

Measure valued Regression

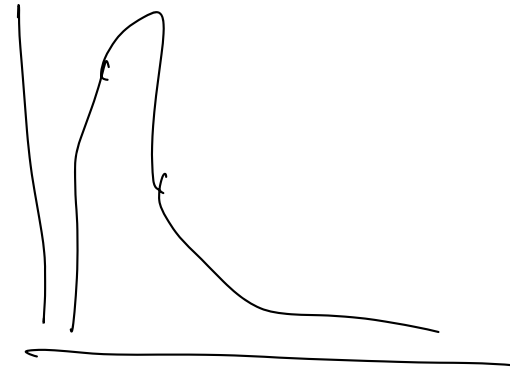
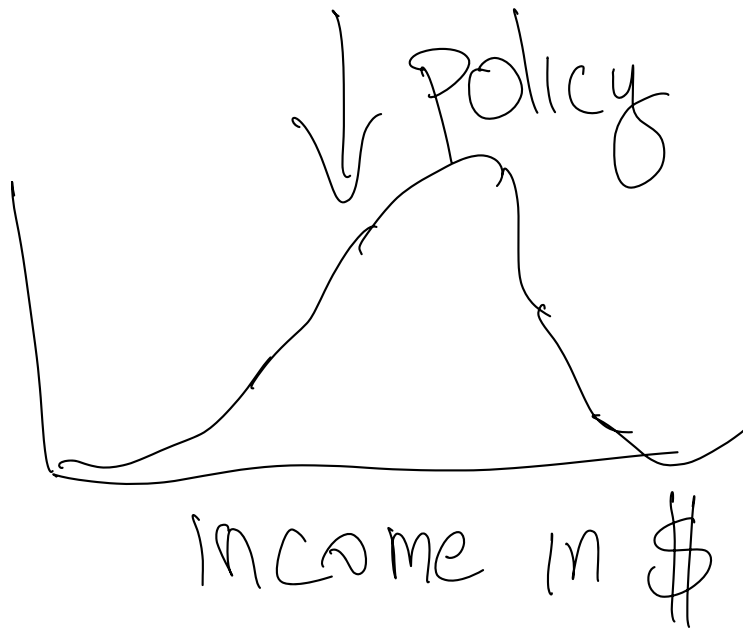
$$M: \mathcal{P}_2(\mathbb{R}^d)^K \rightarrow \mathcal{P}_2(\mathbb{R}^d)$$
$$(\mu_1, \dots, \mu_K) \mapsto \mathcal{L}$$

M is not an OT map but
we will build it using OT.

- ① Motivation
- ② Linearized OT
- ③ Wasserstein barycenters
(signed)
- ④ Put it together to do
measure valued regression

/ Distributional

↓ Synthetic controls (Gunsilius 2023)
Parallel Universe



We can observe the distribution
in our city at times
 $t_1, t_2, \dots, t_j$ $\nearrow$ T
Policy implementation

$\underbrace{\mu_{t_1}, \mu_{t_2}, \dots, \mu_{t_j}}_{\text{policy}}, \mu_T$

We can also observe distributions in other cities $i \in \{1, \dots, K\}$

$\underbrace{\mu_{t_1}^i, \mu_{t_2}^i, \dots, \mu_{t_j}^i}, \mu_I^i$

Want to use the μ_t and μ_t^i to learn a map

$$M: \mathbb{P}_2(\mathbb{R}^d)^K \rightarrow \mathbb{P}_2(\mathbb{R}^d)$$

for times t before policy implementation

$$\mathcal{L}_T^{cf} = M(u_T^1, \dots, u_T^K)$$

Now we can compare $\mathcal{L}_T$ to $\mathcal{L}_T^{cf}$ to determine if the policy had the desired effect.

We want our method to be explainable $\Rightarrow$ Let's choose a map that is as simple as possible (i.e. a "linear")

First approach to constructing linear maps

- Use linearized OT

Choose a reference measure

$$\mu \in \mathcal{P}_2(\mathbb{R}^d) \text{ s.t. } \mu$$

is a.c., then by Brenier's
thm, given any other measure
 $\nu \in \mathcal{P}_2(\mathbb{R}^d)$ there exists
a unique convex function

$$\varphi: \mathbb{R}^d \rightarrow \mathbb{R} \quad \text{s.t.}$$

$$\nabla \varphi \# \ell = \mu$$

This gives us a correspondence between

$$\mathcal{H}_2(\mathbb{R}^d) \longleftrightarrow \{ \varphi: \mathbb{R}^d \rightarrow \mathbb{R} : \varphi \text{ is convex and } \int_{\mathbb{R}^d} |\nabla \varphi(x)|^2 d\ell(x) < \infty \}$$

$$\varphi \text{ is convex and } \int_{\mathbb{R}^d} |\nabla \varphi(x)|^2 d\ell(x) < \infty \}$$

The space of convex functions is not a vector space but

It forms a cone in $H^1(e)$

$$= \left\{ f: \mathbb{R}^d \rightarrow \mathbb{R} : \int |\nabla f(x)|^2 dx < \infty \right\}$$

$$\psi = a_1 \varphi_1 + a_2 \varphi_2$$

Then ψ is a convex function
if $a_1, a_2 \geq 0$

Apply linearized OT to

the construction of the
map M & our previous
setup.

$$\mu_{t_1}^i \dashrightarrow \mu_{t_j}^i, \mu_T^i$$

$$\mathcal{L}_{t_1} \dashrightarrow \mathcal{L}_{t_j}, \mathcal{L}_T$$

Given a reference measure
 μ we can find OT
maps $\chi_{t_1}^i \dashrightarrow \chi_{t_j}^i, \chi_T^i$

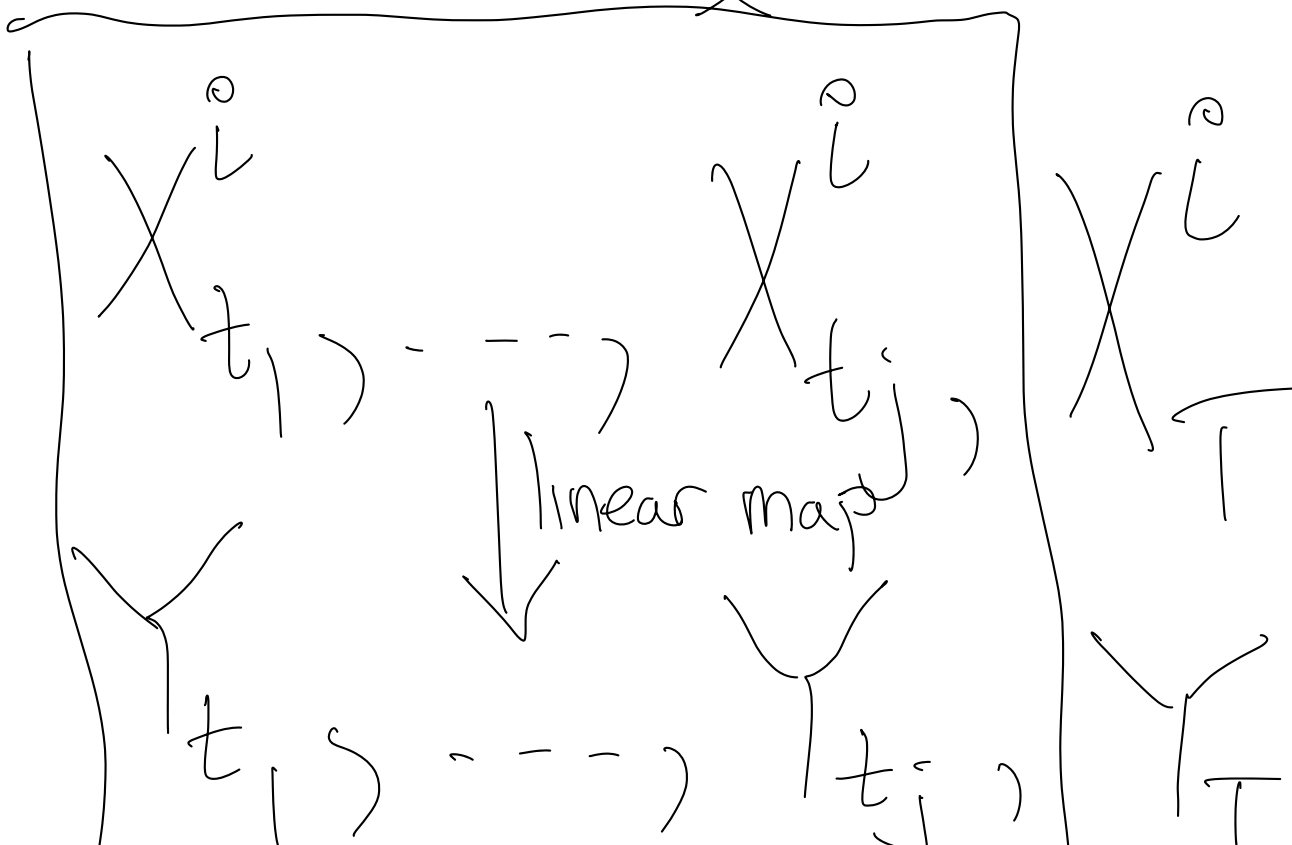
and

$$Y_{t_1}, \dots, Y_{t_j}, Y_T$$

so that

$$X_{t_\ell}^i \# e = u_{t_\ell}^i$$

$$Y_{t_\ell} \# e = L_{t_\ell}$$



Now we can use least squares regression to

learn $A: (\mathbb{R}^d)^K \xrightarrow{\text{map}} \mathbb{R}^d$

$$A \begin{pmatrix} x^1 \\ \vdots \\ x^K \end{pmatrix}$$

$$= Y$$

$$\sum_{l=1}^L \left\| \sum_{i=1}^K A^i x_{t_l}^i - Y_{t_l} \right\|_2^2$$

$\inf_{A: (\mathbb{R}^d)^K \rightarrow \mathbb{R}^d}$

$$\int_{\mathbb{R}^d} |A X_{t_j}^i(z) - Y_{t_j}(z)|^2 dz$$

$$Y = \sum_{i=1}^K A^i X_T^i$$

$$Y \# e = \mathcal{L}_T^{cf}$$

Without too much computation
 we get a linear map
 that sends $\mathbb{P}_2(\mathbb{R}^d)^K \rightarrow \mathbb{P}_2(\mathbb{R})$