

# Sol<sup>n</sup>s HW02-27-12:

1. Matching: By sketching a few vectors along  $x$ -axis,  $y$ -axis, we see that the matches are C, A, B, D.

Stability: A: stable, since <sup>all</sup> trajectories near 0 stays close to 0. (circle around).

B: unstable, since some (in fact most of the) trajectories near 0 go away.

C: unstable, since all trajectories near 0 go away.

D: stable, since All trajectories near 0 spiral into it; hence stay close.

## Phase Portraits from Nullclines

$$14: \begin{cases} x' = xy \\ y' = y - x^2 + 1 \end{cases}$$

$v$ -nullcline:  $xy = 0$  i.e.  $x$ -axis and  $y$ -axis

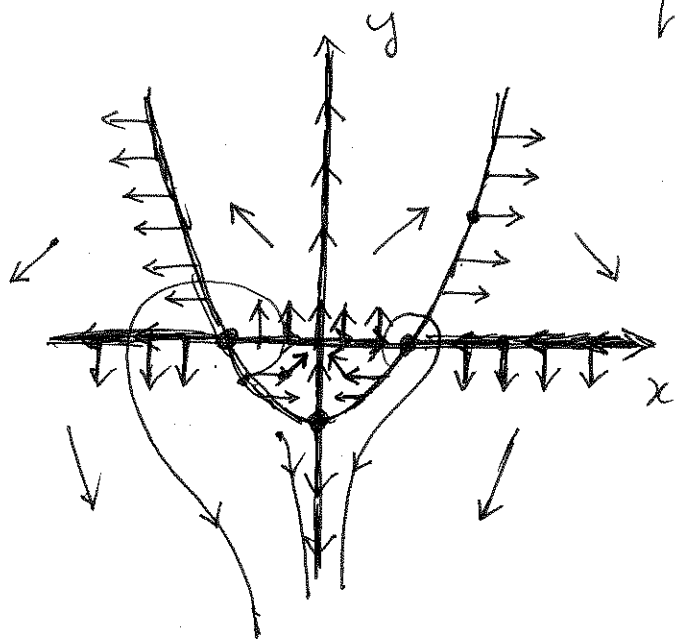
$h$ -nullcline:  $y - x^2 + 1 = 0$  i.e.  $y = x^2 - 1$

equilibria = intersection of  $v$ -nullcline w/  $h$ -nullcline  
 $= (0, -1), (-1, 0), (1, 0)$

At  $(2, 0)$ , vector is  $(0, -3)$









"  $(0, 0)$ , " "  $(0, 1)$

"  $(0, -2)$ , " "  $(0, -1)$



At  $(\pm 2, 3)$ , vector is  $(\pm 6, 0)$ ; at  $(\pm \frac{1}{2}, -\frac{3}{4})$ , vector is  $(\mp \frac{3}{8}, 0)$ .

The nullclines divide the phase plane into 8 regions. We choose appropriate points to determine the directions of vector field in these regions:

At $(-2, 1)$ ,	vector is $(-2, -2)$ :	
" $(-1, 1)$ ,	" " $(-1, 1)$ :	
" $(1, 1)$ ,	" " $(1, 1)$ :	
" $(2, 1)$ ,	" " $(2, -2)$ :	
" $(-2, -1)$ ,	" " $(2, -4)$ :	
" $(-\frac{1}{2}, -\frac{1}{2})$ ,	" " $(\frac{1}{4}, \frac{1}{4})$ :	
" $(\frac{1}{2}, -\frac{1}{2})$ ,	" " $(-\frac{1}{4}, \frac{1}{4})$ :	
" $(2, -1)$ ,	" " $(-2, -4)$ :	

All equilibria are unstable.

$$17: \begin{cases} x' = 1 - x^2 - y^2 \\ y' = x \end{cases}$$

v-nullcline:  $1 - x^2 - y^2 = 0$

h-nullcline:  $x = 0$ .

equilibria  $(0, \pm 1)$ .

$(0, 1)$  is stable;

$(0, -1)$  is unstable.

