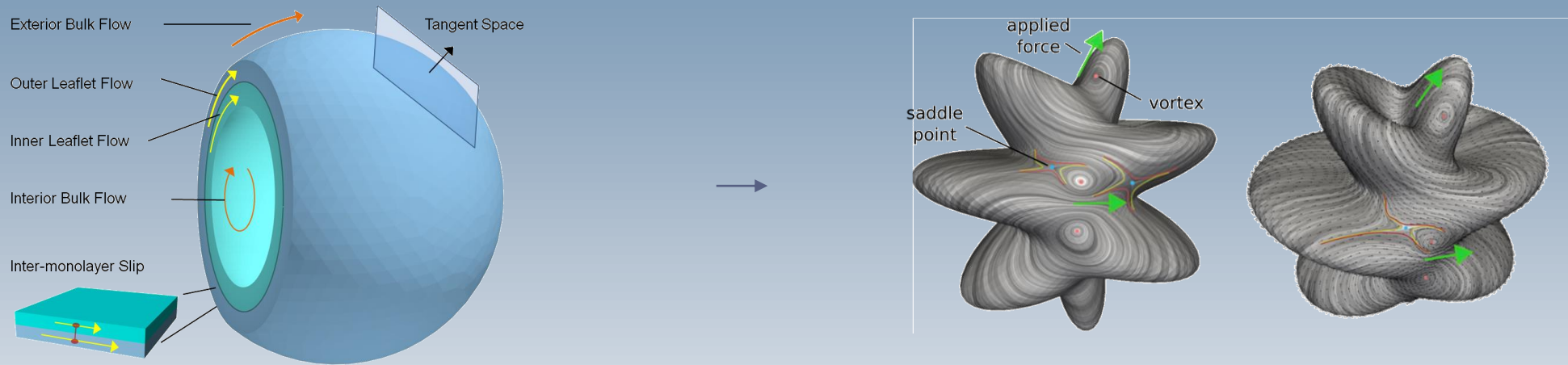


# Surface Fluctuating Hydrodynamics Methods

## Soft Materials with Fluid-Structure Interactions within Curved Fluid Interfaces



November 2020

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In collaboration: D. Rower, B. Gross, M. Padidar, N. Trask, P. Kuberry, and others.



DOE ASCR CM4  
DE-SC0009254



DOE ASCR PhILMS  
DE-SC0019246



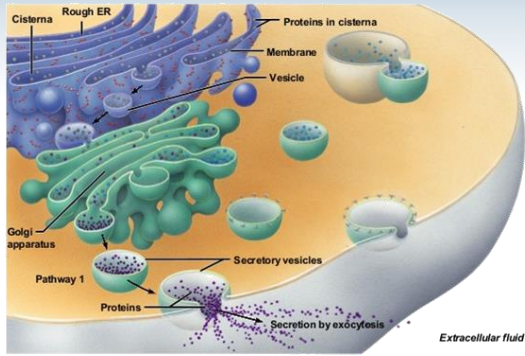
NSF Grant  
DMS - 1616353



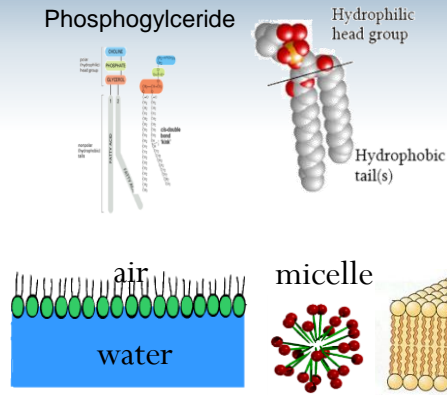
NSF CAREER Grant  
DMS-0956210

# Lipid Bilayer Membranes

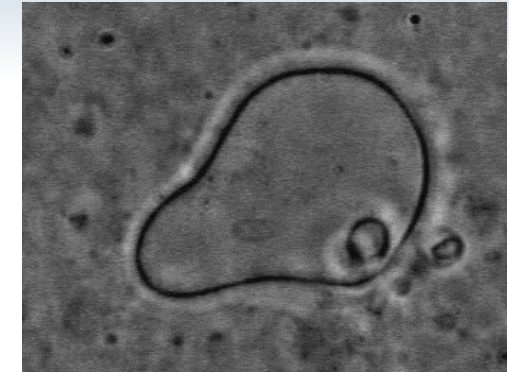
## Cell Membranes



## Phosphoglyceride



## Lipid Bilayer Configurations



## Lipid Bilayer Membranes

- Dynamic structures with diverse roles in cell biology.
- Fluid phase two-layered structures (bilayer).
- Mechanically behaves as a fluid-elastic sheet: in-plane flow, elastic responses to bending.

## Experimental Assays

### Single Particle Tracking

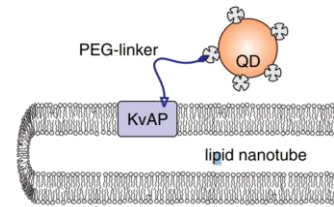
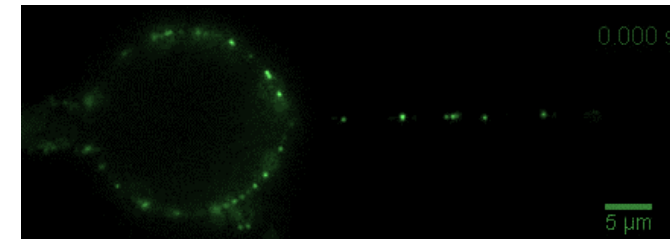
- Quantum Dots (QDs) conjugated to individual proteins.
- Image process --> QD location → protein positions.
- Trajectories measured over time-scales up to seconds.
- Protein diffusivity / kinetics depend on membrane mechanics.

### Fluorescence Contrast Microscopy

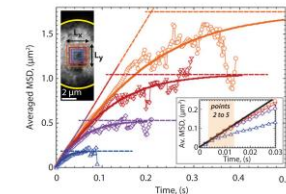
- Lipids labeled and membrane configuration observed.
- Image processing → representation of shapes.
- Thermal undulations → mechanics (bending elasticity, ...).

hydrodynamics, elasticity, geometry...

## Single Particle Tracking of Proteins



Basserau 2011, 2016.



Basserau, Atzberger 2014.

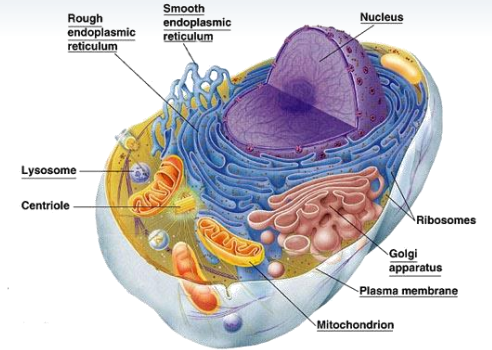
# Fluid Interfaces: General Motivations



soap films



red blood cells



cell mechanics

## Motivations

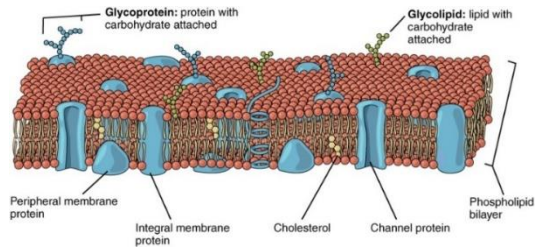
- Hydrodynamic flows within curved fluid interfaces relevant in many problems.
- Soap films, bubbles, cellular mechanics.
- Geometry plays important role in hydrodynamic responses.
- Fluctuations important in many problems:
  - diffusive transport, osmotic swelling, fission/fusion.

## Challenges

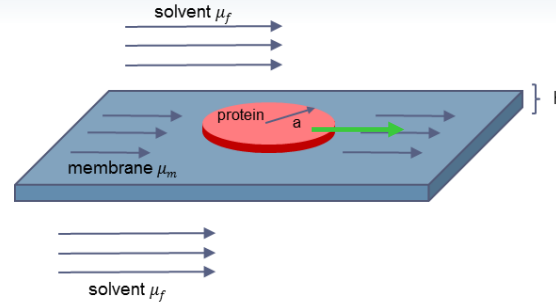
- Need good methods to formulate tractable hydrodynamic equations on manifolds.
- Approaches for performing analysis and reductions.
- Computational methods for efficient numerical approximation.

# Classical Work: Saffman-Delbruck Theory 1975

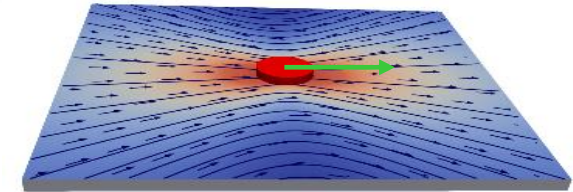
## Proteins in Bilayers



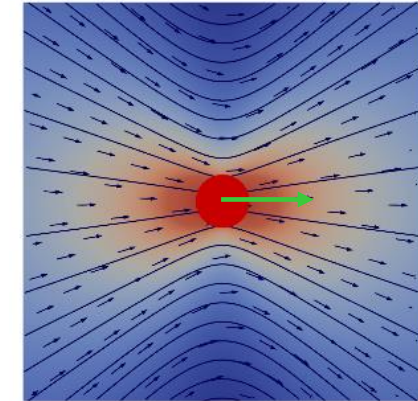
## Saffman-Delbruck Theory



## Immersed Boundary SD



(Atzberger & Sigurdsson, Soft Matter, 2016)

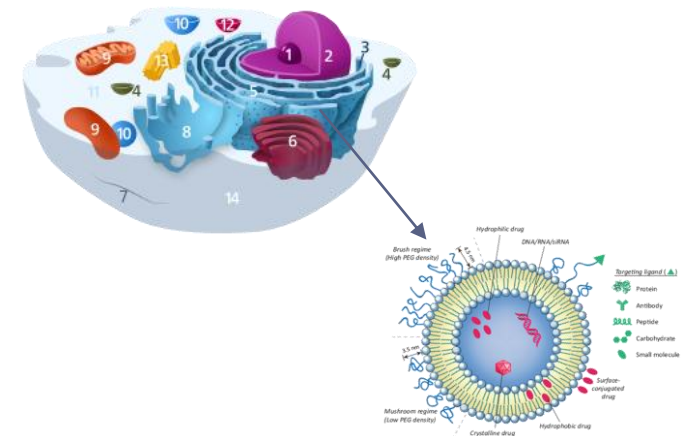


## Membrane Protein Diffusion:

- Membrane treated as 2D fluid slab.  $V = MF \sim D = 2K_B TM$
- Not pure 2D flow even though  $\mu_m \sim 100 \times \mu_f$ , Stokes' Paradox!
- Must treat both 2D lipid flow + coupling to bulk 3D flow of solvent.

## Saffman-Delbruck Theory (1975):

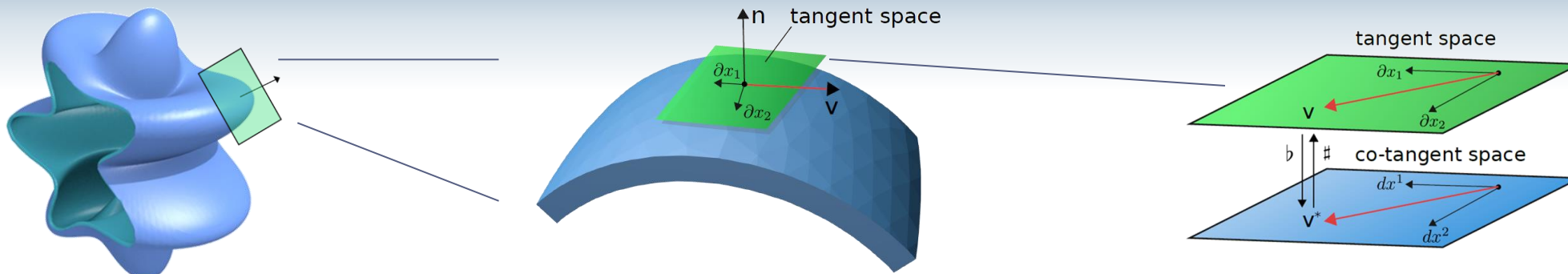
- Mobility / Diffusion as  $h \rightarrow 0$ ,  
 $V = M_{SD} F \sim D = 2K_B T M_{SD}$   
 $M_{SD} = (1/4\pi\mu_m) (\log(2L_{SD}/a) - \gamma)$ ,  $L_{SD} = \mu_m/2\mu_f$
- Predicts diffusion of proteins depends as log on size!
- $L_{SD} \sim 1 \mu m$ ,  $a \sim 10 \text{ nm}$ , long-range coupling.
- Many membranes exhibit curvature over this length-scale.



**How can we account for curvature, hydrodynamics, thermal fluctuations?  
 How does this affect transport?**



# Exterior Calculus Formulation of Mechanics



$$b : v^j \partial_{x^j} \rightarrow v_i dx^i \quad \# : v_i dx^i \rightarrow v^j \partial_{x^j}.$$

## Exterior Calculus Operators

- d** : Exterior Derivative (k-form  $\rightarrow$  (k+1)-form)
- \*** : Hodge Star (k-form  $\rightarrow$  (n-k)-form)
- ^** : Wedge Product (k<sub>1</sub>, k<sub>2</sub>-form  $\rightarrow$  (k<sub>1</sub>+k<sub>2</sub>)-form).

## Operators d and \*

$$d\alpha = \frac{1}{k!} \frac{\partial \alpha_{i_1 \dots i_k}}{\partial x^j} dx^j \wedge dx^{i_1} \wedge \dots \wedge dx^{i_k}$$

$$\star \alpha = \frac{\sqrt{|g|}}{(n-k)!k!} \alpha^{i_1 \dots i_k} \epsilon_{i_1 \dots i_k j_1 \dots j_{n-k}} \cdot dx^{j_1} \wedge \dots \wedge dx^{j_{n-k}}$$

## Vector Calculus Correspondence

$$\begin{aligned} \text{grad}(f) &= [df]^\# \\ \text{div}(\mathbf{F}) &= -(\star d \star \mathbf{F}^b) = -\delta \mathbf{F}^b \\ \text{curl}(\mathbf{F}) &= [\star(d\mathbf{F}^b)]^\# \\ \text{div}(\mathbf{D}) &= -\delta d\mathbf{v}^b + 2K\mathbf{v}^b \end{aligned}$$

## Conservation Laws on Manifolds

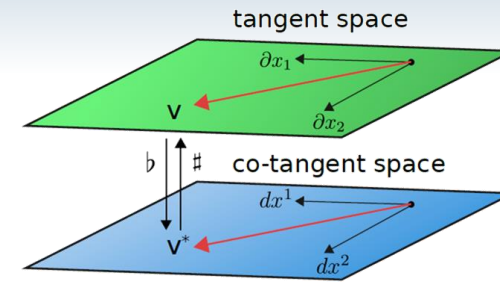
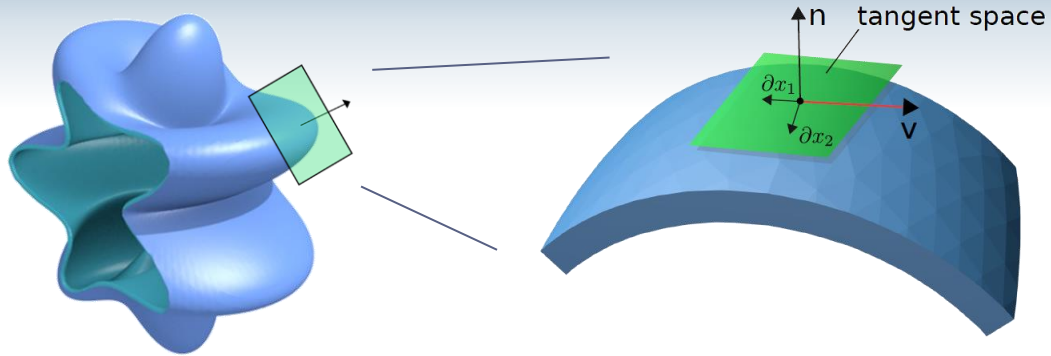
$$\int_{\partial\Omega} \omega = \int_{\Omega} d\omega \quad \text{Stokes Theorem}$$

$$\int_{\partial\Omega} \star\omega = \int_{\Omega} d\star\omega \quad \text{Divergence Theorem}$$

## Diffusion Equation / Laplace-Beltrami

$$\frac{\partial}{\partial t} \int_{\Omega} \star u = \int_{\partial\Omega} \star \omega = \int_{\Omega} d\star\omega. \quad \xrightarrow{\omega = du} \quad \frac{\partial u}{\partial t} = -\star d\star\omega = -\delta\omega = -\delta du.$$

# Exterior Calculus Formulation of Mechanics



$$b : v^j \partial_{x^j} \rightarrow v_i dx^i \quad \# : v_i dx^i \rightarrow v^j \partial_{x^j}$$

## Hydrodynamics on Manifolds

### Rate-of-Deformation Tensor

$$\mathbf{D} = \nabla_{\mathbf{v}} + \nabla_{\mathbf{v}}^T \longrightarrow \operatorname{div}(\mathbf{D}) = -\delta d\mathbf{v}^b + 2K\mathbf{v}^b$$

### Momentum Equations

$$\begin{aligned} \rho (\partial_t \mathbf{v} + \mathbf{v} \cdot \nabla \mathbf{v}) &= \operatorname{div}(\boldsymbol{\sigma}) + \mathbf{b} \\ \partial_t \rho + \rho \operatorname{div}(\mathbf{v}) &= 0. \end{aligned}$$

### Stokes Equations (surface)

$$\begin{aligned} \mu_m (-\delta d\mathbf{v}^b + 2K\mathbf{v}^b) - dp + \mathbf{b}^b &= 0 \\ -\delta \mathbf{v}^b &= 0. \end{aligned}$$

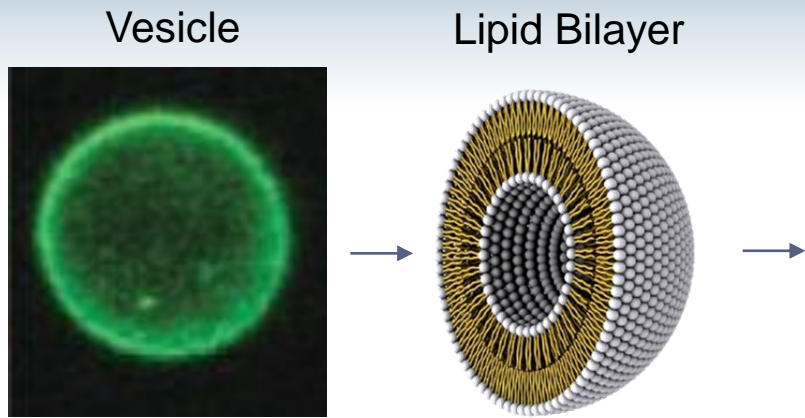
### Surface Hydrodynamic Equations

$$\begin{cases} \rho \frac{D\mathbf{v}^b}{dt} = \mu_m (-\delta d + 2K) \mathbf{v}^b - dp + \mathbf{b}^b \\ -\delta \mathbf{v}^b = 0 \end{cases}$$

### Vector Potential Form: $\mathbf{v}^b = -\star d\Phi$

$$\mu_m (-\delta d)^2 \Phi - 2\mu_m (-\star d(K(-\star d\Phi))) = -\star d\mathbf{b}^b$$

# Lipid Bilayer Membranes: Spherical Vesicles



## Lipid Bilayer Membranes

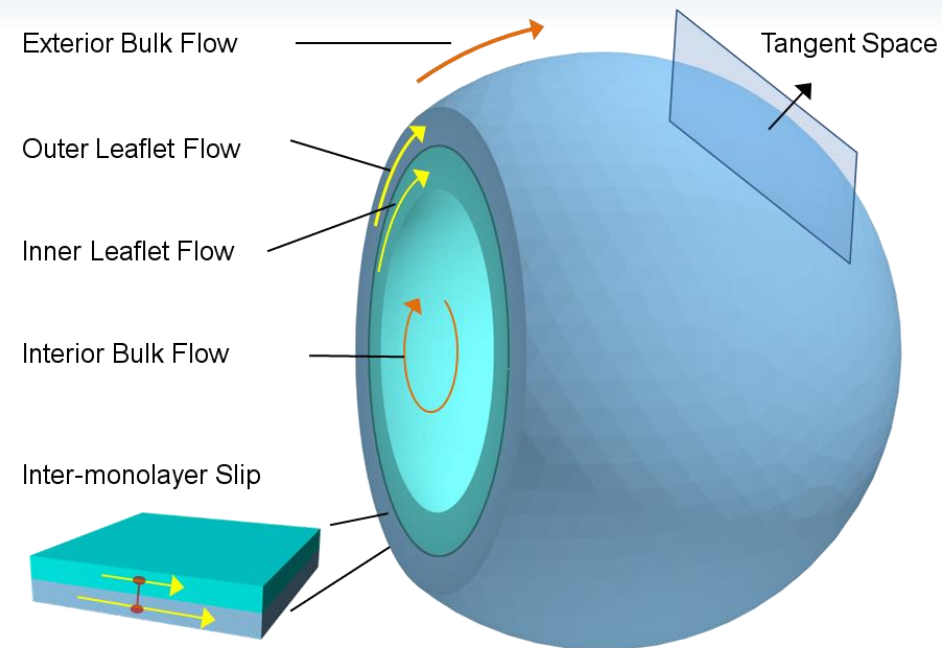
- Each leaflet treated as a 2D fluid.
- Hydrodynamic coupling:
  - i. Intra-monolayer lipid flow.
  - ii. Inter-monolayer slip.
  - iii. Traction with bulk solvent fluid.

## Bilayer Hydrodynamics

$$\left\{ \begin{array}{l} \mu_m [-\delta \mathbf{d} \mathbf{v}_+^b + 2K_+ \mathbf{v}_+^b] + \mathbf{t}_+^b - \gamma (\mathbf{v}_+^b - \mathbf{v}_-^b) \\ \quad = \mathbf{d} p_+ - \mathbf{b}_+^b = -\mathbf{c}_+^b, \quad \mathbf{x} \in \Gamma_+ \\ \delta \mathbf{v}_+^b = 0, \quad \mathbf{x} \in \Gamma_+, \end{array} \right. \quad \text{(outer layer)}$$

$$\left\{ \begin{array}{l} \mu_m [-\delta \mathbf{d} \mathbf{v}_-^b + 2K_- \mathbf{v}_-^b] + \mathbf{t}_-^b - \gamma (\mathbf{v}_-^b - \mathbf{v}_+^b) \\ \quad = \mathbf{d} p_- - \mathbf{b}_-^b = -\mathbf{c}_-^b, \quad \mathbf{x} \in \Gamma_- \\ \delta \mathbf{v}_-^b = 0, \quad \mathbf{x} \in \Gamma_-. \end{array} \right. \quad \text{(inner layer)}$$

## Bilayer Hydrodynamics



## Solvent Hydrodynamics

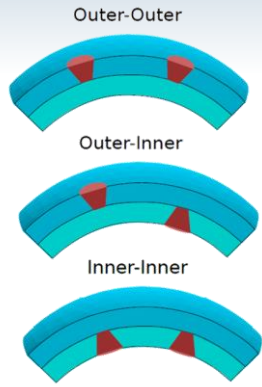
$$\begin{aligned} \mu \Delta \mathbf{u} - \nabla p &= 0, \quad \mathbf{x} \in \Omega \\ \nabla \cdot \mathbf{u} &= 0, \quad \mathbf{x} \in \Omega \\ \mathbf{u} &= \mathbf{v}, \quad \mathbf{x} \in \partial \Omega \\ \mathbf{u}_\infty &= 0. \end{aligned}$$

## Traction coupling

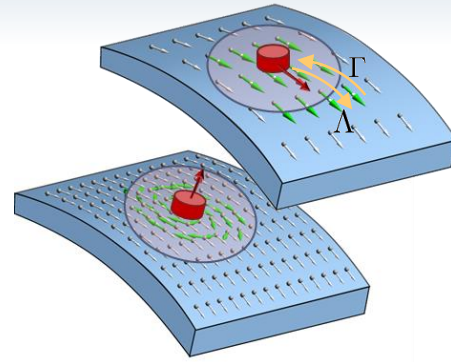
$$\begin{aligned} \mathbf{t}^+ &= \boldsymbol{\sigma}^+ \cdot \mathbf{n}^+ \\ \mathbf{t}^- &= \boldsymbol{\sigma}^- \cdot \mathbf{n}^- \end{aligned}$$

# Immersed Boundary Methods on Manifolds

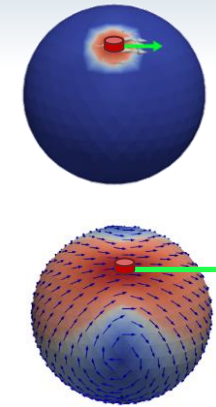
## Leaflet Cases



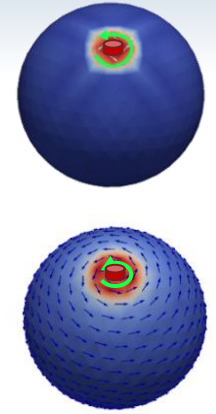
## Immersed Boundary Coupling



## Particle Force



## Particle Torque



## Immersed Boundary Methods for Manifolds

Velocity-Averaging operator:  $\Gamma \mathbf{v} = \int_{\Omega} \mathbf{W}[\mathbf{v}](\mathbf{y}) d\mathbf{y}$

Force-Spreading operator:  $\Lambda \mathbf{F} = \mathbf{W}^*[\mathbf{F}](\mathbf{x})$

Adjoint condition:  $\langle \mathbf{v}, \Lambda \mathbf{F} \rangle = \int_{\Omega} \mathbf{v}(\mathbf{x}) \cdot (\Lambda \mathbf{F})(\mathbf{x}) d\mathbf{x}$

$$\langle \Gamma \mathbf{v}, \mathbf{F} \rangle = \sum_i [\Gamma \mathbf{v}]_i \cdot [\mathbf{F}]_i$$

$$\langle \Gamma \mathbf{v}, \mathbf{F} \rangle = \langle \mathbf{v}, \Lambda \mathbf{F} \rangle \rightarrow \Gamma^T = \Lambda$$

## Weight Tensor

$$\mathbf{W}[\mathbf{v}] = \sum_i \left( (w^{[i]})_{\beta}^{\alpha} v^{\beta} \right) \partial_{\alpha} |_{\mathbf{X}^{[i]}}$$

$$(w^{[i],\alpha})^{\gamma} \partial_{\gamma} = \mathbf{q}^{\alpha}$$

## Reference Fields $\psi(r) = C \exp(-r^2/2\sigma^2)$

$$\mathbf{q}^{\theta} = \psi(\mathbf{x} - \mathbf{X}^{[i]}) \partial_{\theta}$$

$$\mathbf{q}^{\phi} = \psi(\mathbf{x} - \mathbf{X}^{[i]}) / \cos(\theta) \partial_{\phi}$$

$$\mathbf{q}^n = \psi(\mathbf{x} - \mathbf{X}^{[i]}) (\mathbf{n} \times (\mathbf{x} - \mathbf{X}^{[i]}))$$

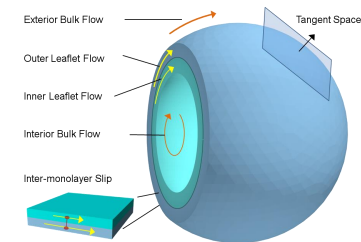
## Mobility Tensor

$$\begin{bmatrix} \mathbf{V} \\ \boldsymbol{\omega} \end{bmatrix} = \mathbf{M} \begin{bmatrix} \mathbf{F} \\ \boldsymbol{\tau} \end{bmatrix}$$

## IB-Membrane Mobility

$$M_{ij} = \Gamma_i \mathcal{S} \Lambda_j$$

## S is fluid solution operator

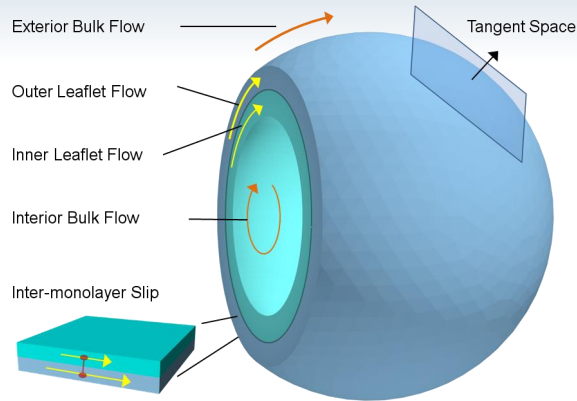


2019 Atzberger, Padidar, Rower  
2016 Atzberger & Sigurdsson

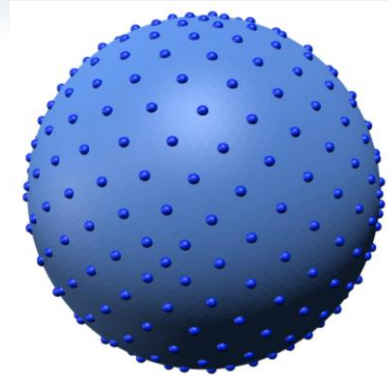


# Analytic Solutions and Lebedev Quadrature

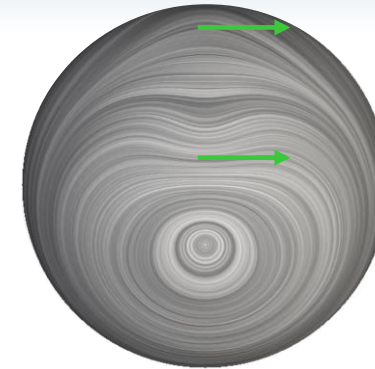
## Bilayer Hydrodynamics



## Lebedev Nodes



## Flow Streamlines



## Bilayer Hydrodynamics

$$\left\{ \begin{array}{l} \mu_m [-\delta \mathbf{d} \mathbf{v}_+^b + 2K_+ \mathbf{v}_+^b] + \mathbf{t}_+^b - \gamma (\mathbf{v}_+^b - \mathbf{v}_-^b) \\ \quad = \mathbf{d} p_+ - \mathbf{b}_+^b = -\mathbf{c}_+^b, \quad \mathbf{x} \in \Gamma_+ \\ \delta \mathbf{v}_+^b = 0, \quad \mathbf{x} \in \Gamma_+, \end{array} \right. \quad \text{(outer layer)}$$

$$\left\{ \begin{array}{l} \mu_m [-\delta \mathbf{d} \mathbf{v}_-^b + 2K_- \mathbf{v}_-^b] + \mathbf{t}_-^b - \gamma (\mathbf{v}_-^b - \mathbf{v}_+^b) \\ \quad = \mathbf{d} p_- - \mathbf{b}_-^b = -\mathbf{c}_-^b, \quad \mathbf{x} \in \Gamma_- \\ \delta \mathbf{v}_-^b = 0, \quad \mathbf{x} \in \Gamma_-. \end{array} \right. \quad \text{(inner layer)}$$

## L<sup>2</sup>-Orthogonal Projection

Spherical Harmonics

$$\mathcal{P}[f] = \bar{f}(\theta, \phi) = \sum_i \hat{f}_i Y_i(\theta, \phi),$$

$$\hat{f}_i = \langle f, Y_i \rangle_Q$$

## Solution Spherical Harmonics

$$\mathbf{v}_\pm^b = -\star \mathbf{d} \sum_s a_s^\pm \Phi_s, \quad \mathbf{c}^b = -\star \mathbf{d} \sum_s c_s \Phi_s$$

$$\begin{bmatrix} a_s^+ \\ a_s^- \end{bmatrix} = \mathcal{A}_s^{-1} \begin{bmatrix} -c_s^+ \\ -c_s^- \end{bmatrix}$$

$$\mathcal{A}_s = \begin{bmatrix} A_1^\ell - \gamma & \gamma \\ \gamma & A_2^\ell - \gamma \end{bmatrix}$$

$$A_1^\ell = \frac{\mu_m}{R_+^2} \left( 2 - \ell(\ell + 1) - \frac{R_+}{L^+}(\ell + 1) \right)$$

$$A_2^\ell = \frac{\mu_m}{R_-^2} \left( 2 - \ell(\ell + 1) - \frac{R_-}{L^-}(\ell - 1) \right)$$

$$L^\pm = \mu_\pm / 2\mu_f$$

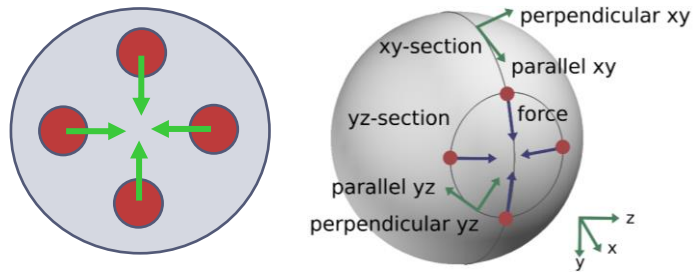
2016 Atzberger & Sigurdsson

# Many Particle Interactions

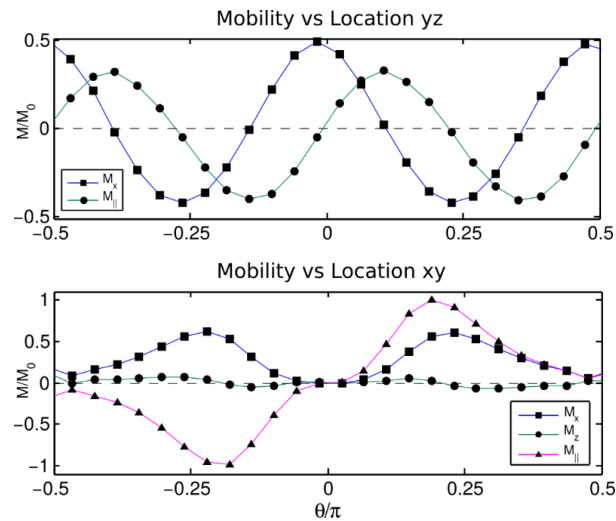
## Collective Motions

$$\frac{d\mathbf{X}}{dt} = \mathbf{MF}$$

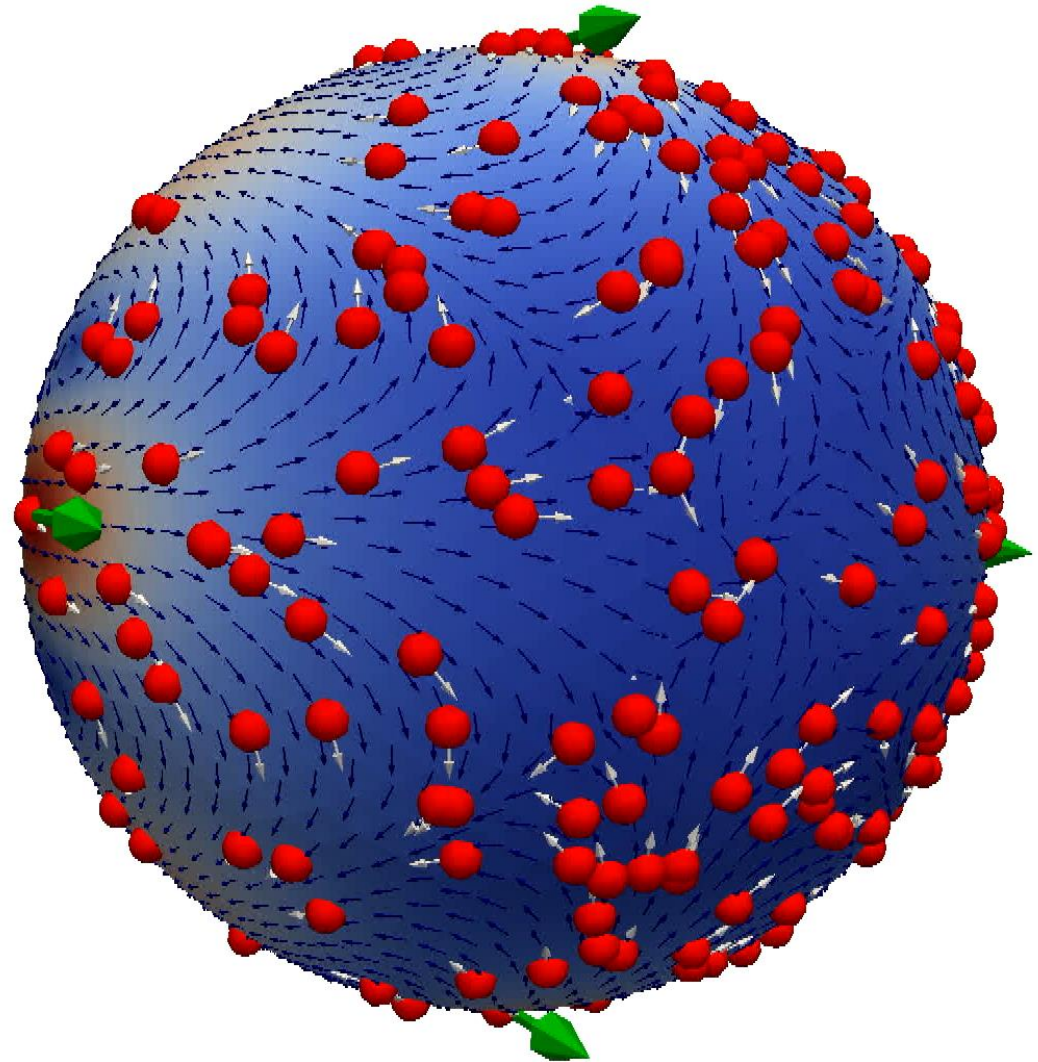
## Driving Force and Cross-Section



## Mobility Response



## Hydrodynamic Response

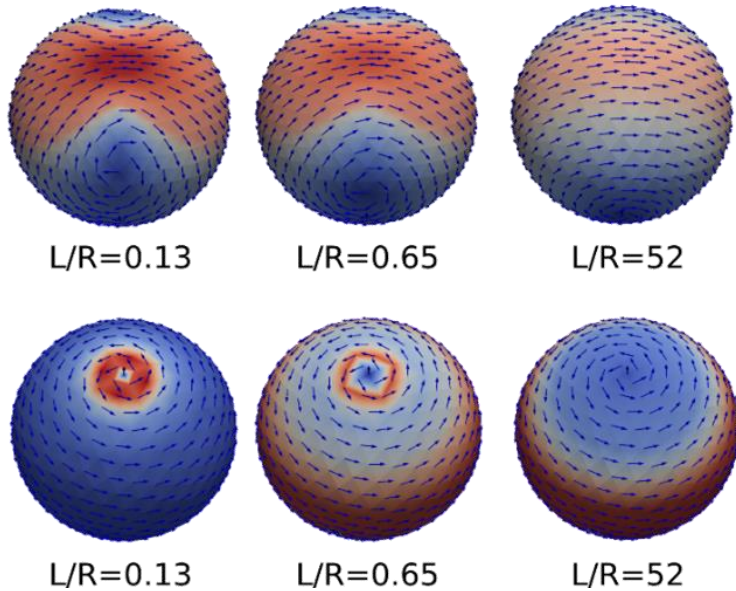


2016 Atzberger & Sigurdsson

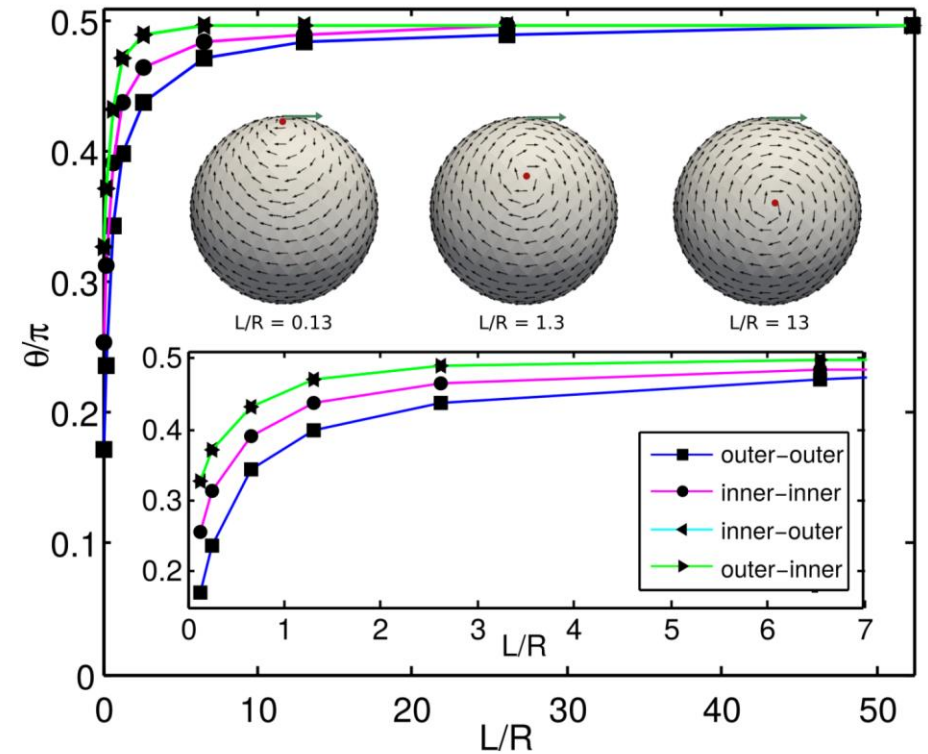


# Mobility for Spherical Vesicles

## Mobility Response vs Membrane Viscosity

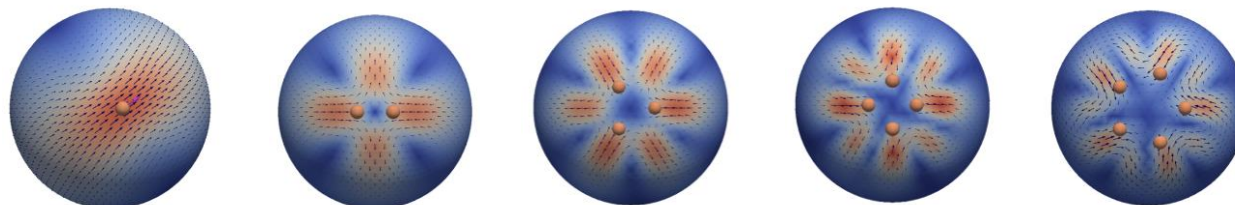


## Vortex Location vs Membrane Viscosity



## Collective Motions

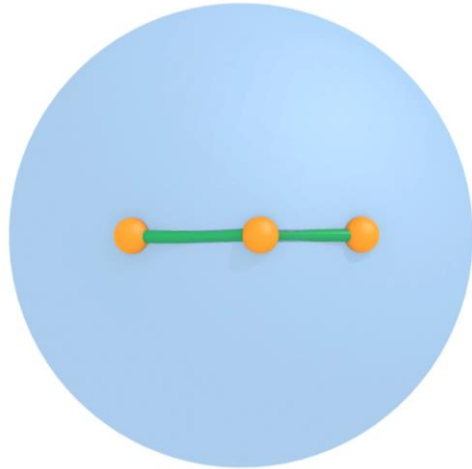
$$\frac{d\mathbf{X}}{dt} = \mathbf{MF}$$



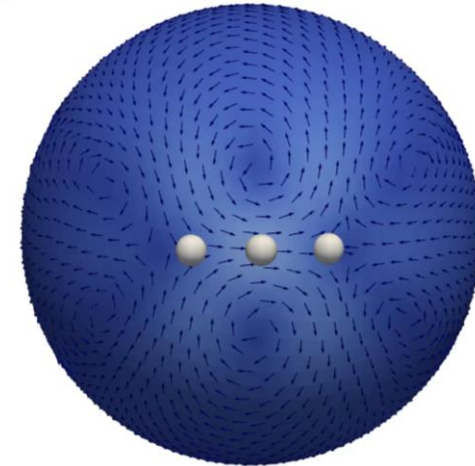


# Surface Hydrodynamic Methods

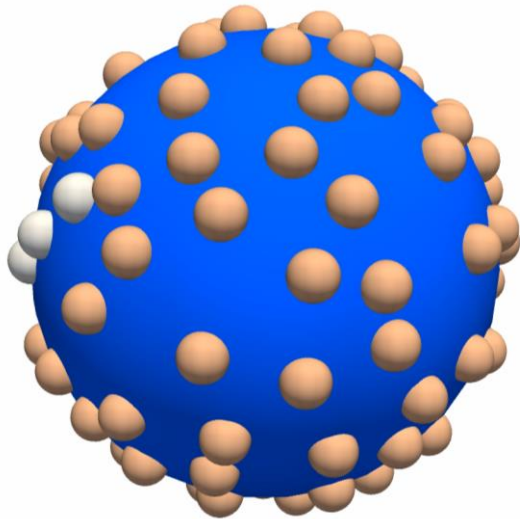
Golestanian Swimmer



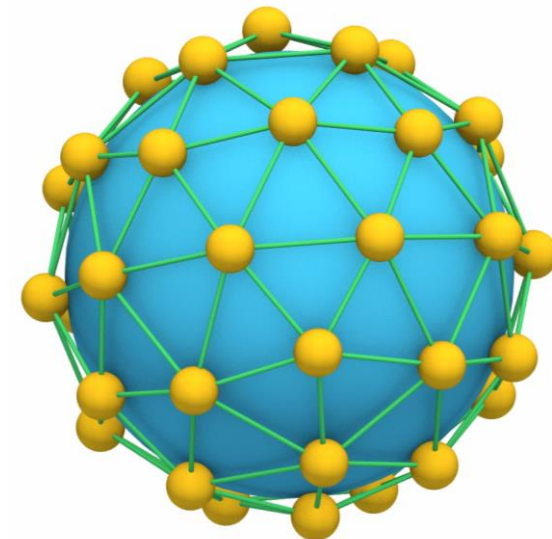
Golestanian Swimmer Flows



Active Swimmer and Mixing



Polymer Network Fluctuations



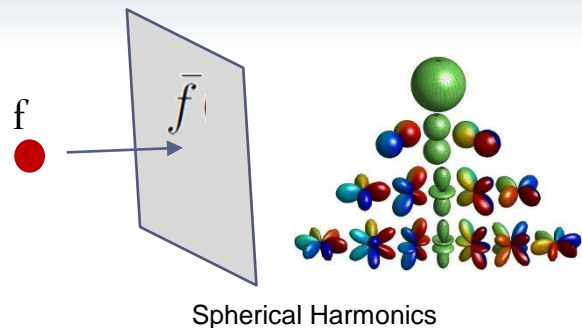
2016 Atzberger & Sigurdsson, 2019 Padidar, Rower, & Atzberger.



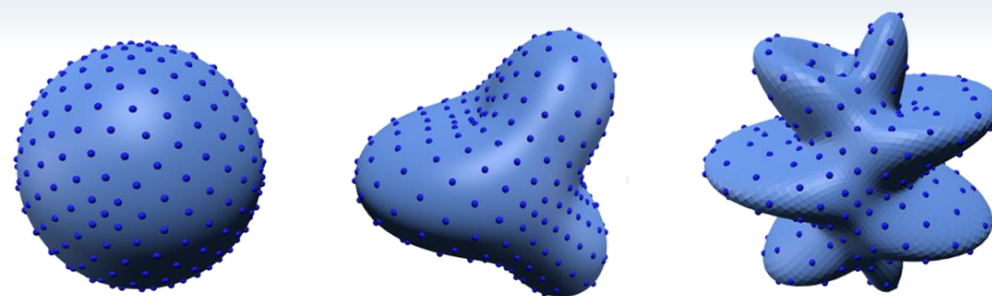
# Hydrodynamics and Geometry

# Spectral Solver for Surface Hydrodynamics

## L<sup>2</sup>-Orthogonal Projection



## Lebedev Quadrature



## Spectral Approximation

### L<sup>2</sup>-Projection:

$$\mathcal{P}[f] = \bar{f}(\theta, \phi) = \sum_i \hat{f}_i Y_i(\theta, \phi),$$

$$\hat{f}_i = \langle f, Y_i \rangle_Q$$

### Inner-Product:

$$\langle u, v \rangle_Q = \sum_{\ell} w_{\ell} u(\mathbf{x}_{\ell}) v(\mathbf{x}_{\ell})$$

Differential forms  $\mathbf{v}^b$  (0-forms, 1-forms, 2-forms).

Represented as scalar / vector fields  $\mathbf{v}^{\#}$  at the Lebedev nodes.

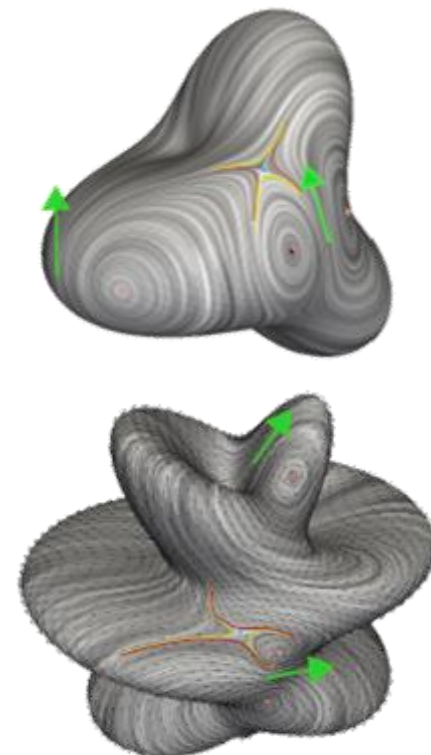
Exterior Derivative:  $\mathbf{d}$  approximated by  $\bar{\mathbf{d}}$   $\longleftarrow \bar{\mathbf{v}}^{\#}(\theta, \phi) = [\mathcal{P}\bar{v}^x, \mathcal{P}\bar{v}^y, \mathcal{P}\bar{v}^z]$

Hodge Star:  $*$  approximated by  $\bar{*}$

Approximating PDEs on the Manifold:  $\tilde{\mathcal{L}} = -\bar{\delta}\bar{\mathbf{d}} = -\bar{*}\bar{\mathbf{d}}\bar{*}\bar{\mathbf{d}}$ .  $\bar{u} = \sum_j \hat{u}_j Y_j$ ,  $\bar{g} = \sum_j \hat{g}_j Y_j$

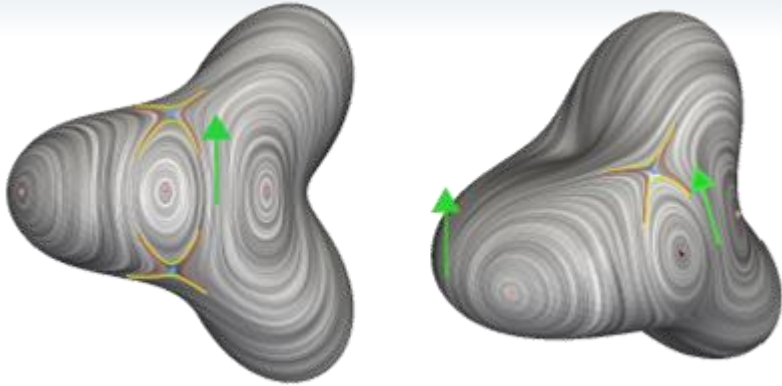
$$\mathcal{L}u = -g \longrightarrow \langle \tilde{\mathcal{L}}\bar{u}, Y_i \rangle_Q = -\langle \bar{g}, Y_i \rangle_Q \longrightarrow K\hat{u} = -M\hat{g}.$$

Method can be used for approximating general PDEs on manifolds.

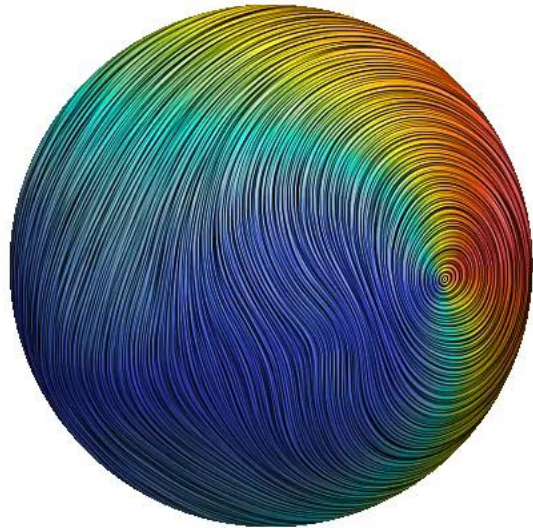


# Role of geometry in hydrodynamic flow responses

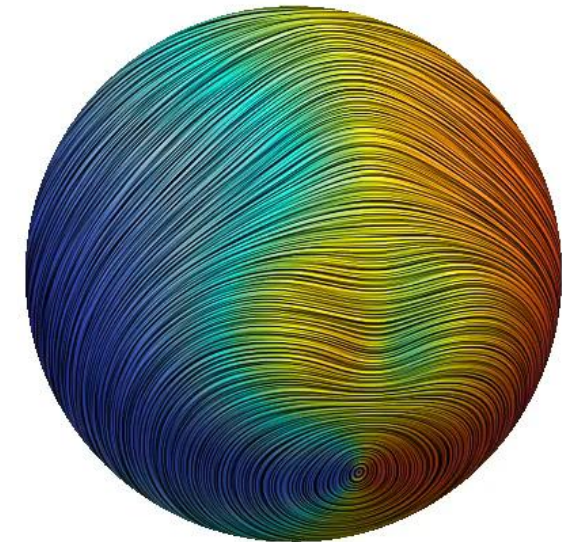
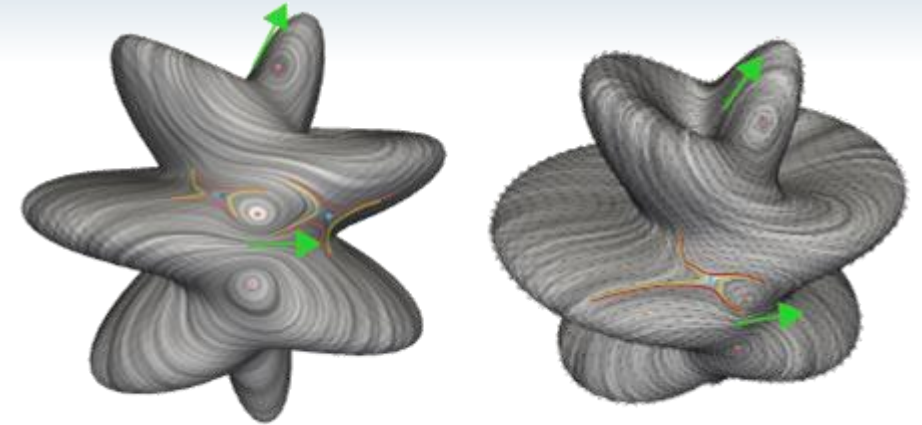
## Manifold B Flow Response



Flow transitions:

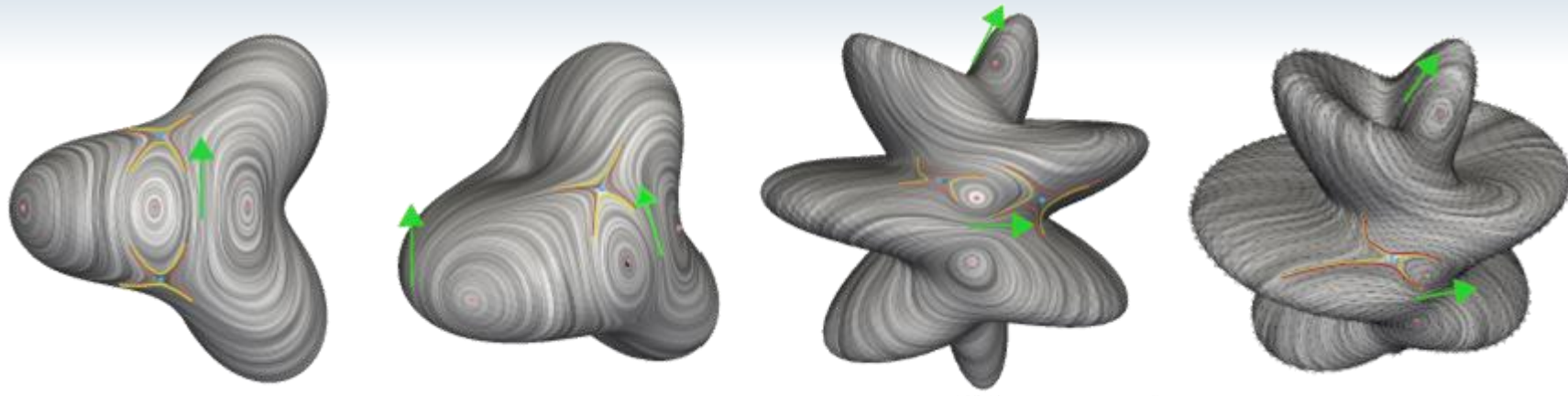


## Manifold C Flow Response



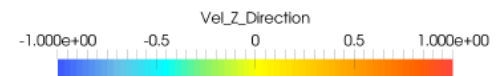
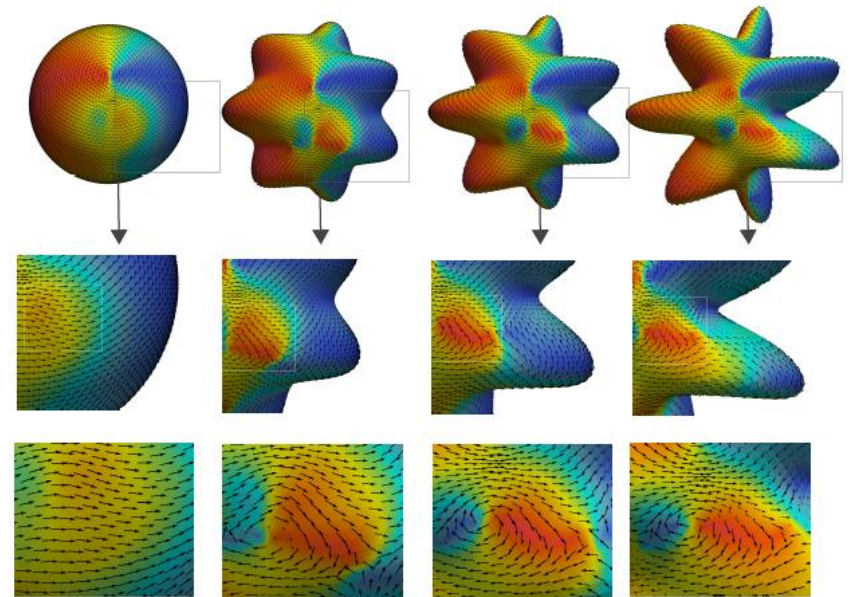
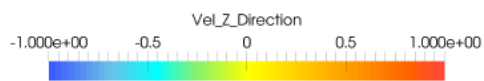
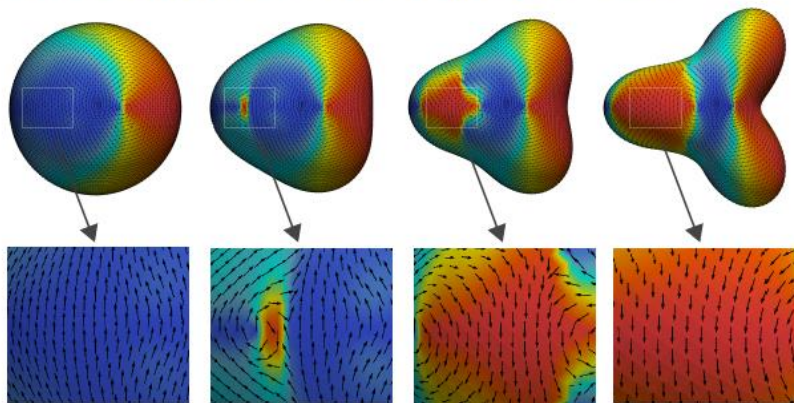


# Role of geometry in hydrodynamic flow responses



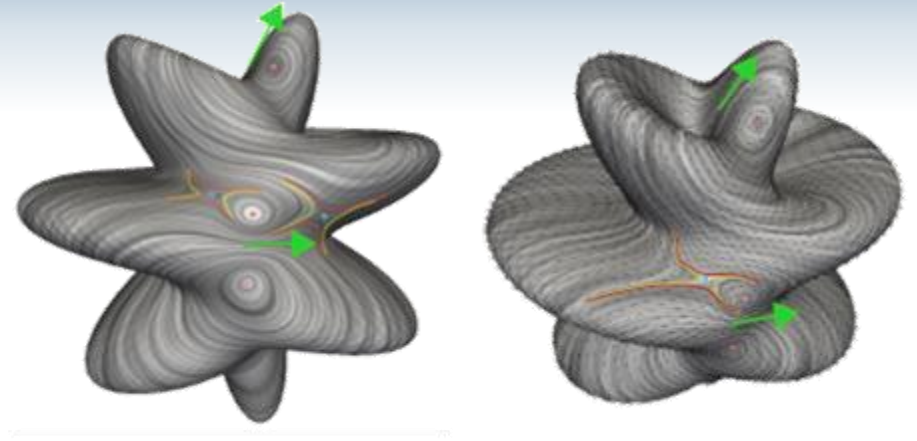
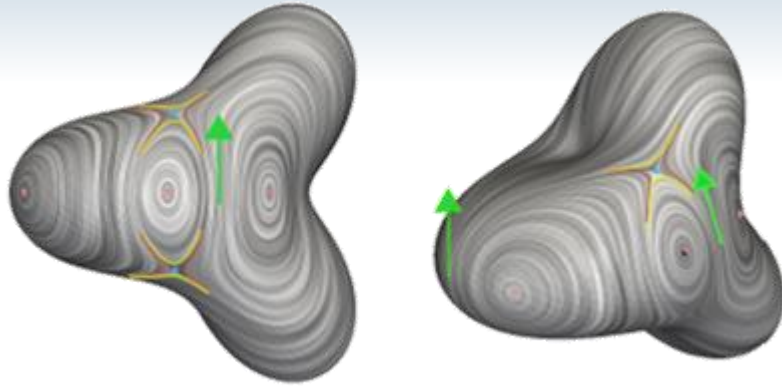
Role of Geometry in Hydrodynamic Flows

Role of Geometry in Hydrodynamic Flows





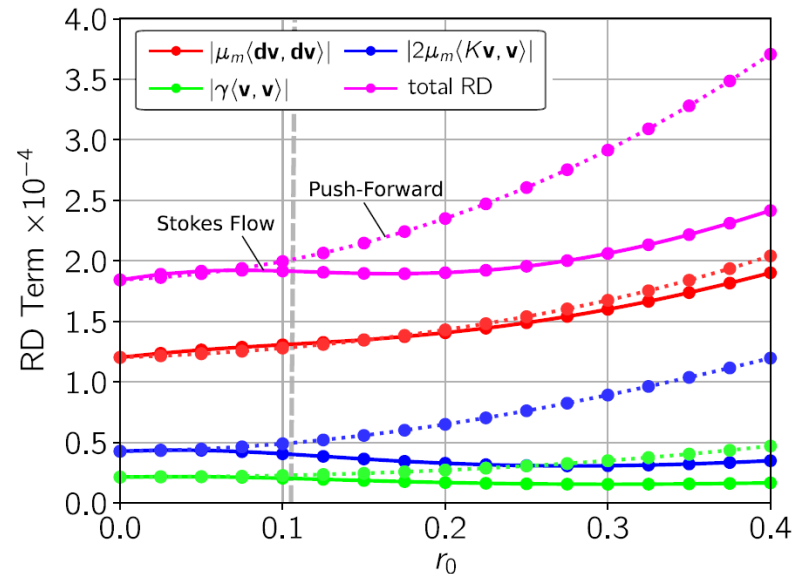
# Role of geometry in hydrodynamic flow responses



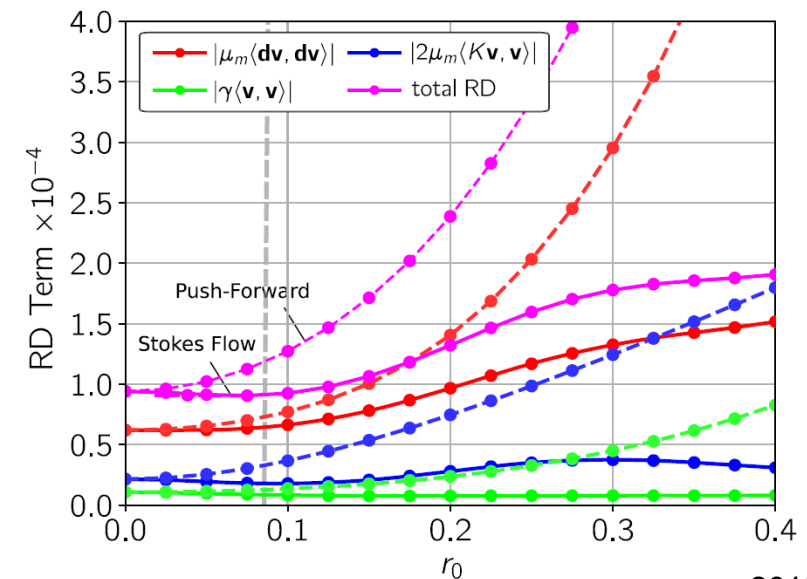
**Rayleigh Dissipation Rate:**

$$\text{RD}[\mathbf{v}^b] = \mu_m \langle \mathbf{d}\mathbf{v}^b, \mathbf{d}\mathbf{v}^b \rangle_{\mathcal{M}} - 2\mu_m \langle K\mathbf{v}^b, \mathbf{v}^b \rangle_{\mathcal{M}} + \gamma \langle \mathbf{v}^b, \mathbf{v}^b \rangle_{\mathcal{M}}$$

Rayleigh-Dissipation (Manifold B)



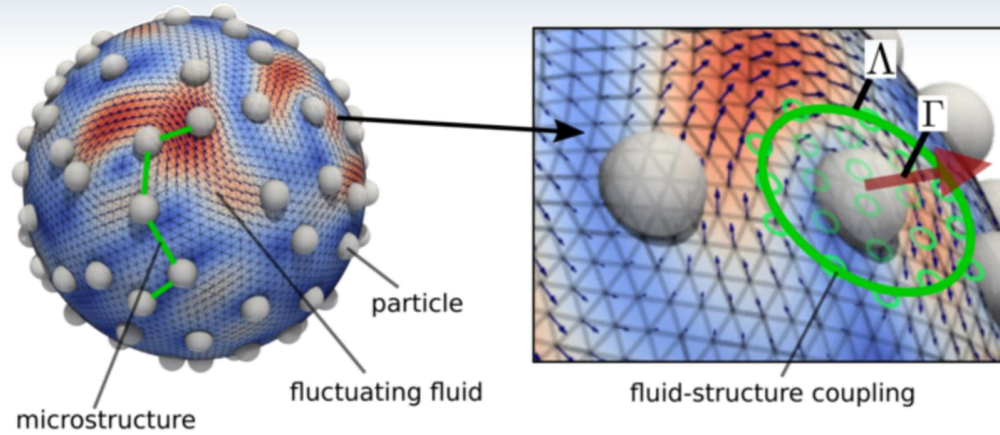
Rayleigh-Dissipation (Manifold C)



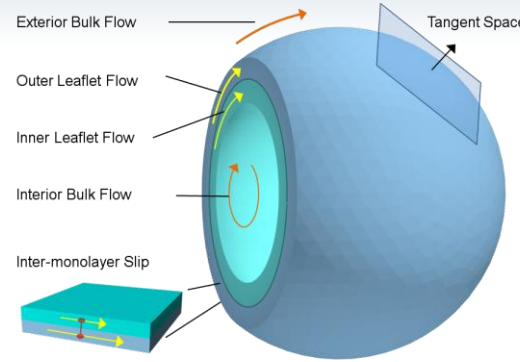
# Thermal Fluctuations

# Surface Fluctuating Hydrodynamics

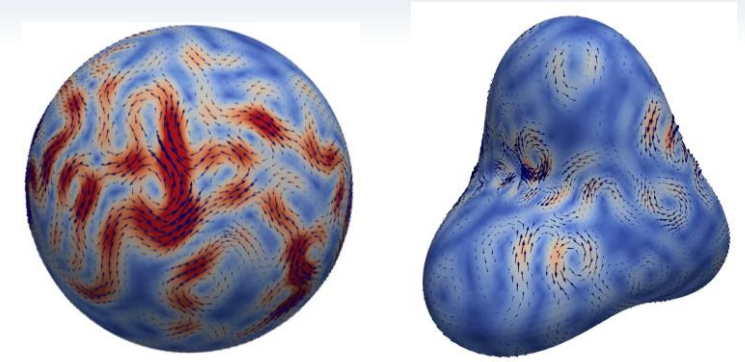
## Fluid-structure Interactions



## Hydrodynamics



## Fluctuating Fluid Velocity Fields



### Surface Fluctuating Hydrodynamics (Inertial Regime)

#### Fluid

$$\rho \frac{d\mathbf{v}^b}{dt} = \mu_m (-\delta d\mathbf{v}^b + 2K\mathbf{v}^b) - d\mathbf{p} + \mathbf{t}^b + \Lambda [\gamma (\mathbf{V} - \Gamma\mathbf{v}^b)] + \mathbf{f}_{thm}^b$$

$$-\delta\mathbf{v}^b = 0.$$

#### Microstructures

$$m \frac{d\mathbf{V}}{dt} = -\gamma (\mathbf{V} - \Gamma\mathbf{v}^b) - \nabla\phi + \mathbf{F}_{thm}$$

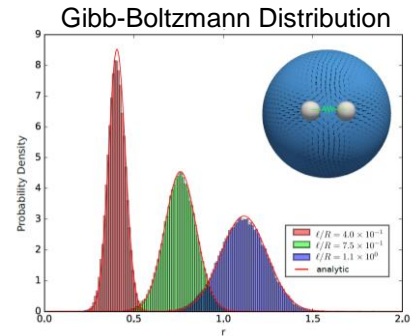
$$\frac{d\mathbf{X}}{dt} = \mathbf{V}.$$

#### Thermal Fluctuations

$$\langle \mathbf{f}_{thm}(t)\mathbf{f}_{thm}(s)^T \rangle = -2k_B T \mathcal{L}_{ff} \delta(t-s)$$

$$\langle \mathbf{F}_{thm}(t)\mathbf{F}_{thm}(s)^T \rangle = 2k_B T \gamma \mathcal{L} \delta(t-s)$$

$$\langle \mathbf{F}_{thm}(t)\mathbf{f}_{thm}(s)^T \rangle = -2k_B T \gamma \Gamma \delta(t-s).$$



$$\mathcal{L}_{ff} = \mathcal{L}_f - \gamma \Lambda \Gamma$$

$$\mathcal{L}_f = \mu_m (-\delta \mathbf{d} + 2K) + \mathcal{T}_f$$

### Surface Fluctuating Hydrodynamics (Overdamped)

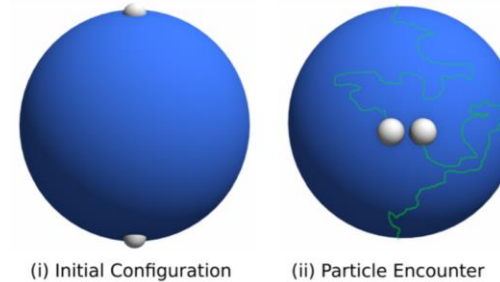
#### Microstructures

$$\frac{d\mathbf{X}}{dt} = \mathbf{M}\mathbf{F} + k_B T \nabla \cdot \mathbf{M} + \mathbf{F}_{thm}$$

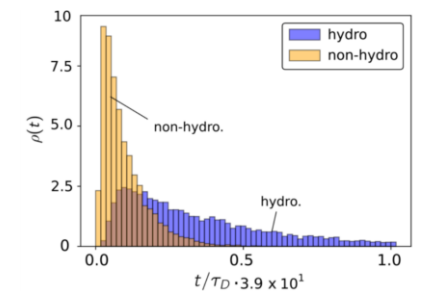
#### Thermal Fluctuations

$$\langle \mathbf{F}_{thm}(s)\mathbf{F}_{thm}(t)^T \rangle = 2k_B T \mathbf{M} \delta(t-s) \quad M_{ij} = \Gamma_i \mathcal{S} \Lambda_j$$

#### Particle Diffusive Encounters

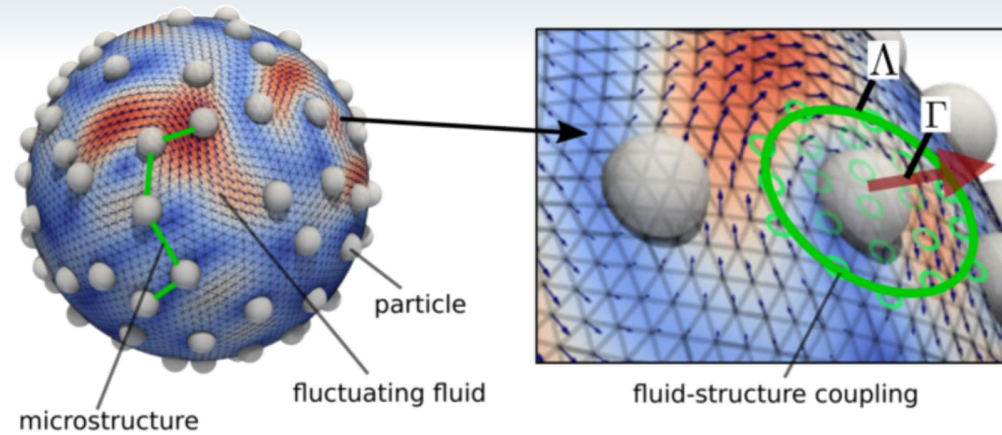


#### Two Particle Meeting Times

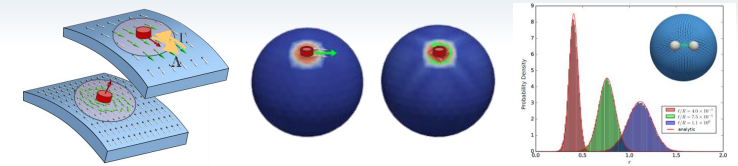


# Surface Fluctuating Hydrodynamics

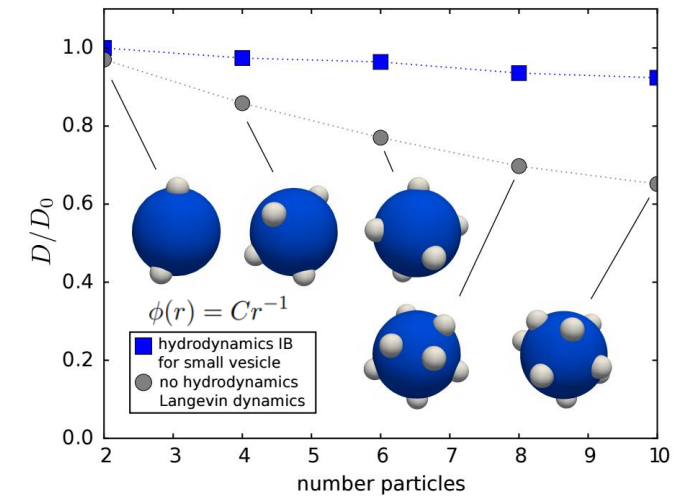
Fluid-structure interactions for drift-diffusion dynamics



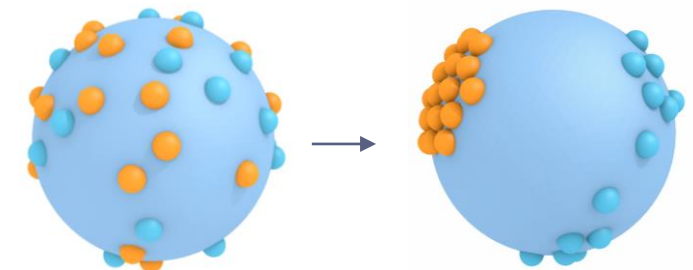
Immersed Boundary for Manifolds



Collective Diffusion



Collective Particle Drift-Diffusion



## Surface Fluctuating Hydrodynamics (Overdamped)

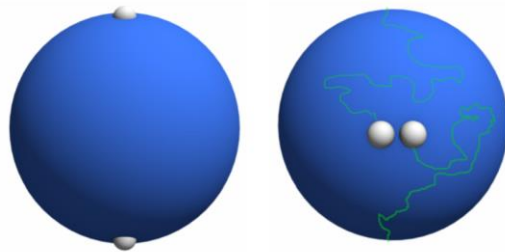
### Microstructures

$$\frac{d\mathbf{X}}{dt} = \mathbf{M}\mathbf{F} + k_B T \nabla \cdot \mathbf{M} + \mathbf{F}_{thm}$$

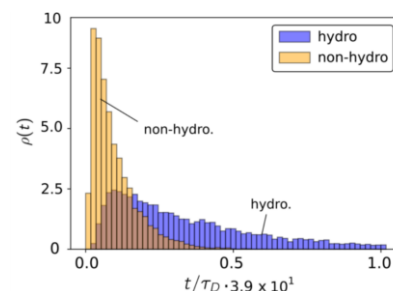
### Thermal Fluctuations

$$\langle \mathbf{F}_{thm}(s) \mathbf{F}_{thm}(t)^T \rangle = 2k_B T \mathbf{M} \delta(t - s)$$

### Particle Diffusive Encounters



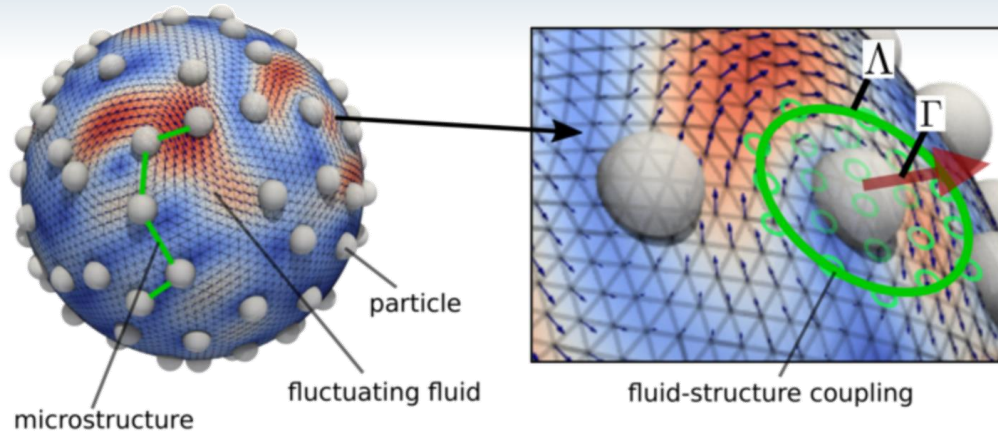
### Two Particle Meeting Times



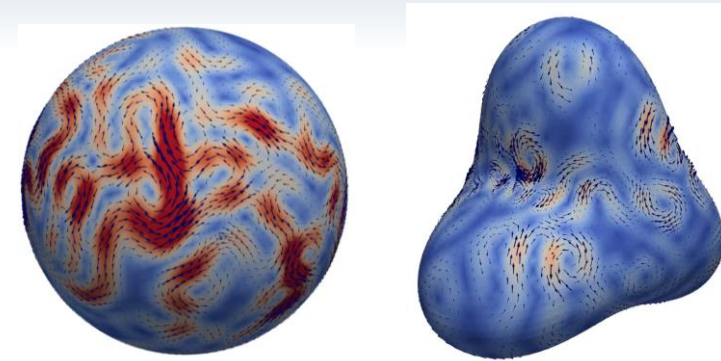


# Surface Fluctuating Hydrodynamics

## Fluid-structure Interactions



## Fluctuating Fluid Velocity Fields



### Surface Fluctuating Hydrodynamics (Inertial Regime)

#### Fluid

$$\rho \frac{d\mathbf{v}^b}{dt} = \mu_m (-\delta d\mathbf{v}^b + 2K\mathbf{v}^b) - d\mathbf{p} + \mathbf{t}^b + \Lambda [\gamma (\mathbf{V} - \Gamma\mathbf{v}^b)] + \mathbf{f}_{thm}^b$$

$$-\delta\mathbf{v}^b = 0.$$

#### Microstructures

$$m \frac{d\mathbf{V}}{dt} = -\gamma (\mathbf{V} - \Gamma\mathbf{v}^b) - \nabla\phi + \mathbf{F}_{thm}$$

$$\frac{d\mathbf{X}}{dt} = \mathbf{V}.$$

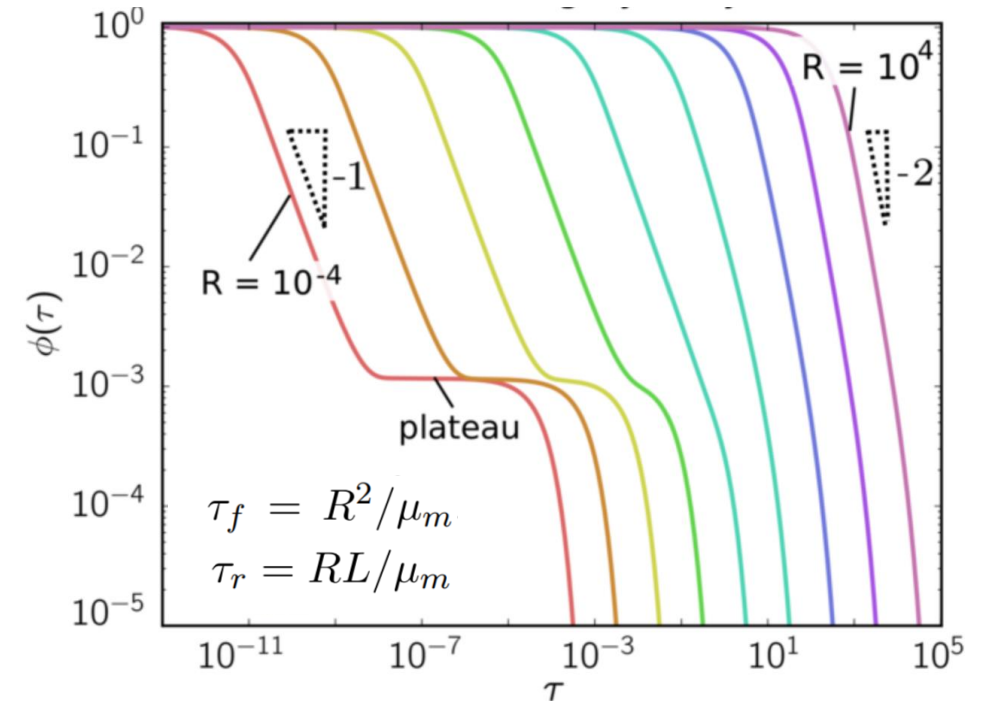
#### Thermal Fluctuations

$$\langle \mathbf{f}_{thm}(t)\mathbf{f}_{thm}(s)^T \rangle = -2k_B T \mathcal{L}_{ff} \delta(t-s)$$

$$\langle \mathbf{F}_{thm}(t)\mathbf{F}_{thm}(s)^T \rangle = 2k_B T \gamma \mathcal{L} \delta(t-s) \quad \mathcal{L}_{ff} = \mathcal{L}_f - \gamma \Lambda \Gamma$$

$$\langle \mathbf{F}_{thm}(t)\mathbf{f}_{thm}(s)^T \rangle = -2k_B T \gamma \Gamma \delta(t-s). \quad \mathcal{L}_f = \mu_m (-\delta\mathbf{d} + 2K) + \mathcal{T}_f$$

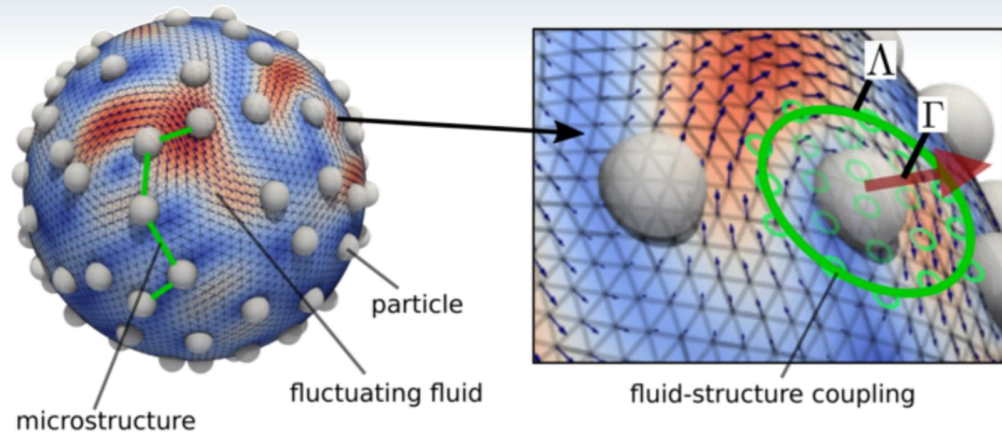
## Velocity Autocorrelations



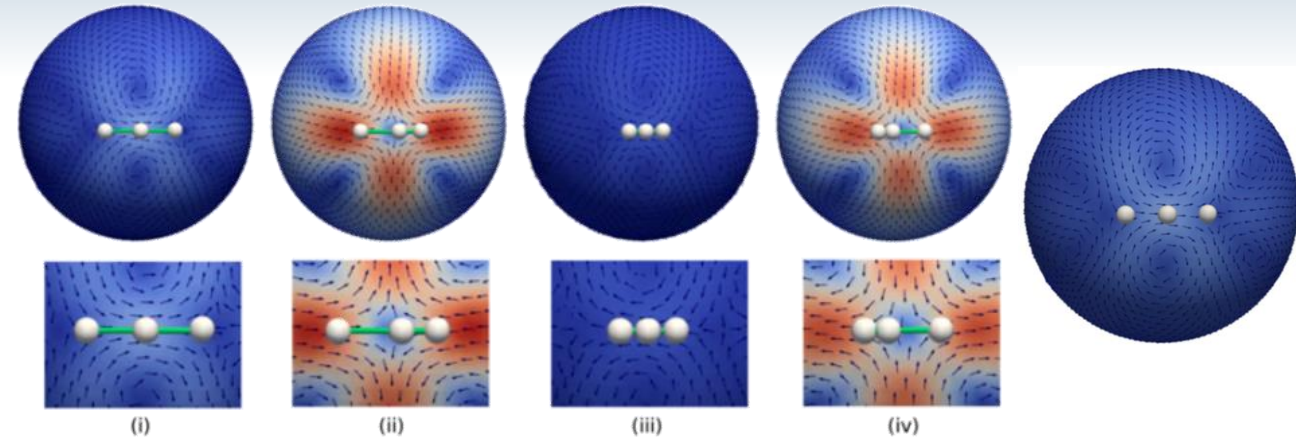
exhibits  $\tau^{-1}, \tau^{-2}$  power laws vs  $\tau^{-3/2}$  bulk fluids

# Surface Fluctuating Hydrodynamics

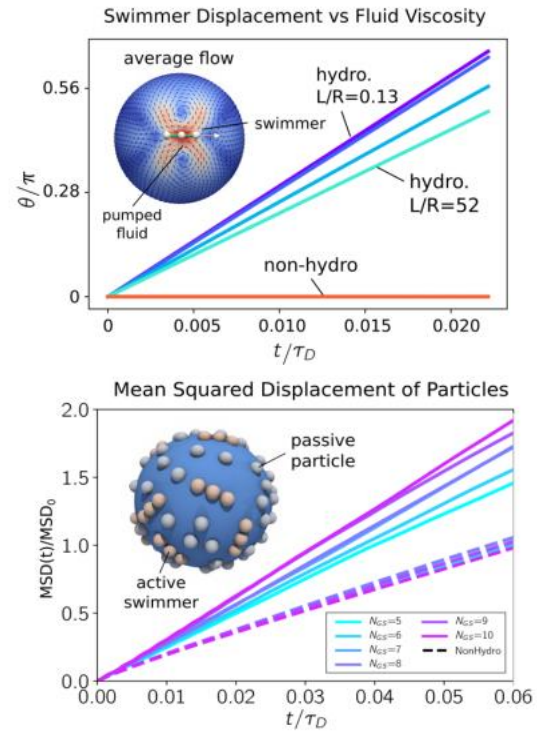
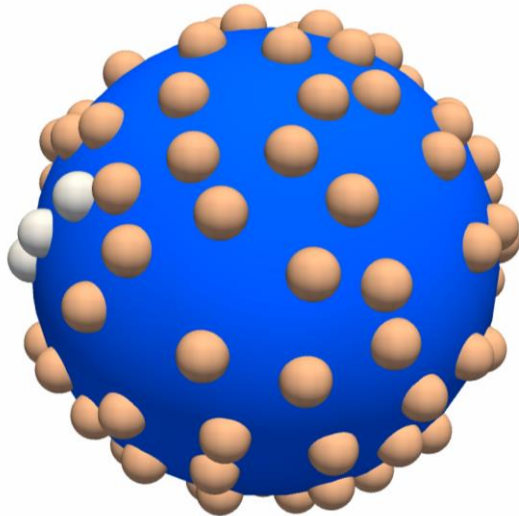
## Fluid-structure Interactions



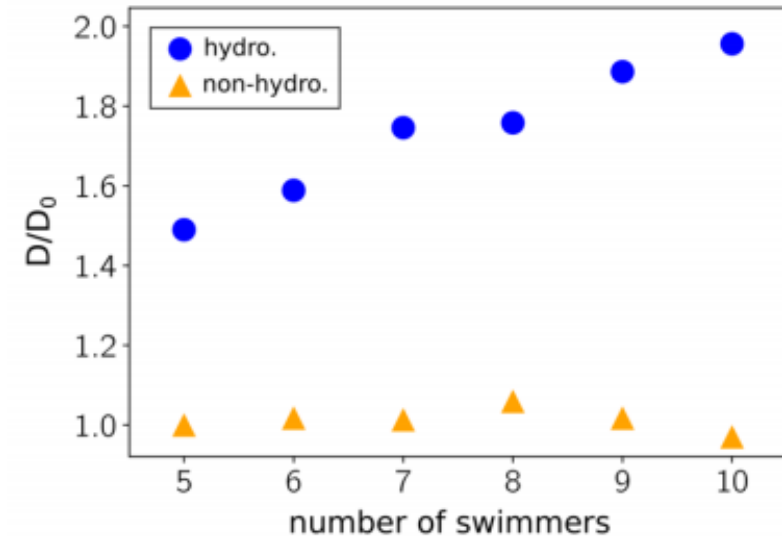
## Golestani Swim Cycle



## Active Mixing: Drift-Diffusion



## Particle Diffusivity





# Meshless Methods: Generalized Moving Least Squares (GMLS)

**PDEs on manifolds** present **challenges for discretization** and solvers from geometric contributions.

**Incompressible Hydrodynamic Surface Flow (vector-potential):**

$$\mu_m (-\delta d)^2 \Phi - \gamma \delta d \Phi - 2\mu_m (-\star d (K(-\star d \Phi))) = -\star db^b.$$

**GMLS methods developed** to obtain consistent high-order discretizations.

**Generalized Moving Least Squares:**

**Target operator:**  $\tau_{x_i}[u]$  with Banach space  $V$  and dual  $V^*$ .

Probing functionals:  $\Lambda[u] = (\lambda_1[u], \lambda_2[u], \dots, \lambda_N[u])$

**Find best reconstruction** of  $p^*$  in  $V_n$  of  $u$  in  $V$ .

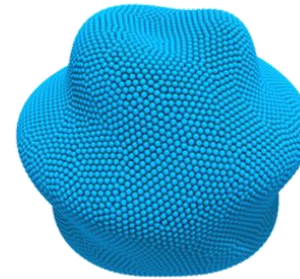
$$p^* = \arg \min_{p \in V_n} \sum_{j=1}^N (\lambda_j[u] - \lambda_j[p])^2 \omega(\lambda_j, \tau_{x_i})$$

**Approximate target operator**  $\tau_{x_i}[u]$  by

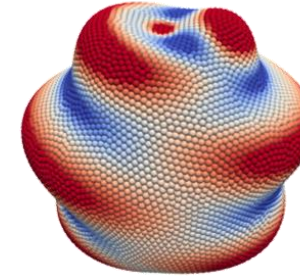
$$\tilde{\tau}[u] := \tau[p^*]$$

**PDEs on Manifolds:** GMLS both for geometric quantities and for operators acting on surface fields.

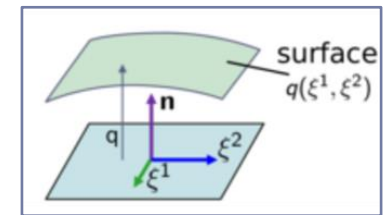
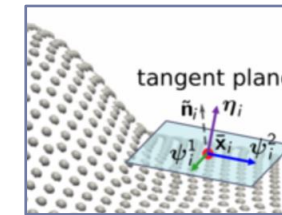
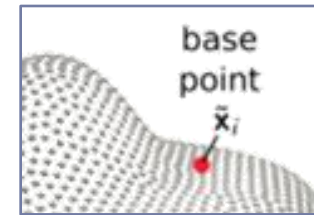
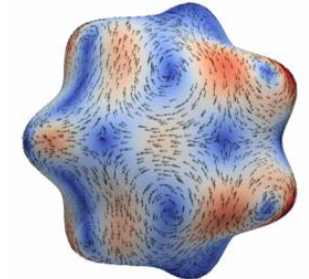
manifold representation



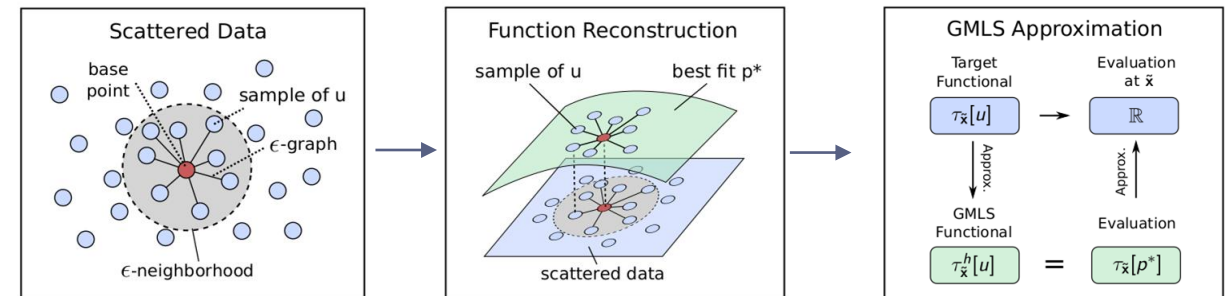
geometric quantities



surface fields



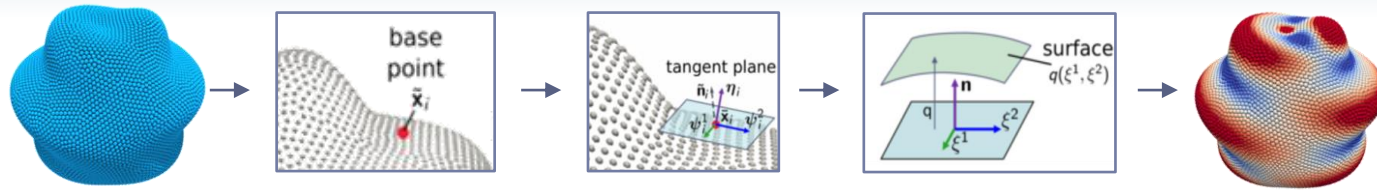
GMLS Approximation for PDEs on Manifolds



2020 Gross, Trask, Atzberger

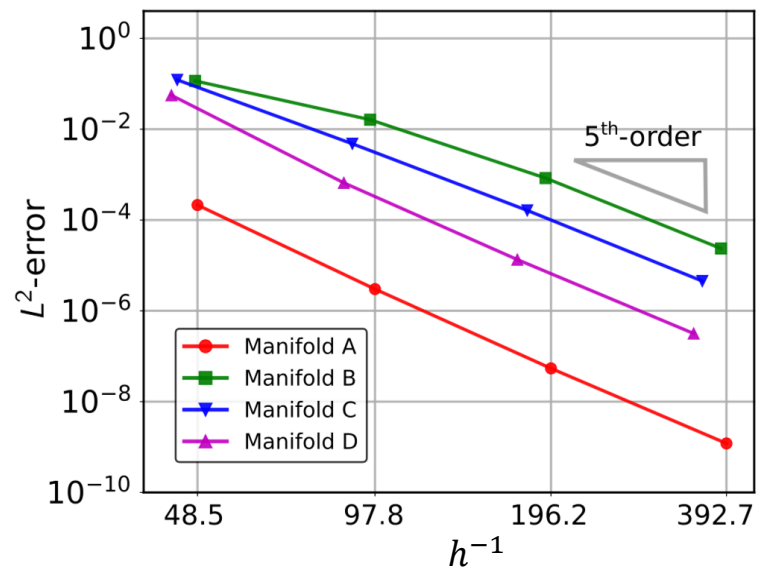
# Gaussian Curvature: GMLS Estimation

## GMLS Gaussian Curvature Estimation:



## Gaussian Curvature Accuracy

h	Manifold A		Manifold B		Manifold C		h	Manifold D	
	$l_2$ -error	Rate	$l_2$ -error	Rate	$l_2$ -error	Rate		$l_2$ -error	Rate
0.1	2.1351e-04	-	1.1575e-01	-	1.2198e-01	-	.08	5.5871e-02	-
0.05	3.0078e-06	6.07	1.6169e-02	2.84	4.7733e-03	4.67	.04	6.5739e-04	6.51
0.025	5.3927e-08	5.77	8.3821e-04	4.26	1.6250e-04	4.88	.02	1.3418e-05	5.67
0.0125	1.1994e-09	5.48	2.3571e-05	5.14	4.5204e-06	5.17	.01	3.1631e-07	5.37

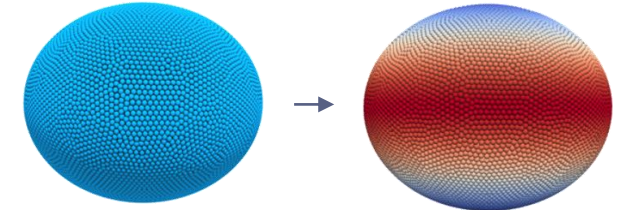


2019 Gross, Trask, Atzberger

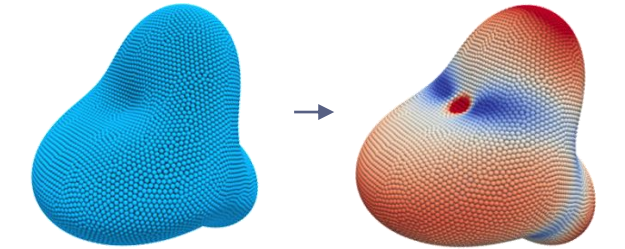
## Point Set

## Curvature

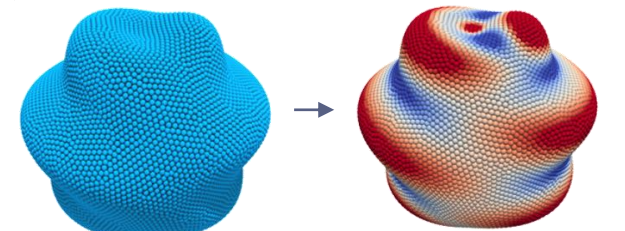
Manifold A



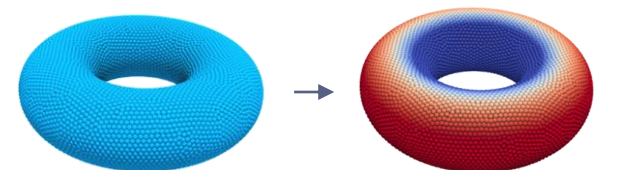
Manifold B



Manifold C



Manifold D

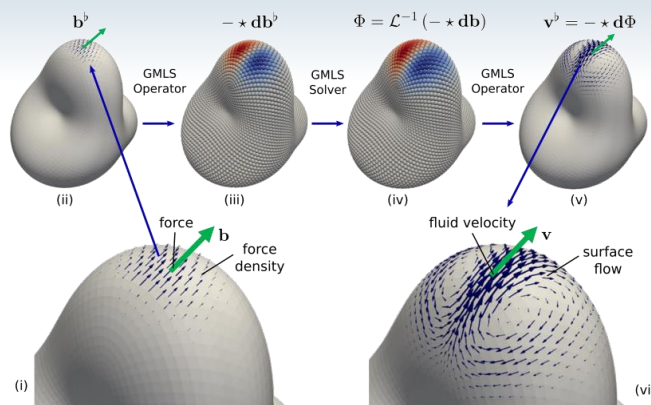
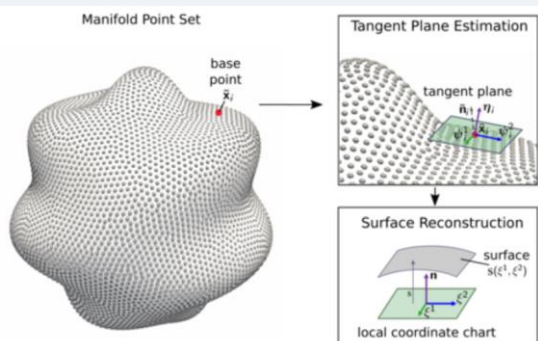
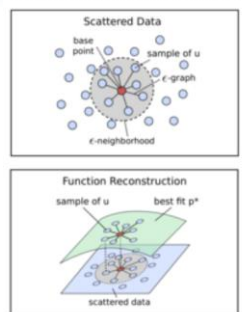




# GMLS Solvers for PDEs on Manifolds

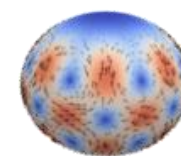
## PDEs on Manifolds and Solvers

Generalized Moving Least Squares

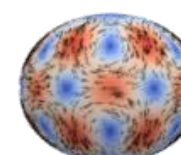


## Hydrodynamic Flows on Manifolds

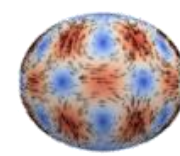
Manifold A



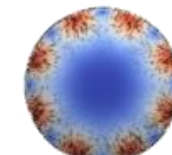
(i) Driving Force



(iii) Fluid Flow (y-axis)

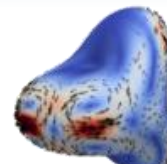


(ii) Fluid Flow (x-axis)



(iv) Fluid Flow (z-axis)

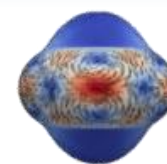
Manifold B



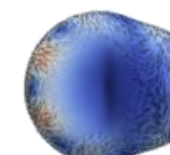
(i) Driving Force



(iii) Fluid Flow (y-axis)

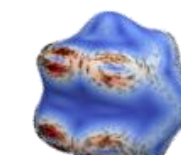


(ii) Fluid Flow (x-axis)

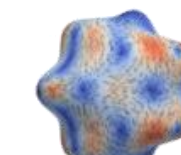


(iv) Fluid Flow (z-axis)

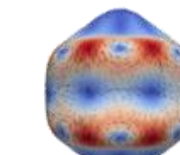
Manifold C



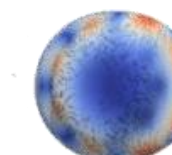
(i) Driving Force



(iii) Fluid Flow (y-axis)

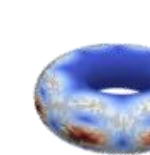


(ii) Fluid Flow (x-axis)



(iv) Fluid Flow (z-axis)

Manifold D



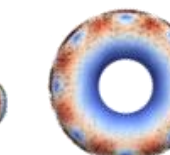
(i) Driving Force



(iii) Fluid Flow (y-axis)



(ii) Fluid Flow (x-axis)



(iv) Fluid Flow (z-axis)

**Regression** for learning geometric operators and developing solvers for PDEs on surfaces (transport equations / hydrodynamic flows).

**Fourth-order PDEs** with non-linear coupling geometry and differentiation via exterior calculus operators. **Collocation Method.**

**High-order Convergence:** Biharmonic equation for hydrodynamics.

$$\mu_m (-\delta d)^2 \Phi - \gamma \delta d \Phi - 2\mu_m (-\star d (K(-\star d \Phi))) = -\star db^b$$

h	$\ell_2$ -error	Rate	$\ell_2$ -error	Rate	$\ell_2$ -error	Rate
	$m = 4$		$m = 6$		$m = 8$	
0.1	9.7895e-02	-	6.5222e-02	-	2.8024e-01	-
0.05	1.4383e-02	2.77	2.8402e-03	4.52	1.2100e-02	4.53
0.025	3.6243e-03	1.98	3.9929e-04	2.82	4.9907e-04	4.59
0.0125	7.8747e-04	2.20	1.2357e-05	5.00	5.7023e-06	6.44

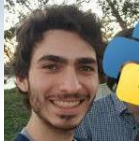
**Meshfree Methods on Manifolds for Hydrodynamic Flows on Curved Surfaces: A Generalized Moving Least Squares (GMLS) Approach,** B.J. Gross, N. Trask,, P. Kuberry, and P J. Atzberger, Journal of Computational Physics, Vol. 409, 15 May (2020) <https://doi.org/10.1016/j.jcp.2020.109340>

# Conclusions

# Conclusions



B. Gross



D. Rower

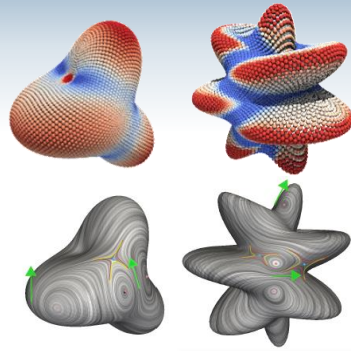


M. Padidar

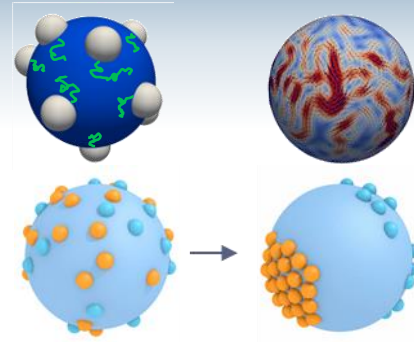


J. Sigurdsson

UCSB Student  
Collaborators



Meshless and Spectral Methods for  
Hydrodynamic Flow on Surfaces



Stochastic Drift-Diffusion Dynamics  
Hydrodynamic Coupling



Paper  
2016 Atzberger & Sigurdsson

## Summary

**Extended Saffman-Delbruck Approach** for hydrodynamics of curved membranes.

**Exterior calculus formulations and solvers** for mechanics on manifolds.

**Surface Fluctuating Hydrodynamics** for drift-diffusion dynamics of microstructures in membranes.

**Potential applications:** cell biology (vesicles, liposomes, organelles), solvers for other bio-problems.

## Papers

**Surface Fluctuating Hydrodynamics Methods for the Drift-Diffusion Dynamics of Particles and Microstructures within Curved Fluid Interfaces,**  
D. Rower, M. Padidar, and P. J. Atzberger, arXiv:1906.01146, (2019).

**Hydrodynamic Coupling of Particle Inclusions Embedded in Curved Lipid Bilayer Membranes**  
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