

Key

Backup notes if people are curious.

Ideally, write on board before presentation begins.

Usual pacing: 10 minutes / page.
⇒ ~25 minutes

The Gauss Green Theorem

The graph of $u: \mathbb{R}^{n-1} \rightarrow \mathbb{R}$ over $G \subseteq \mathbb{R}^{n-1}$ is

$$\Gamma(u; G) = \{(x, u(x)) : x \in G\}.$$

For brevity, set $\Gamma(u) = \Gamma(u, \mathbb{R}^{n-1})$.

Thm 9.1: For every $\varphi \in C_c^0(\mathbb{R}^n)$,

$$\int_{\Gamma(u)} \varphi \, d\mathcal{H}^{n-1} = \int_{\mathbb{R}^{n-1}} \varphi(z, u(z)) \sqrt{1 + |\nabla u(z)|^2} \, dz.$$

To prove thm. 9.1, we use...

(Recall) Remark 8.3: If $f: \mathbb{R}^{n-1} \rightarrow \mathbb{R}^n$ is an injective Lipschitz function and $\varphi \in C_c^0(\mathbb{R}^n)$,

$$\int_{f(\mathbb{R}^{n-1})} \varphi \, d\mathcal{H}^{n-1} = \int_{\mathbb{R}^{n-1}} \varphi(f(z)) Jf(z) \, dz.$$

Proof 9.1: Define $f: \mathbb{R}^{n-1} \rightarrow \mathbb{R}^n$ by $f(z) = (z, u(z))$, and note f is injective and Lipschitz.

We calculate the Jacobian of f and invoke theorem 8.1 and remark 8.3 to obtain the result.

□

Thm 9.3 (Gauss Green): If E is an open set with C^1 -boundary, then $\forall \varphi \in C_c^1(\mathbb{R}^n)$,

$$\int_E \nabla \varphi(x) dx = \int_{\partial E} \varphi \nu_E d\mathcal{H}^{n-1}.$$

Notation: Define $p: \mathbb{R}^n \rightarrow \mathbb{R}^{n-1}$ by $p(y_1, \dots, y_n) = (y_1, \dots, y_{n-1})$.
For $x \in \mathbb{R}^n$, $s > 0$,

$$\mathcal{C}(x, s) = \{y \in \mathbb{R}^n : \|px - py\| < s, |x_n - y_n| < s\}.$$

Proof: Step 1: Fix $x \in \partial E$.

There exists $s > 0$, $u \in C^1(B(px, s))$ s.t.

1. $\mathcal{C}(x, s) \cap E = \{y \in \mathcal{C}(x, s) : y_n > u(py)\}$.
2. $\mathcal{C}(x, s) \cap \partial E = \{y \in \mathcal{C}(x, s) : y_n = u(py)\}$.

For $\delta > 0$, define the Lipschitz function $f_\delta: \mathcal{C}(x, s) \rightarrow \mathbb{R}$ by

$$f_\delta(y) = \begin{cases} 0 & y_n > u(py) + \delta \\ \frac{1}{2\delta} (y_n - u(py) + \delta) & |u(py) - y_n| < \delta \end{cases}$$

For $\varphi \in C_c^1(\mathcal{C}(x, s))$,

$$\int_E \nabla \varphi = \int_{E \cap \mathcal{C}(x, s)} \nabla \varphi$$

$$\stackrel{\text{DCT}}{=} \lim_{\delta \rightarrow 0^+} \int_{\mathcal{C}(x, s)} f_\delta \nabla \varphi \quad // f_\delta \rightarrow \mathbb{1}_{\mathcal{C}(x, s) \cap E}$$

$$\stackrel{\text{IBP}}{=} - \lim_{\delta \rightarrow 0^+} \int_{\mathcal{C}(x, s)} \varphi \nabla f_\delta.$$

Skipping some steps,

$$- \lim_{\delta \rightarrow 0^+} \int_{B(x, \delta)} \varphi \nabla f_\delta$$

$$\stackrel{\star\star}{=} \int_{B(x, \delta)} \varphi(z, u(z)) \overset{\text{unit normal}}{v_E(z, u(z))} \sqrt{1 + |\nabla u(z)|^2} dz$$

$$\stackrel{\star}{=} \stackrel{\text{Thm 9.1}}{\int_{(x, \delta) \cap \partial E}} \varphi v_E d\mathcal{H}^{n-1}$$

$$= \int_{\partial E} \varphi v_E d\mathcal{H}^{n-1}$$

Step 2: Fix $\varphi \in C_c^1(\mathbb{R}^n)$.

Let A be an open set s.t. $\text{spt } \varphi \cap \partial E \subseteq A$.

We know

$$\{B(x, s) \subseteq A : x \in A \cap \partial E, s \text{ as in step 1}\}$$

is an open cover of $\text{spt } \varphi \cap \partial E$.

Let $\{B(x_k, s_k)\}_{k=1}^N$ be a finite subcover.

By step 1, $\forall 1 \leq k \leq N$, $\xi_k \in C_c^1(B(x_k, s_k))$,

$$\int_E \nabla(\xi_k \varphi) = \int_{\partial E} \xi_k \varphi v_E d\mathcal{H}^{n-1}.$$

A standard partition of unity argument gives the result.

□

★: $\mathcal{C}(x, s) \cap \partial E = \Gamma(u, B(p_x, s))$.

⊆: If $y \in \mathcal{C}(x, s) \cap \partial E$,

1. $|p_y - p_x| < s$.
2. $y_n = u(p_y)$.

So $y \in \Gamma(u, B(p_x, s))$.

⊇: If $y \in \Gamma(u, B(p_x, s))$, then

1. $|p_y - p_x| < s$.
2. $y_n = u(p_y)$.

We NTS $|y_n - x_n| < s$, i.e. $|u(p_y) - u(p_x)| < s$.
This follows by the implicit function thm.
See remark 9.2

Write
on board

★★: Take gradient of f , take $\delta \rightarrow 0$, use

$$v_E(y) = \frac{(\nabla u(p_y), -1)}{\sqrt{1 + |\nabla u(p_y)|^2}} \quad \forall y \in \mathcal{C}(x, s) \cap \partial E.$$