

# Mixed Methods

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206D: Finite Element Methods  
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When  $\mathcal{L}$  contains only bilinear and quadratic expressions in  $u$  and  $\lambda$ , we obtain a saddle point problem.

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# Saddle Point Problems

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A central theorem for saddle point problems.

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Referred to as the Brezzi Conditions or Ladyzhenskaya-Babuska-Brezzi (LBB-Conditions).

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Suppose assumptions of prior theorem and *Condition (C)* satisfied. The solution to Mixed FEM I satisfies

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This establishes stability of the formulation.

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Note that  $\nabla M_h \subset X_h$ , allow us to verify same as in continuous case.

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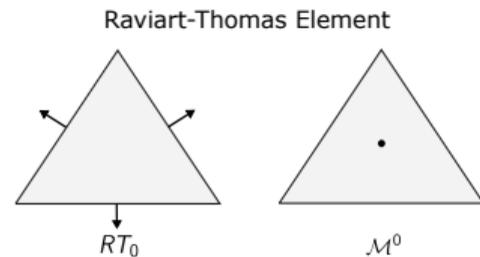
We can obtain stable Finite Element discretizations for triangulations  $\mathcal{T}_h$ . For  $k \geq 1$ , let

## Poisson Problem: Stable Mixed Finite Element Spaces

$$\begin{aligned} X_h &:= (\mathcal{M}^{k-1})^d = \{\sigma_h \in L_2(\Omega)^d; \sigma_h|_T \in \mathcal{P}_{k-1}, \forall T \in \mathcal{T}_h\} \\ M_h &:= \mathcal{M}_{0,0}^k = \{v_h \in H_0^1(\Omega); v_h|_T \in \mathcal{P}_k, \forall T \in \mathcal{T}_h\} \end{aligned}$$

Note that  $\nabla M_h \subset X_h$ , allow us to verify same as in continuous case.

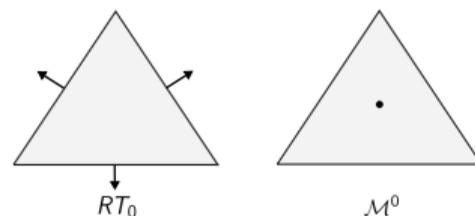
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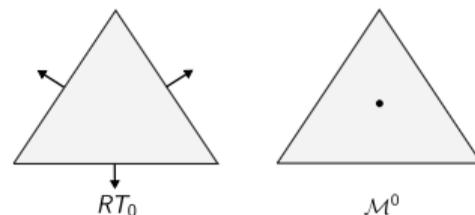


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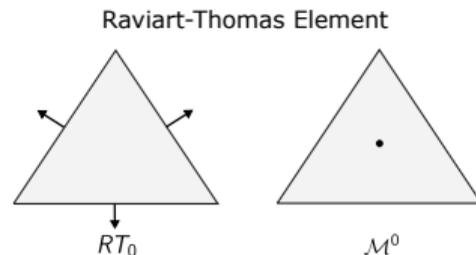


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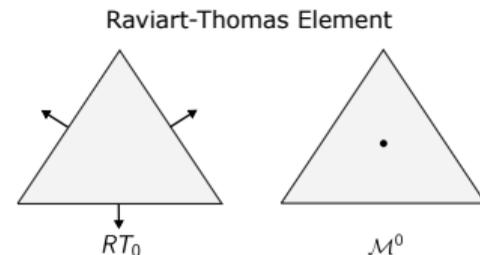
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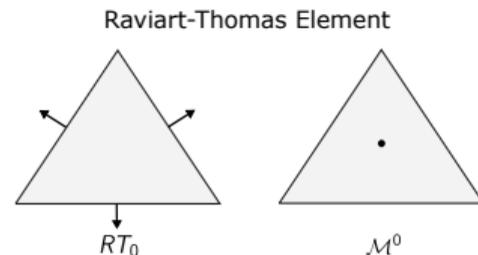
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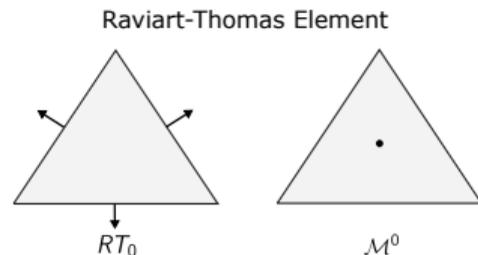
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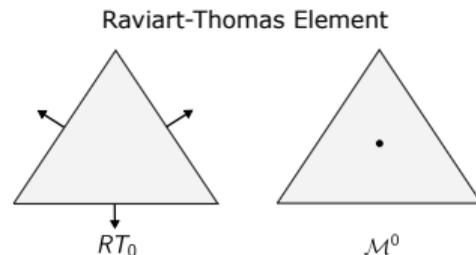
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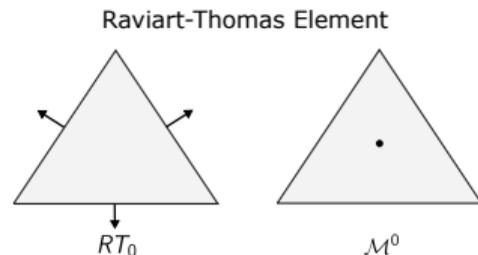
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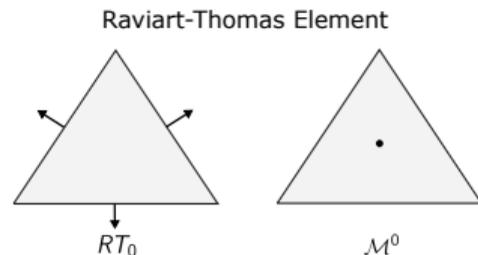
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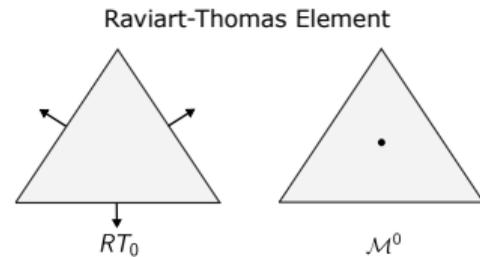
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$$\left( T, (\mathcal{P}_0)^2 + \mathbf{x} \cdot \mathcal{P}_0, n_i \cdot p(z_i), i = 1, 2, 3, z_i \text{ is edge midpoint.} \right)$$



# Poisson Problem: Raviart-Thomas Element

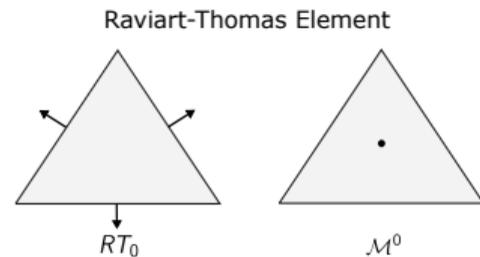
## Mesh-Dependent Norms:



# Poisson Problem: Raviart-Thomas Element

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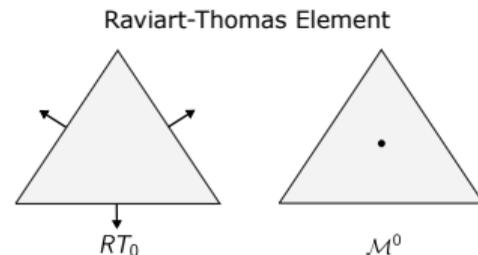
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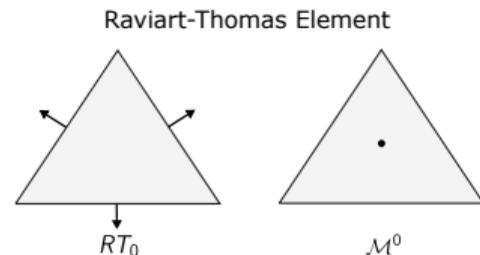


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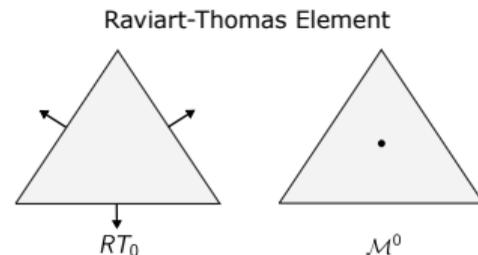
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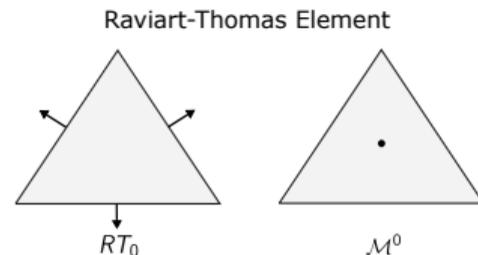
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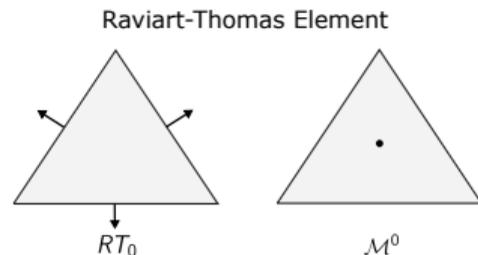
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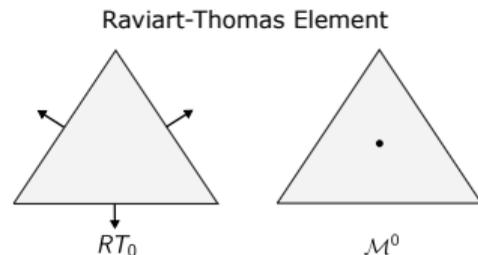
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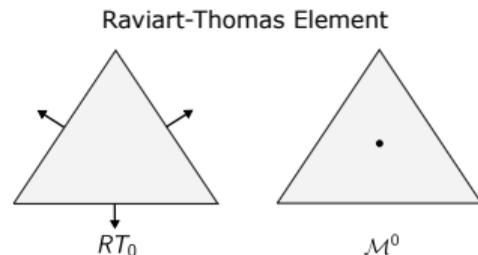
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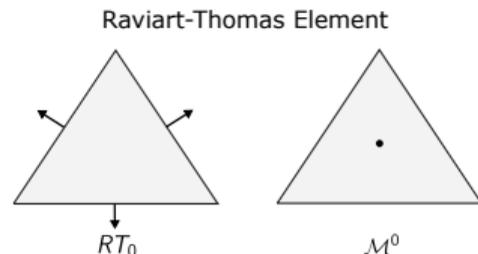
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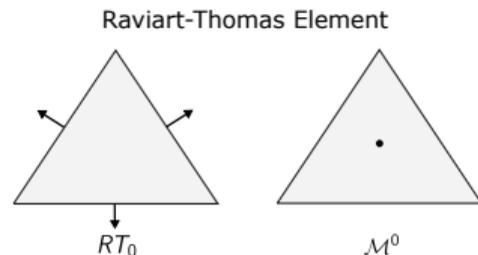
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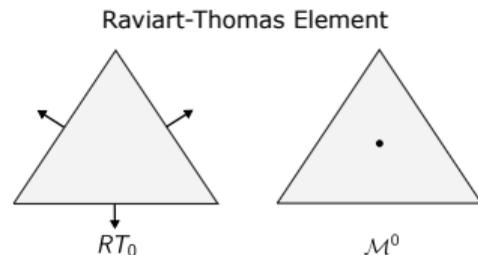
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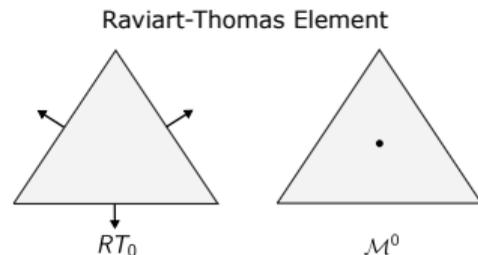
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The  $V^\perp$  is  $H^1$ -orthogonal complement of  $V$ .

Following two theorems used to establish inf-sup (for proof see literature: Necas 1965, Duvant, Lions 1976).

## Theorem I

Let  $\Omega \subset \mathbb{R}^n$  be a bounded connected domain with Lipschitz continuous boundary. The following mappings are isomorphisms

$$\begin{aligned} \operatorname{div} : V^\perp &\rightarrow L_{2,0}(\Omega) \\ v &\mapsto \operatorname{div} v. \end{aligned}$$

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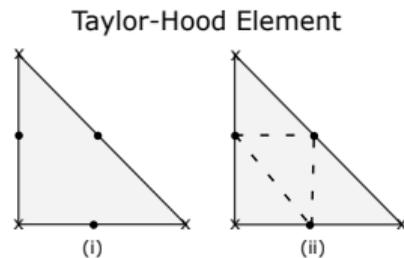
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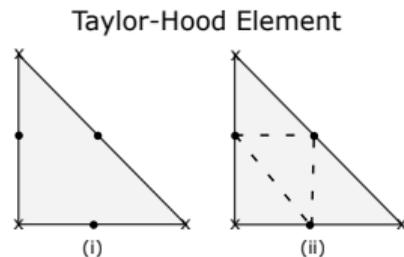
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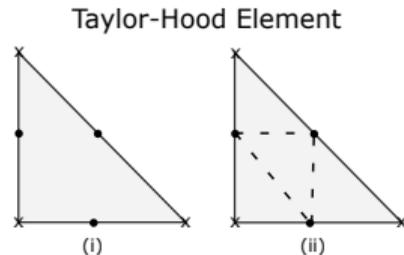
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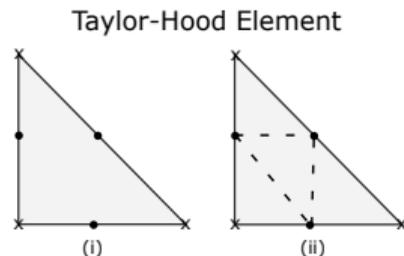


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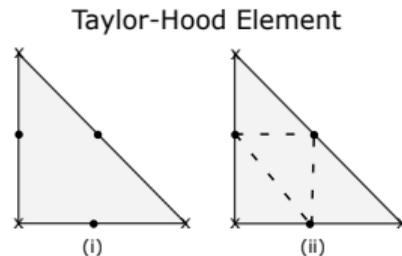
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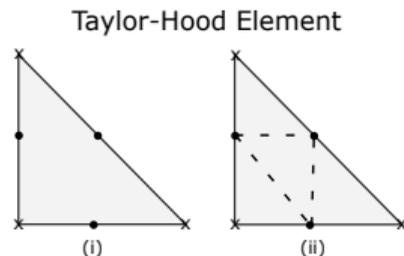
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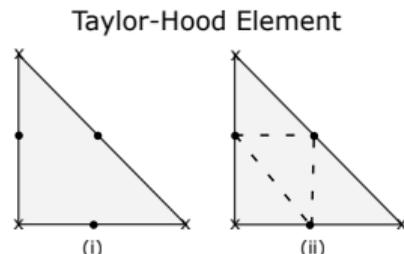
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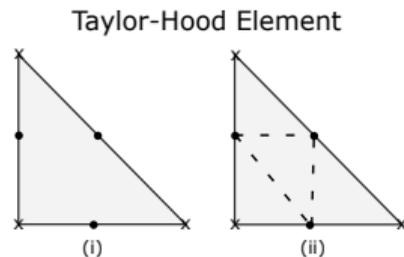
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$$M_h := \mathcal{M}_0^1 \cap L_{2,0} = \left\{q_h \in C(\Omega) \cap L_{2,0}(\Omega); q_h|_T \in \mathcal{P}_1, T \in \mathcal{T}_h\right\}$$

# Stokes Hydrodynamic Equations: Taylor-Hood Element

Consider triangulation  $\mathcal{T}_h$  and polynomial shape spaces  $\mathcal{P}_j$ .

**Taylor-Hood Elements:** Stability achieved by velocity field in polynomial space larger degree than the pressure space.



$$X_h := \left(\mathcal{M}_{0,0}^2\right)^d = \left\{v_h \in C(\bar{\Omega})^d \cap H_0^1(\Omega)^d; v_h|_T \in \mathcal{P}_2, \forall T \in \mathcal{T}_h\right\}$$

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**Modified Taylor-Hood Element:** Use piece-wise linear functions on sub-triangles (macro element)

$$X_h := \mathcal{M}_{0,0}^1(\mathcal{T}_{h/2})^2 = \left\{v_h \in C(\bar{\Omega})^d \cap H_0^1(\Omega)^d; v_h|_T \in \mathcal{P}_2, \forall T \in \mathcal{T}_{h/2}\right\}$$

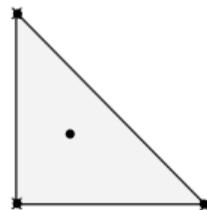
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**Figure:** x denotes pressure values, · denotes velocity values.

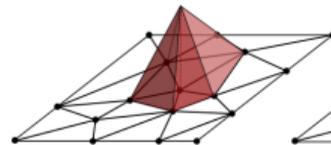
# Stokes Hydrodynamic Equations: MINI Element

**MINI Elements:** Achieves stability by using interior "bubble" elements.

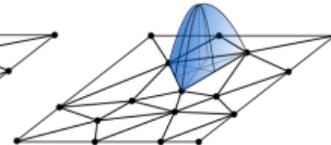
MINI Element



P1 Element



Bubble Element

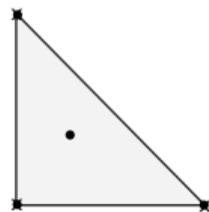


# Stokes Hydrodynamic Equations: MINI Element

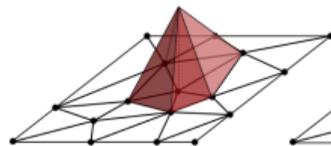
**MINI Elements:** Achieves stability by using interior "bubble" elements.

For triangle, let  $\lambda_1, \lambda_2, \lambda_3$  denotes the **barycentric coordinates** of a points  $\mathbf{x}$ .

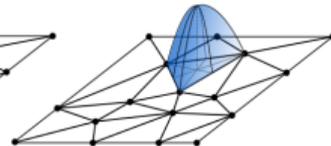
MINI Element



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Bubble Element



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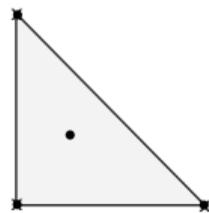
For triangle, let  $\lambda_1, \lambda_2, \lambda_3$  denotes the **barycentric coordinates** of a points  $\mathbf{x}$ .

Add to the shape space the "bubble" function

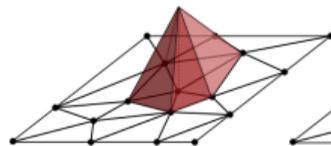
$$b(\mathbf{x}) = \lambda_1 \lambda_2 \lambda_3.$$

Note,  $b$  vanishes on boundary of  $T$ .

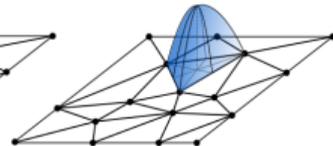
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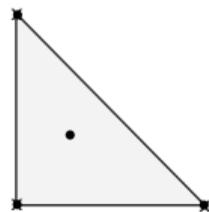
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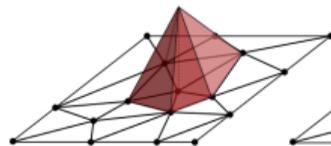
The finite element spaces are

$$X_h := [\mathcal{M}_{0,0}^1 \oplus B_3]^2, \quad M_h := \mathcal{M}_0^1 \cap L_{2,0}(\Omega),$$

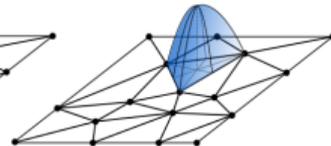
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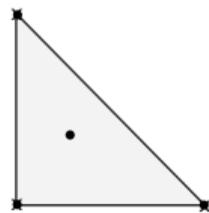
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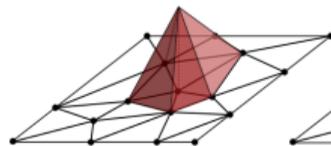
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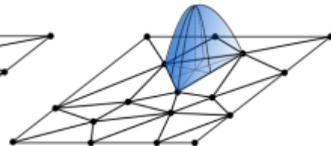
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**Figure:**  $\times$  denotes pressure values,  $\cdot$  denotes velocity values.

MINI Element

