutions to the matrix equation $A\vec{x} = \vec{b}$ (where $\vec{b} \neq \vec{0}$) |
| (c) The $y = 1$ plane in \mathbb{R}^3 | (h) The span of the columns of the matrix A (for any matrix; for concreteness, feel free to think about 3×3 matrices in particular, although it is true for $m \times n$ matrices for any m and n) |
| (d) The vectors $\begin{bmatrix} x \\ y \end{bmatrix}$ in \mathbb{R}^2 with $x \geq 1$ | |
| (e) The axes in \mathbb{R}^2 | |

- (a) Yes—adding only the zero vector and scaling the zero vector don't do anything to it, and obviously $\vec{0}$ is in $\{\vec{0}\}$ —it's the *only* thing in it!
- (b) Yes— $\vec{0}$ is in the $y = 0$ plane, we saw that property ii) held in the warm-up, and scaling a vector with y component zero won't make the y component nonzero, so property iii) holds as well. Since all the properties are true, the $y = 0$ plane is a subspace of \mathbb{R}^3 .
- (c) No—in the warm-up we saw that property ii) doesn't work, but also iii) fails (scaling by anything but 1 changes the y component), and in fact $\vec{0}$ isn't in the $y = 1$ plane so i) fails as well! Of course, as soon as we notice that *any* of these properties failed, we knew that the $y = 1$ plane is not a subspace.
- (d) No—in the warm-up we saw that property iii) fails, and of course so does i). In this case, property ii) does *not* fail, even though it is not a subspace.
- (e) No—in the warm-up we saw property ii) fails, so this is not a subspace. In this case, property i) and iii) are both true, so it's important to check all three properties.
- (f) Yes—this is actually a very important subspace, called the *null space* of A . We know that $\vec{0}$ is a solution to the equation $A\vec{x} = \vec{0}$ because the product of any matrix with the zero vector is the zero vector. Since multiplication by a matrix is a linear transformation, if we know $A\vec{u} = \vec{0}$ and $A\vec{v} = \vec{0}$, then we also know $A(\vec{u} + \vec{v}) = A\vec{u} + A\vec{v} = \vec{0} + \vec{0} = \vec{0}$, and similarly $A(c\vec{u}) = cA\vec{u} = \vec{0}$, so properties ii) and iii) hold as well.
- (g) No—the quickest way to see this is to consider that $A\vec{0} = \vec{0} \neq \vec{b}$, but in fact properties ii) and iii) fail as well.
- (h) Yes—this is another very important subspace, known as the *column space* of A . The vector $\vec{0}$ is a linear combination of the columns of any matrix A (just use all weights zero), so i) holds. If \vec{u} and \vec{v} are linear combinations of the columns of a matrix A , then so is $\vec{u} + \vec{v}$ (use the sum of the weight from \vec{u} and the one from \vec{v} on each column), and so is $c\vec{u}$ (use c times the weights from \vec{u}). This shows that this is a subspace.

¹A *subset* of \mathbb{R}^n is just some collection of vectors in \mathbb{R}^n .

A Basis: A *basis* for a subspace is a linearly independent set whose span is precisely that subspace. To check if a collection of vectors is a basis for a subspace H , we can put the vectors as the columns of a matrix B . Then the requirement that it is linearly independent is satisfied precisely if every *column* is a pivot column (equivalently, there are no free variables), and the requirement that the span is H is satisfied if the equation $B\vec{x} = \vec{b}$ has a solution precisely when $\vec{b} \in H$. In the special case that H is all of \mathbb{R}^n , these conditions are equivalent to B being invertible.

2 Are the following sets of vectors bases for the specified subspaces? (You may assume that it is indeed a subspace.)

(a) The set $\left\{ \begin{bmatrix} 0 \\ 0 \end{bmatrix} \right\}$ for the subspace $\left\{ \begin{bmatrix} 0 \\ 0 \end{bmatrix} \right\}$

(b) The set $\left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \end{bmatrix} \right\}$ for the “subspace” \mathbb{R}^2

(c) The set $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$ for the subspace $\text{Span} \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$

(d) The set $\left\{ \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ -1 \end{bmatrix} \right\}$ for the subspace of \mathbb{R}^3 consisting of all vectors whose components sum to zero.

(e) The set $\left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \right\}$ for the subspace $\text{Span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \right\}$

(a) No—any set containing the zero vector is linearly dependent, but a basis must be linearly independent.

(b) Yes—they are linearly independent (two vectors are linearly dependent if and only if one is a multiple of the other), and since $B = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$ is invertible, the equation $B\vec{x} = \vec{b}$ has a solution for all \vec{b} in \mathbb{R}^2 .

(c) No—they are linearly independent, but their span is all of \mathbb{R}^2 , while the subspace is not all of \mathbb{R}^2 .

(d) Yes—the two vectors are linearly independent. The equation $B\vec{x} = \vec{b}$ has the augmented matrix

$$\left[\begin{array}{cc|c} 1 & -1 & b_1 \\ 0 & 2 & b_2 \\ -1 & -1 & b_3 \end{array} \right].$$

When row reducing this, we see that we will get a contradiction unless $b_1 + b_2 + b_3 = 0$ (and that if that equation is true the system is consistent). That is, $B\vec{x} = \vec{b}$ has a solution precisely when the components of \vec{b} sum to zero, as desired.

(e) The matrix

$$B = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 0 \\ 1 & 3 & -1 \end{bmatrix}$$

has REF

$$\begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix}.$$

This has a free variable, so the set of vectors is not linearly independent, so can't be a basis, even though its span is clearly the subspace in question.

What's special about a subspace? It "looks like" \mathbb{R}^m living inside \mathbb{R}^n . Eventually, we want to capitalize on this to break complicated descriptions into simpler ones. For example, we might be excited to discover that for a part of \mathbb{R}^{37} that looks like \mathbb{R}^2 , a particularly nasty linear transformation works just like rotation (even if it's hard to describe elsewhere). Subspaces are precisely the parts of \mathbb{R}^n that work nicely with things like linear equations and transformations.