

Differential Equations

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Higher Order Linear Equations

Consider nth-order equation:

$$L[y] = \frac{d^n y}{dt^n} + p_1(t) \frac{d^{n-1} y}{dt^{n-1}} + \cdots + p_{n-1}(t) \frac{dy}{dt} + p_n(t)y = g(t)$$

$$y(t_0) = y_0, \quad y'(t_0) = y'_0, \quad \dots, \quad y^{(n-1)}(t_0) = y_0^{(n-1)}$$

Def: For a collection of solutions $\{y_1, y_2, \dots, y_n\}$ the **Wronskian** is

$$W(y_1, \dots, y_n) = \begin{vmatrix} y_1 & y_2 & \cdots & y_n \\ y_1' & y_2' & \cdots & y_n' \\ \vdots & \vdots & \ddots & \vdots \\ y_1^{(n-1)} & y_2^{(n-1)} & \cdots & y_n^{(n-1)} \end{vmatrix}$$

Def: A collection of functions $\{f_1, f_2, \dots, f_n\}$ are called **Linearly Independent** if

$$k_1 f_1(t) + k_2 f_2(t) + \cdots + k_n f_n(t) = 0 \implies k_1 = k_2 = \cdots = k_n = 0$$

Theorem:

Consider the homogeneous equation with p_1, p_2, \dots, p_n where each is continuous on the interval $I = (a, b)$. Let y_1, y_2, \dots, y_n each be solutions of the differential equation. If the Wronskian $W = W[y_1, y_2, \dots, y_n](t_0) \neq 0$ for some $t_0 \in I$ then $W \neq 0$ for all $t \in I$ and any solution of the differential equation can be expressed as

$$y(t) = c_1 y_1(t) + \cdots + c_n y_n(t).$$

Homogeneous equation:

$$L[y] = y^{(n)} + p_1(t)y^{(n-1)} + \cdots + p_{n-1}(t)y' + p_n(t)y = 0.$$

$$y(t_0) = y_0, \quad y'(t_0) = y'_0, \quad \dots, \quad y^{(n-1)}(t_0) = y_0^{(n-1)}$$

General solution:

$$y = c_1 y_1(t) + c_2 y_2(t) + \cdots + c_n y_n(t)$$

Determining coefficients:

$$c_1 y_1(t_0) + \cdots + c_n y_n(t_0) = y_0$$

$$c_1 y_1'(t_0) + \cdots + c_n y_n'(t_0) = y'_0$$

$$\vdots$$

$$c_1 y_1^{(n-1)}(t_0) + \cdots + c_n y_n^{(n-1)}(t_0) = y_0^{(n-1)}$$

Higher Order Equations

EX1

$$y''' + y' = 0, \quad y_1(t) = 1, \quad y_2(t) = \cos(t), \quad y_3(t) = \sin(t), \quad y(0) = 2, \quad y'(0) = 3, \quad y''(0) = -1$$

Wronskian

$$W[y_1, y_2, y_3](t) = \det \begin{bmatrix} 1 & \cos(t) & \sin(t) \\ 0 & -\sin(t) & \cos(t) \\ 0 & -\cos(t) & -\sin(t) \end{bmatrix} = \sin^2(t) - (-\cos^2(t)) = \sin^2(t) + \cos^2(t) = 1.$$

$t_0 = 0$:

$$W(t_0) = \det \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix} = (1) \det \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} = (1)(0 - (-1)) = 1 \checkmark$$

$$\begin{aligned} \text{Thm} \Rightarrow y(t) &= c_1 y_1(t) + c_2 y_2(t) + c_3 y_3(t) \\ &= c_1 + c_2 \cos(t) + c_3 \sin(t). \end{aligned}$$

Initial conditions

$$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ -1 \end{bmatrix}, \Rightarrow c_1 = 1, c_2 = 1, c_3 = 3 \Rightarrow \text{Solution } y(t) = 1 + \cos(t) + 3\sin(t).$$

Higher Order Equations

EX: $y''' + 2y'' - y' - 2y = 0$, $y_1(t) = e^t$, $y_2(t) = e^{-t}$, $y_3(t) = e^{-3t}$, $y(0) = 4$, $y'(0) = -2$, $y''(0) = 12$

Wronskian

$$\begin{aligned} t_0 = 0, W[y_1, y_2, y_3](t_0) &= \det \begin{bmatrix} y_1(t_0) & y_2(t_0) & y_3(t_0) \\ y_1'(t_0) & y_2'(t_0) & y_3'(t_0) \\ y_1''(t_0) & y_2''(t_0) & y_3''(t_0) \end{bmatrix} = \det \begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & -3 \\ 1 & 1 & 9 \end{bmatrix} \\ &= (1) \det \begin{bmatrix} -1 & -3 \\ 1 & 9 \end{bmatrix} + (-1) \det \begin{bmatrix} 1 & 1 \\ 1 & 9 \end{bmatrix} + (1) \det \begin{bmatrix} 1 & 1 \\ -1 & -3 \end{bmatrix} \\ &= -9 + 3 - 9 + 1 + (-3) + 1 = -18 + 2 = -16 \neq 0 \end{aligned}$$

thm $\Rightarrow y(t) = c_1 e^t + c_2 e^{-t} + c_3 e^{-3t}$

initial conditions

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & -3 \\ 1 & 1 & 9 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 4 \\ -2 \\ 12 \end{bmatrix} \Rightarrow c_1 = 2, c_2 = 1, c_3 = 1 \Rightarrow y(t) = 2e^t + e^{-t} + e^{-3t}$$

Higher Order Equations

EX: Are the following functions linearly independent

$$f_1(t) = 1, f_2(t) = t, f_3(t) = \frac{1}{2}t^2, -\infty < t < \infty$$

$$k_1 f_1(t) + k_2 f_2(t) + k_3 f_3(t) = 0, \quad t_0 = 0, t_1 = 1, t_2 = -1$$

$$k_1 f_1(t_0) + k_2 f_2(t_0) + k_3 f_3(t_0) = 0$$

$$k_1 f_1(t_1) + k_2 f_2(t_1) + k_3 f_3(t_1) = 0$$

$$k_1 f_1(t_2) + k_2 f_2(t_2) + k_3 f_3(t_2) = 0$$

$$\underbrace{\begin{bmatrix} f_1(t_0) & f_2(t_0) & f_3(t_0) \\ f_1(t_1) & f_2(t_1) & f_3(t_1) \\ f_1(t_2) & f_2(t_2) & f_3(t_2) \end{bmatrix}}_A \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix} = 0$$

if $\det(A) \neq 0 \Rightarrow k_1 = k_2 = k_3 = 0$.

$$\underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & \frac{1}{2} \\ 1 & -1 & \frac{1}{2} \end{bmatrix}}_A \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{aligned} \det(A) &= (1) \det \begin{bmatrix} 1 & \frac{1}{2} \\ -1 & \frac{1}{2} \end{bmatrix} \\ &= \frac{1}{2} - (-\frac{1}{2}) = 1 \neq 0 \\ &\Rightarrow k_1 = k_2 = k_3 = 0. \end{aligned}$$

$$\begin{aligned} &\left\{ \begin{array}{l} k_1 = 0 \\ k_1 + k_2 + \frac{1}{2}k_3 = 0 \\ k_1 - k_2 + \frac{1}{2}k_3 = 0 \end{array} \right\} \Rightarrow \\ &= \left\{ \begin{array}{l} k_1 = 0 \\ k_2 + \frac{1}{2}k_3 = 0 \\ k_3 = 0 \end{array} \right\} = \left\{ \begin{array}{l} k_1 = 0 \\ k_2 = 0 \\ k_3 = 0 \end{array} \right\} \end{aligned}$$

Higher Order Equations & Systems of Equations

Existence, Uniqueness, Robustness

Higher Order ODEs & Systems of ODEs

Summary: Higher-Order ODEs and Systems of ODEs

Higher-Order ODEs

$$y^{(m)}(t) = f(t, y, y', \dots, y^{(m-1)}), \quad a \leq t \leq b$$

$$y(a) = \alpha_1, y'(a) = \alpha_2, \dots, y^{(m-1)}(a) = \alpha_m$$



System of ODEs

$$\frac{du_1}{dt} = f_1(t, u_1, u_2, \dots, u_m),$$

$$\frac{du_2}{dt} = f_2(t, u_1, u_2, \dots, u_m),$$

⋮

$$\frac{du_m}{dt} = f_m(t, u_1, u_2, \dots, u_m),$$

$$u_1(a) = \alpha_1, u_2(a) = \alpha_2, \dots, u_m(a) = \alpha_m$$

System for Higher-Order ODEs

$$\frac{du_1}{dt} = \frac{dy}{dt} = u_2,$$

$$\frac{du_2}{dt} = \frac{dy'}{dt} = u_3,$$

⋮

$$\frac{du_{m-1}}{dt} = \frac{dy^{(m-2)}}{dt} = u_m$$

$$\frac{du_m}{dt} = \frac{dy^{(m-1)}}{dt} = y^{(m)} = f(t, y, y', \dots, y^{(m-1)})$$

$$= f(t, u_1, u_2, \dots, u_m)$$

$$u_1(a) = y(a) = \alpha_1, \quad u_2(a) = y'(a) = \alpha_2,$$

$$\dots, \quad u_m(a) = y^{(m-1)}(a) = \alpha_m$$

Well-posedness

Lipschitz condition: A function $f(t, y_1, \dots, y_m)$ is called **Lipschitz** if for some constant L

$$|f(t, u_1, \dots, u_m) - f(t, z_1, \dots, z_m)| \leq L \sum_{j=1}^m |u_j - z_j|$$

for all (t, u_1, \dots, u_m) and (t, z_1, \dots, z_m) in D , where

$$D = \{(t, u_1, \dots, u_m) \mid a \leq t \leq b \text{ and } -\infty < u_i < \infty, \text{ for each } i = 1, 2, \dots, m\}$$

Robustness to perturbations

For any $\epsilon > 0$, consider the perturbation to the ODE

$$\tilde{\alpha} = \alpha + \delta_0, \quad \tilde{f}_i = f_i + \delta_i(t),$$

where $|\delta_0| < \delta, |\delta_i(t)| < \delta$. Let \tilde{y} be the solution to the ODE with $\tilde{\alpha}$ and \tilde{f}_i .

We say the solution is **robust to perturbations** if there is a $\delta > 0$

so that $|\tilde{y}(t) - y(t)| < \epsilon$.

Theorem (systems of ODEs): If the functions f_i in the system of ODEs each satisfy the **Lipschitz condition** on D then

- (i) there exists a solution
- (ii) the solution is unique
- (iii) robust to perturbations (initial conditions, rhs).



Corollary (higher-order ODEs): If the functions f of the ODE satisfies the **Lipschitz condition** on D then

- (i) there exists a solution
- (ii) the solution is unique
- (iii) robust to perturbations (initial conditions, rhs).

Lipschitz Continuity for Functions of \mathbb{R}^n

Definition: A function $f(t, y_1, \dots, y_m)$ is called Lipschitz if for some constant L

$$|f(t, u_1, \dots, u_m) - f(t, z_1, \dots, z_m)| \leq L \sum_{j=1}^m |u_j - z_j|$$

for all (t, u_1, \dots, u_m) and (t, z_1, \dots, z_m) in D , where

$$D = \{(t, u_1, \dots, u_m) \mid a \leq t \leq b \text{ and } -\infty < u_i < \infty, \text{ for each } i = 1, 2, \dots, m\}$$

Example: $f(t, u_1, u_2) = u_1 u_2$ **not Lipschitz!**

$$|u_1 u_2 - z_1 z_2| \stackrel{?}{\leq} L (|u_1 - z_1| + |u_2 - z_2|)$$

let $z_1 = u_1$, then for any L , we have

$$|u_1 u_2 - u_1 z_2| = |u_1| |u_2 - z_2| > L |u_2 - z_2| \text{ for } |u_1| > L. \Rightarrow \underline{\text{not Lipschitz.}}$$

System of ODEs

$$\frac{du_1}{dt} = f_1(t, u_1, u_2, \dots, u_m),$$

$$\frac{du_2}{dt} = f_2(t, u_1, u_2, \dots, u_m),$$

\vdots

$$\frac{du_m}{dt} = f_m(t, u_1, u_2, \dots, u_m),$$

$$u_1(a) = \alpha_1, u_2(a) = \alpha_2, \dots, u_m(a) = \alpha_m$$

Example: $f(t, u_1, u_2) = tu_1 + tu_2$ is Lipschitz.

$a \leq t \leq b$, let $L = \max\{a, b\}$, then

$$|t u_1 + t u_2 - (t z_1 + t z_2)| = |t| (|u_1 - z_1| + |u_2 - z_2|)$$

$$\leq |t| (|u_1 - z_1| + |u_2 - z_2|)$$

$$\leq L (|u_1 - z_1| + |u_2 - z_2|) \checkmark$$

$\Rightarrow f$ is Lipschitz.

Higher Order Linear Equations

Undetermined Coefficients

Variation of Parameters

Higher Order Linear Equations

Consider nth-order equation:

$$L[y] = \frac{d^n y}{dt^n} + p_1(t) \frac{d^{n-1} y}{dt^{n-1}} + \cdots + p_{n-1}(t) \frac{dy}{dt} + p_n(t)y = g(t)$$

$$y(t_0) = y_0, \quad y'(t_0) = y'_0, \quad \dots, \quad y^{(n-1)}(t_0) = y_0^{(n-1)}$$

Homogeneous equation:

$$L[y] = y^{(n)} + p_1(t)y^{(n-1)} + \cdots + p_{n-1}(t)y' + p_n(t)y = 0.$$

$$y(t_0) = y_0, \quad y'(t_0) = y'_0, \quad \dots, \quad y^{(n-1)}(t_0) = y_0^{(n-1)}$$

General solution:

$$y = c_1 y_1(t) + c_2 y_2(t) + \cdots + c_n y_n(t)$$

Inhomogeneous equation:

$$L[y] = y^{(n)} + p_1(t)y^{(n-1)} + \cdots + p_{n-1}(t)y' + p_n(t)y = g(t)$$

$$y(t_0) = y_0, \quad y'(t_0) = y'_0, \quad \dots, \quad y^{(n-1)}(t_0) = y_0^{(n-1)}$$

General solution:

$$y = c_1 y_1(t) + c_2 y_2(t) + \cdots + c_n y_n(t) + S(t) \quad L[S] = g(t).$$

Theorem: Consider the linear equation with $p_1(t), p_2(t), \dots, p_n(t)$ where each is continuous on the interval $I = (a, b)$. The solution $y(t)$ exists on the interval I and is unique.

Theorem: Consider the homogeneous equation with p_1, p_2, \dots, p_n where each is continuous on the interval $I = (a, b)$. Let y_1, y_2, \dots, y_n each be solutions of the differential equation. If the Wronskian $W = W[y_1, y_2, \dots, y_n](t_0) \neq 0$ for some $t_0 \in I$ then $W \neq 0$ for all $t \in I$ and any solution of the differential equation can be expressed as $y(t) = c_1 y_1(t) + \cdots + c_n y_n(t)$.

Higher Order Linear Equations

Method of Undetermined Coefficients

Higher Order Linear Equations: Constant Coefficients

Homogeneous equation with constant coefficients:

$$L[y] = a_0 y^{(n)} + a_1 y^{(n-1)} + \dots + a_{n-1} y' + a_n y = 0.$$

$$y(t_0) = y_0, \quad y'(t_0) = y'_0, \quad \dots, \quad y^{(n-1)}(t_0) = y_0^{(n-1)}$$



General solution:

$$y = c_1 y_1(t) + c_2 y_2(t) + \dots + c_n y_n(t)$$

Determining coefficients:

$$c_1 y_1(t_0) + \dots + c_n y_n(t_0) = y_0$$

$$c_1 y_1'(t_0) + \dots + c_n y_n'(t_0) = y'_0$$

⋮

$$c_1 y_1^{(n-1)}(t_0) + \dots + c_n y_n^{(n-1)}(t_0) = y_0^{(n-1)}$$

Candidate solution

$$\tilde{y}(t) = e^{rt}$$

$$L[y] = a_0 r^n e^{rt} + a_1 r^{n-1} e^{rt} + \dots + a_{n-1} r e^{rt} + a_n e^{rt} = 0$$

$$\Rightarrow \underline{p(r) = a_0 r^n + a_1 r^{n-1} + \dots + a_{n-1} r + a_n = 0}$$

If the roots of $p(r) = 0$ are all real ^{characteristic polynomial} and they are all distinct then

$$y_1(t) = e^{r_1 t}, \quad y_2(t) = e^{r_2 t}, \quad \dots, \quad y_n(t) = e^{r_n t}$$

The general solution

$$y(t) = c_1 e^{r_1 t} + c_2 e^{r_2 t} + \dots + c_n e^{r_n t}$$

Higher Order Linear Equations: Constant Coefficients

$$\text{Ex: } \left\{ \begin{array}{l} y^{(4)} + y^{(3)} - 7y^{(2)} - y^{(1)} + 6y = 0 \\ y(0) = 1, y'(0) = 0, y''(0) = -2, y'''(0) = -1 \end{array} \right\}$$

$$p(r) = r^4 + r^3 - 7r^2 - r + 6 = 0$$

$$r_1 = 1, r_2 = -1, r_3 = 2, r_4 = -3$$

$$y(t) = c_1 e^t + c_2 e^{-t} + c_3 e^{2t} + c_4 e^{-3t} \leftarrow \text{general solution}$$

Now we need to find c_1, c_2, c_3, c_4 so $y(t)$ matches the initial conditions.

$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 2 & -3 \\ 1 & 1 & 4 & 9 \\ 1 & -1 & -8 & -27 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ -2 \\ -1 \end{bmatrix} \Rightarrow \underline{c} = \begin{bmatrix} \frac{11}{8} \\ \frac{5}{12} \\ \frac{-2}{3} \\ \frac{-1}{8} \end{bmatrix} \Rightarrow c_1 = \frac{11}{8}, c_2 = \frac{5}{12}, c_3 = \frac{-2}{3}, c_4 = \frac{-1}{8}$$

$$\Rightarrow y(t) = \frac{11}{8} e^t + \frac{5}{12} e^{-t} + \frac{-2}{3} e^{2t} + \frac{-1}{8} e^{-3t}$$

Higher Order Linear Equations

Method of Undetermined Coefficients

Real and Distinct Roots

Higher Order Linear Equations: Constant Coefficients (Real and Distinct Roots)

Homogeneous equation with constant coefficients:

$$L[y] = a_0y^{(n)} + a_1y^{(n-1)} + \cdots + a_{n-1}y' + a_ny = 0.$$

$$y(t_0) = y_0, \quad y'(t_0) = y'_0, \quad \dots, \quad y^{(n-1)}(t_0) = y_0^{(n-1)}$$

Summary of Solution Technique:

Find roots of the characteristic polynomial:

$$\rho(r) = a_0r^n + a_1r^{n-1} + \cdots + a_{n-1}r + a_n = 0$$

Are all the roots real and distinct?

Yes, then use **general solution** form

$$y = c_1e^{r_1t} + c_2e^{r_2t} + \cdots + c_ne^{r_nt}$$

Find coefficients using initial conditions by solving

$$c_1y_1(t_0) + \cdots + c_ny_n(t_0) = y_0$$

$$c_1y_1'(t_0) + \cdots + c_ny_n'(t_0) = y_0'$$

\vdots

$$c_1y_1^{(n-1)}(t_0) + \cdots + c_ny_n^{(n-1)}(t_0) = y_0^{(n-1)}$$

No, then need to use another method.

Higher Order Linear Equations: Constant Coefficients

Inhomogeneous equation with constant coefficients:

$$L[y] = a_0 y^{(n)} + a_1 y^{(n-1)} + \cdots + a_{n-1} y' + a_n y = g(t)$$

$$y(t_0) = y_0, \quad y'(t_0) = y'_0, \quad \dots, \quad y^{(n-1)}(t_0) = y_0^{(n-1)}$$



General solution:

$$y = c_1 y_1(t) + c_2 y_2(t) + \cdots + c_n y_n(t) + S(t)$$

$$L[S] = g(t).$$

Determining coefficients:

$$c_1 y_1(t_0) + \cdots + c_n y_n(t_0) = y_0 - S(t_0)$$

$$c_1 y_1'(t_0) + \cdots + c_n y_n'(t_0) = y'_0 - S'(t_0)$$

$$\vdots$$

$$c_1 y_1^{(n-1)}(t_0) + \cdots + c_n y_n^{(n-1)}(t_0) = y_0^{(n-1)} - S^{(n-1)}(t_0)$$

Higher Order Linear Equations: Constant Coefficients (Real and Distinct Roots)

Ex: $y^{(3)} - 2y^{(2)} - y' + 2y = 3e^t$
 $y(0) = 5, y'(0) = 3, y''(0) = 9$

$$p(r) = r^3 - 2r^2 - r + 2 = 0$$

$$p(r) = (r^2 - 1)(r - 2) = (r - 1)(r + 1)(r - 2)$$

$$r_1 = 1, r_2 = -1, r_3 = 2$$

$$y_1(t) = e^t, y_2(t) = e^{-t}, y_3(t) = e^{2t}$$

$$\rightarrow y(t) = c_1 e^t + c_2 e^{-t} + c_3 e^{2t} + s(t)$$

$$\mathcal{L}[s] = 3e^t, \quad s(t) = (A_1 + A_2 t)e^t$$

$$s'(t) = A_2 e^t + (A_1 + A_2 t)e^t = (A_1 + A_2)e^t + A_2 t e^t$$

$$s''(t) = A_2 e^t + A_2 e^t + (A_1 + A_2 t)e^t = (A_1 + 2A_2)e^t + A_2 t e^t = -3e^t + \frac{-3}{2} t e^t \Big|_{t=0} = -3$$

$$s^{(3)}(t) = A_2 e^t + A_2 e^t + A_2 e^t + (A_1 + A_2 t)e^t = (A_1 + 3A_2)e^t + A_2 t e^t$$

$$e^t (A_1 + 3A_2 - 2A_1 - 4A_2 - A_1 - A_2 + 2A_1) + t e^t (A_2 - 2A_2 - A_2 + 2A_2) = 3e^t$$

$$(0 \cdot A_1 - 2A_2)e^t + (0 \cdot A_1 + 0 \cdot A_2)t e^t = 3e^t + 0 \cdot t e^t$$

$$\Rightarrow -2A_2 = 3, \quad 0 = 0 \Rightarrow A_2 = -\frac{3}{2}$$

$$\Rightarrow s(t) = -\frac{3}{2} t e^t, \quad s'(0) = -\frac{3}{2}$$

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & 2 \\ 1 & 1 & 4 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 5 - 0 \\ 3 - (-\frac{3}{2}) \\ 9 - (-3) \end{bmatrix}$$

Higher Order Linear Equations: Constant Coefficients (Real and Distinct Roots)

Inhomogeneous equation with constant coefficients:

$$L[y] = a_0 y^{(n)} + a_1 y^{(n-1)} + \dots + a_{n-1} y' + a_n y = g(t)$$

$$y(t_0) = y_0, \quad y'(t_0) = y'_0, \quad \dots, \quad y^{(n-1)}(t_0) = y_0^{(n-1)}$$

Summary of Solution Technique:

Find roots of the characteristic polynomial:

$$\rho(r) = a_0 r^n + a_1 r^{n-1} + \dots + a_{n-1} r + a_n = 0$$

Are all the roots real and distinct?

Yes, then use **general solution** form

$$y = c_1 e^{r_1 t} + c_2 e^{r_2 t} + \dots + c_n e^{r_n t} + S(t)$$

Find special solution solving $L[S] = g(t)$.

Find coefficients using initial conditions by solving

$$c_1 y_1(t_0) + \dots + c_n y_n(t_0) = y_0 \quad \text{--- } S(t_0)$$

$$c_1 y_1'(t_0) + \dots + c_n y_n'(t_0) = y_0' \quad \text{--- } S'(t_0)$$

⋮

$$c_1 y_1^{(n-1)}(t_0) + \dots + c_n y_n^{(n-1)}(t_0) = y_0^{(n-1)} \quad \text{--- } S^{(n-1)}(t_0)$$

No, then need to use another method.

Higher Order Linear Equations

Method of Undetermined Coefficients

Distinct Real and Complex Roots (possibly mixed)

Higher Order Linear Equations: Constant Coefficients (Distinct Roots, Real and Complex-Valued)

Homogeneous equation with constant coefficients:

$$L[y] = a_0 y^{(n)} + a_1 y^{(n-1)} + \dots + a_{n-1} y' + a_n y = 0$$
$$y(t_0) = y_0, \quad y'(t_0) = y'_0, \quad \dots, \quad y^{(n-1)}(t_0) = y_0^{(n-1)}$$

Summary of Solution Technique:

Find roots of the characteristic polynomial:

$$\rho(r) = a_0 r^n + a_1 r^{n-1} + \dots + a_{n-1} r + a_n = 0$$

Are the roots distinct real and complex-valued?

Yes, then use **general solution form**

$$y(t) = c_1 \exp(t\lambda_1) \cos(\mu_1 t) + c_2 \exp(t\lambda_1) \sin(\mu_1 t) + \dots + c_{2k-1} \exp(t\lambda_k) \cos(\mu_k t) + c_{2k} \exp(t\lambda_k) \sin(\mu_k t) \\ + c_{2k+1} \exp(tr_{2k+1}) + \dots + c_n \exp(tr_n).$$

Find coefficients using initial conditions by solving

$$c_1 y_1(t_0) + \dots + c_n y_n(t_0) = y_0$$
$$c_1 y_1'(t_0) + \dots + c_n y_n'(t_0) = y_0'$$
$$\vdots$$
$$c_1 y_1^{(n-1)}(t_0) + \dots + c_n y_n^{(n-1)}(t_0) = y_0^{(n-1)}$$

No, then need to use another method.

Lemma: Roots of a polynomial $p(r)$ with real coefficients have any complex-valued roots occurring in conjugate pairs $r_+ = \lambda + i\mu$, $r_- = \lambda - i\mu$.

Exponentials:

$$\exp(tr_-) = \exp((\lambda - i\mu)t) = e^{\lambda t} (\cos(\mu t) - i e^{\lambda t} \sin(\mu t))$$
$$\exp(tr_+) = \exp((\lambda + i\mu)t) = e^{\lambda t} (\cos(\mu t) + i e^{\lambda t} \sin(\mu t))$$

Lemma: For the two complex-valued roots r_-, r_+ , we have any function which is a linear combination of the complex exponentials can be expressed in terms of real-valued functions as

$$\tilde{y}(t) = \tilde{c}_+ \exp(tr_+) + \tilde{c}_- \exp(tr_-)$$
$$= c_+ \exp(t\lambda) \cos(\mu t) + c_- \exp(t\lambda) \sin(\mu t)$$

Higher Order Linear Equations: Constant Coefficients (Complex Roots)

Ex: $y^{(3)} + y = 0$

$y(0) = 2, y'(0) = -1, y''(0) = 1 - \frac{\pi^2}{9}$

$p(r) = r^3 + 1 = 0, e^{i\phi} = \cos(\phi) + i\sin(\phi)$

$r^3 = -1, -1 = e^{i\pi}, r = e^{i\theta}, 1 = e^{i2\pi \cdot n}$

$e^{i3\theta} = e^{i\pi} \Rightarrow 3\theta \equiv \pi \pmod{2\pi}$

$3\theta_1 = \pi, 3\theta_2 = \pi - 2\pi, 3\theta_3 = \pi + 2\pi$

$\theta_1 = \frac{\pi}{3}, \theta_2 = -\frac{\pi}{3}, \theta_3 = \pi$

$r_1 = e^{i\frac{\pi}{3}}, r_2 = e^{-i\frac{\pi}{3}}, r_3 = e^{i\pi} = -1$

$r_1 = \cos(\frac{\pi}{3}) + i\sin(\frac{\pi}{3}), r_2 = \cos(\frac{\pi}{3}) - i\sin(\frac{\pi}{3}), r_3 = -1$

General Solution

$y(t) = c_1 e^{\lambda_1 t} \cos(\mu_1 t) + c_2 e^{\lambda_1 t} \sin(\mu_1 t) + c_3 e^{-t}$

$$\begin{bmatrix} 1 & 0 & 1 \\ \lambda_1 & \mu_1 & -1 \\ \lambda_1^2 - \mu_1^2 & 2\lambda_1 \mu_1 & 1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \\ 1 - \frac{\pi^2}{9} \end{bmatrix}$$

$y'(t) = c_1 \lambda_1 e^{\lambda_1 t} \cos(\mu_1 t) - c_1 e^{\lambda_1 t} \mu_1 \sin(\mu_1 t) + c_2 \lambda_1 e^{\lambda_1 t} \sin(\mu_1 t) + c_2 e^{\lambda_1 t} \mu_1 \cos(\mu_1 t) - c_3 e^{-t}$

$y''(t) = c_1 \lambda_1^2 e^{\lambda_1 t} \cos(\mu_1 t) - c_1 \lambda_1 \mu_1 e^{\lambda_1 t} \sin(\mu_1 t) - c_1 \lambda_1 \mu_1 e^{\lambda_1 t} \sin(\mu_1 t) - c_1 e^{\lambda_1 t} \mu_1^2 \cos(\mu_1 t) + c_2 \lambda_1^2 e^{\lambda_1 t} \sin(\mu_1 t) + c_2 \lambda_1 \mu_1 e^{\lambda_1 t} \cos(\mu_1 t) + c_2 \lambda_1 \mu_1 e^{\lambda_1 t} \cos(\mu_1 t) - c_2 e^{\lambda_1 t} \mu_1^2 \sin(\mu_1 t) + c_3 e^{-t}$

$\lambda_1 = \cos(\frac{\pi}{3})$
 $\mu_1 = \sin(\frac{\pi}{3})$

Higher Order Linear Equations: Constant Coefficients (Distinct Roots, Real and Complex-Valued)

Inhomogeneous equation with constant coefficients:

$$L[y] = a_0 y^{(n)} + a_1 y^{(n-1)} + \dots + a_{n-1} y' + a_n y = g(t)$$

$$y(t_0) = y_0, \quad y'(t_0) = y'_0, \quad \dots, \quad y^{(n-1)}(t_0) = y_0^{(n-1)}$$

Summary of Solution Technique:

Find roots of the characteristic polynomial:

$$\rho(r) = a_0 r^n + a_1 r^{n-1} + \dots + a_{n-1} r + a_n = 0$$

Are the roots distinct real and complex-valued?

Yes, then use general solution form

$$y(t) = c_1 \exp(t\lambda_1) \cos(\mu_1 t) + c_2 \exp(t\lambda_1) \sin(\mu_1 t) + \dots + c_{2k-1} \exp(t\lambda_k) \cos(\mu_k t) + c_{2k} \exp(t\lambda_k) \sin(\mu_k t) \\ + c_{2k+1} \exp(tr_{2k+1}) + \dots + c_n \exp(tr_n) + S(t)$$

Find coefficients using initial conditions by solving

$$c_1 y_1(t_0) + \dots + c_n y_n(t_0) = y_0 \quad -S(t_0)$$

$$c_1 y_1'(t_0) + \dots + c_n y_n'(t_0) = y_0' \quad -S'(t_0)$$

⋮

$$c_1 y_1^{(n-1)}(t_0) + \dots + c_n y_n^{(n-1)}(t_0) = y_0^{(n-1)} \quad -S^{(n-1)}(t_0)$$

No, then need to use another method.

Lemma: Roots of a polynomial $p(r)$ with real coefficients have any complex-valued roots occurring in conjugate pairs $r_+ = \lambda + i\mu$, $r_- = \lambda - i\mu$.

Exponentials:

$$\exp(tr_-) = \exp((\lambda - i\mu)t)$$

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Lemma: For the two complex-valued roots r_-, r_+ , we have any function which is a linear combination of the complex exponentials can be expressed in terms of real-valued functions as

$$\tilde{y}(t) = \tilde{c}_+ \exp(tr_+) + \tilde{c}_- \exp(tr_-) \\ = c_+ \exp(t\lambda) \cos(\mu t) + c_- \exp(t\lambda) \sin(\mu t)$$

Higher Order Linear Equations

Method of Undetermined Coefficients

Repeated Roots

Higher Order Linear Equations: Constant Coefficients (Real, Complex, and Repeated Roots)

Homogeneous equation with constant coefficients:

$$L[y] = a_0 y^{(n)} + a_1 y^{(n-1)} + \cdots + a_{n-1} y' + a_n y = 0,$$
$$y(t_0) = y_0, \quad y'(t_0) = y'_0, \quad \dots, \quad y^{(n-1)}(t_0) = y_0^{(n-1)}$$

Summary of Solution Technique:

Are coefficients of the ODE constant?

Yes, then find roots of the characteristic polynomial:

$$\rho(r) = a_0 r^n + a_1 r^{n-1} + \cdots + a_{n-1} r + a_n = 0$$

Use **general solution** form

$$y = c_1 y_1(t) + c_2 y_2(t) + \cdots + c_n y_n(t)$$

where y_j determined from the cases discussed.

Find coefficients using initial conditions by solving

$$c_1 y_1(t_0) + \cdots + c_n y_n(t_0) = y_0$$

$$c_1 y_1'(t_0) + \cdots + c_n y_n'(t_0) = y'_0$$

⋮

$$c_1 y_1^{(n-1)}(t_0) + \cdots + c_n y_n^{(n-1)}(t_0) = y_0^{(n-1)}$$

No, must use another method.

Lemma: Roots r^* of a polynomial $p(r)$ with multiplicity s correspond to solutions

$$e^{r_1 t}, \quad t e^{r_1 t}, \quad t^2 e^{r_1 t}, \quad \dots, \quad t^{s-1} e^{r_1 t}$$

Real-valued Case: roots with multiplicity s contribute functions y_j

$$e^{r_1 t}, \quad t e^{r_1 t}, \quad t^2 e^{r_1 t}, \quad \dots, \quad t^{s-1} e^{r_1 t}$$

Complex-valued Case: roots with multiplicity s contribute functions y_j

$$e^{\lambda t} \cos \mu t, \quad e^{\lambda t} \sin \mu t, \quad t e^{\lambda t} \cos \mu t, \quad t e^{\lambda t} \sin \mu t,$$

$$\dots, \quad t^{s-1} e^{\lambda t} \cos \mu t, \quad t^{s-1} e^{\lambda t} \sin \mu t.$$

Higher Order Linear Equations: Constant Coefficients

Ex: $y^{(3)} + 3y^{(2)} + 3y^{(1)} + y = 0$

$$p(r) = r^3 + 3r^2 + 3r + 1 = 0$$

$r = -1$ is root multiplicity 3

$$p(r) = (r + 1)^3$$

$$y(t) = c_1 e^{-t} + c_2 t e^{-t} + c_3 t^2 e^{-t}$$

Higher Order Linear Equations

Method of Undetermined Coefficients

Summary

Higher Order Linear Equations: Constant Coefficients (Summary)

Homogeneous equation with constant coefficients:

$$L[y] = a_0 y^{(n)} + a_1 y^{(n-1)} + \cdots + a_{n-1} y' + a_n y = 0,$$
$$y(t_0) = y_0, \quad y'(t_0) = y'_0, \quad \dots, \quad y^{(n-1)}(t_0) = y_0^{(n-1)}$$

Summary of Solution Technique:

Are coefficients of the ODE constant?

Yes, then find roots of the characteristic polynomial:

$$\rho(r) = a_0 r^n + a_1 r^{n-1} + \cdots + a_{n-1} r + a_n = 0$$

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Complex-valued Case: roots with multiplicity s contribute functions y_j

$$\begin{aligned} e^{\lambda t} \cos \mu t, \quad e^{\lambda t} \sin \mu t, \quad t e^{\lambda t} \cos \mu t, \quad t e^{\lambda t} \sin \mu t, \\ \dots, \quad t^{s-1} e^{\lambda t} \cos \mu t, \quad t^{s-1} e^{\lambda t} \sin \mu t. \end{aligned}$$

Higher Order Linear Equations: Constant Coefficients (Summary)

Inhomogeneous equation with constant coefficients:

$$L[y] = a_0 y^{(n)} + a_1 y^{(n-1)} + \dots + a_{n-1} y' + a_n y = g(t)$$

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$$c_1 y_1(t_0) + \dots + c_n y_n(t_0) = y_0 \quad \sim S(t_0)$$

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⋮

$$c_1 y_1^{(n-1)}(t_0) + \dots + c_n y_n^{(n-1)}(t_0) = y_0^{(n-1)} \quad \sim S^{(n-1)}(t_0)$$

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$$e^{r_1 t}, \quad t e^{r_1 t}, \quad t^2 e^{r_1 t}, \quad \dots, \quad t^{s-1} e^{r_1 t}$$

Complex-valued Case: roots with multiplicity s contribute functions y_j

$$\begin{aligned} e^{\lambda t} \cos \mu t, \quad e^{\lambda t} \sin \mu t, \quad t e^{\lambda t} \cos \mu t, \quad t e^{\lambda t} \sin \mu t, \\ \dots, \quad t^{s-1} e^{\lambda t} \cos \mu t, \quad t^{s-1} e^{\lambda t} \sin \mu t. \end{aligned}$$