

Complex Tricks That Makes Life Simpler (and Easier)

• $z = a + ib \rightsquigarrow \bar{z} = a - ib$

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$$\Rightarrow \overline{z_1 + z_2} = \bar{z}_1 + \bar{z}_2$$

$$\overline{z_1 z_2} = \bar{z}_1 \bar{z}_2$$

• If $\lambda = a + ib$ solves

$$a_n \lambda^n + \dots + a_1 \lambda + a_0 = 0 \quad (\underline{a_i \in \mathbb{R}})$$

then $\bar{\lambda} = a - ib$ also solves the same eqⁿ:

$$a_n \bar{\lambda}^n + \dots + a_1 \bar{\lambda} + a_0$$

$$= \overline{a_n \lambda^n + \dots + a_1 \lambda + a_0} = \bar{0} = 0.$$

\Rightarrow complex sol's come in pairs!

• If $A \in \mathbb{R}^{n \times n}$ is an $n \times n$ matrix w/ real entries, and $\lambda = a + ib$ is an eigenvalue whose eigenvector is \vec{v} , then $\bar{\vec{v}}$ is an eigenvector of A w/ eigenvalue $\bar{\lambda}$.

$$A\vec{v} = \lambda \vec{v} \Rightarrow \overline{A\vec{v}} = \overline{\lambda \vec{v}}$$

$$\Rightarrow A\bar{\vec{v}} = \bar{\lambda} \bar{\vec{v}}$$

Complex eigenvalues

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$$A = \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & & \vdots \\ a_{n1} & \cdots & a_{nn} \end{bmatrix}$$

$n \times n$ matrix w. real entries, i.e.
 $a_{ij} \in \mathbb{R}$.

\Rightarrow complex eigenvalues appear in pairs, with each member of the pair complex conjugate of the other.

For simplicity, assume A 2×2 matrix.

$$\text{If } \lambda_1 = \alpha + i\beta \quad (\beta \neq 0) \Rightarrow \boxed{\lambda_2 = \bar{\lambda}_1} = \alpha - i\beta.$$

$$\vec{v}_1 \text{ eigenvector} \Rightarrow \boxed{\vec{v}_2 = \overline{\vec{v}_1}}$$

\Rightarrow general solⁿ of $\vec{x}' = A\vec{x}$ is

$$\vec{x}(t) = C_1 e^{(\alpha+i\beta)t} \vec{v}_1 + C_2 e^{(\alpha-i\beta)t} \overline{\vec{v}_1}$$

still complex.

Real form: Euler $\Rightarrow e^{(\alpha+i\beta)t} = e^{\alpha t} (\cos \beta t + i \sin \beta t)$.

$$\text{Write } \vec{v}_1 = \vec{p} + i\vec{q} \quad (\text{with } \vec{p}, \vec{q} \text{ real vectors})$$

$$\Rightarrow e^{(\alpha+i\beta)t} \vec{v}_1 = e^{\alpha t} [\underbrace{\cos \beta t \cdot \vec{p} - \sin \beta t \cdot \vec{q}}_{\text{real part}}] + i e^{\alpha t} [\underbrace{\sin \beta t \cdot \vec{p} + \cos \beta t \cdot \vec{q}}_{\text{imaginary part}}]$$

$$\Rightarrow \boxed{\vec{x}(t) = C_1 e^{\alpha t} [\cos \beta t \cdot \vec{p} - \sin \beta t \cdot \vec{q}] + C_2 e^{\alpha t} [\sin \beta t \cdot \vec{p} + \cos \beta t \cdot \vec{q}]}$$

Decoupling and Nonhomog System

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$$\vec{x}' = A\vec{x} + \vec{f}(t)$$

- ① Eigenvalues & eigenvectors $\lambda_1, \dots, \lambda_n$

$\vec{v}_1, \dots, \vec{v}_n$ linearly indep

$\Rightarrow P = [\vec{v}_1 | \dots | \vec{v}_n]$ diagonalizes A.

$$P^{-1}AP = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}$$

- ② $\vec{x} = P\vec{u}$ decouples the system:

$$\vec{u}' = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix} \vec{u} + \underbrace{P^{-1}\vec{f}(t)}_{\approx \begin{bmatrix} g_1(t) \\ \vdots \\ g_n(t) \end{bmatrix}}$$

i.e. $\begin{cases} u'_1 = \lambda_1 u_1 + g_1(t) \\ \vdots \\ u'_n = \lambda_n u_n + g_n(t) \end{cases}$

- ③ Solve each u_i (using integrating factors)

Solve \vec{x} by

$$\vec{x} = P\vec{u}$$