# Characterizations of invertible matrices

Math 4A - Scharlemann

4 February 2015



**CELL PHONES OFF** 

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A given matrix may or may not be invertible, but if it is invertible, then there are an amazing number of equivalent facts true about the matrix, as we shall see.

Suppose A is an  $n \times n$  matrix A; then these are equivalent:

A is invertible.

- A is invertible.
- When put in echelon form, A has n pivot positions.
- When put in reduced echelon form, A becomes I<sub>n</sub>

Quick review

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- 2 When put in echelon form, A has n pivot positions.
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- **1** The columns of A are linearly independent.
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Suppose the only solution of the equation  $A\vec{x} = \vec{0}$  is  $\vec{x} = \vec{0}$ . Then there are no free variables in the system of equations given by  $A\vec{x} = \vec{0}$ , so all n positions are pivot positions.

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Suppose when put in echelon form, A has n pivot positions. Then the pivots occupy the whole diagonal, so when put in reduced echelon form, the matrix becomes  $I_n$ .

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Suppose when put in reduced echelon form, the matrix becomes  $I_n$ . We have seen that the same row operations applied to  $I_n$  will give  $A^{-1}$ . so A is invertible. 4 D > 4 A > 4 B > 4 B > B 9 9 0

## We have just shown that these are equivalent:

A is invertible.

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- There is an  $n \times n$  matrix C so that  $CA = I_n$ .
- ① There is an  $n \times n$  matrix D so that  $AD = I_n$ .
- $\triangle$   $A^T$  is invertible

Is the matrix

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 2 & 4 \\ 1 & 2 & 5 \end{bmatrix}$$

invertible?

- A Yes, the theorem says it is.
- B It's easy to see the theorem says it is not.
- C You can't easily say without doing a long calculation.

# You may have noticed that

$$-2 \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + 1 \cdot \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix} + 0 \cdot \begin{bmatrix} 3 \\ 4 \\ 5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

or equivalently

$$\begin{bmatrix} 1 & 2 & 3 \\ 1 & 2 & 4 \\ 1 & 2 & 5 \end{bmatrix} \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}.$$

So 4) is false. Since 4) is equivalent to A being invertible, A is not invertible.

### **Theorem**

A is invertible if and only if  $A^T$  is invertible. Indeed

$$(A^T)^{-1} = (A^{-1})^T$$

Proof: Suppose A is invertible and C is its inverse. Then  $AC = I_n = CA$ .

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This shows that  $C^T$  is an inverse for  $A^T$ .



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Easy to reverse the argument: If  $AD = I_n$  then A invertible.

## We now have that these are equivalent:

A is invertible.

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invertible?

- A Yes, the theorem says it is.
- B It's easy to see the theorem says it is not.
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## Discussion

Quick review

Observe that

$$B = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 3 & 4 & 5 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 2 & 4 \\ 1 & 2 & 5 \end{bmatrix}^{T} = A^{T}.$$

Since we know that A is not invertible, it follows from 10) that  $A^T = B$  is not invertible.

Recall: the product  $A\vec{x}$  is a vector that linearly combines (coefficients the entries in  $\vec{x}$ ) the column vectors in A.

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Since the first is black, we can color the second black.

By the same argument, these three statements are equivalent (but none is yet black)

- For each  $\vec{b} \in \mathbb{R}^n$  there is a solution of the equation  $A\vec{x} = \vec{b}$ .
- The columns of A span  $\mathbb{R}^n$ .
- Linear transformation  $A: \mathbb{R}^n \to \mathbb{R}^n$  is onto (surjective).

## This leaves us at:

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Suppose there is a D so that  $AD = I_n$ . Then for any  $\vec{b} \in \mathbb{R}^n$ , let  $\vec{x} = D\vec{b}$  and discover that  $A\vec{x} = A(D\vec{b}) = (AD)\vec{b} = I_n\vec{b} = \vec{b}$ .

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To complete an equivalence, we need to show:

## Theorem

Quick review

Suppose for each  $b \in \mathbb{R}^n$  there is a solution of the equation  $A\vec{x} = \vec{b}$ . Then there is an  $n \times n$  matrix D so that  $AD = I_n$ .

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Proof: For each  $\vec{e}_i$ ,  $1 \le i \le n$ , let  $\vec{d}_i$  be the solution to the equation  $A\vec{x} = \vec{e}_i$ . That is:

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## $\mathsf{Theorem}$

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Now set

$$D = \begin{bmatrix} \vec{d}_1 & \vec{d}_2 & \dots & \vec{d}_n \end{bmatrix}$$

Then

$$AD = A \begin{bmatrix} \vec{d}_1 & \vec{d}_2 & \dots & \vec{d}_n \end{bmatrix} = \begin{bmatrix} A\vec{d}_1 & A\vec{d}_2 & \dots & A\vec{d}_n \end{bmatrix} = \begin{bmatrix} \vec{e}_1 & \vec{e}_2 & \dots & \vec{e}_n \end{bmatrix} = I_n$$

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Suppose I tell you the equation

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has only the solution  $\vec{x} = \vec{0}$ . What can you say about the equation

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- There is at least one solution  $\vec{x}$ .
- There is at most one solution  $\vec{x}$ .
- C You can't easily say without doing a long calculation.

Discussion:
Let 
$$A = \begin{bmatrix} 1 & 1 & 1 \\ 2 & -1 & 0 \\ 3 & 4 & 5 \end{bmatrix}$$
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Quick review

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Then the hypothesis is that the only solution to  $A\vec{x} = \vec{0}$  is  $\vec{x} = \vec{0}$ .

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For each  $\vec{b}$  there is a solution to the equation  $A\vec{x} = \vec{b}$ .

So option A), there is at least one solution to the equation

$$\begin{bmatrix} 1 & 1 & 1 \\ 2 & -1 & 0 \\ 3 & 4 & 5 \end{bmatrix} \vec{x} = \begin{bmatrix} -1 \\ 7 \\ -3 \end{bmatrix}$$
 is correct.

Let 
$$A = \begin{bmatrix} 1 & 1 & 1 \\ 2 & -1 & 0 \\ 3 & 4 & 5 \end{bmatrix}$$
.

Then the hypothesis is that the only solution to  $A\vec{x} = \vec{0}$  is  $\vec{x} = \vec{0}$ . This is one of the black conditions, equivalent to A is invertible.

We have just seen that these are all equivalent to the green

conditions, including:

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 is correct.

Once we see that the last is also equivalent, option B) is also true: There is at most one solution  $\vec{x}$ .

The final item is brought into the equivalence via:

## Theorem

These are equivalent:

- The only solution to the equation  $A\vec{x} = \vec{0}$  is  $\vec{x} = \vec{0}$ .
- Linear transformation  $A: \mathbb{R}^n \to \mathbb{R}^n$  is one-to-one (injective)

Proof: Suppose A is injective. Then whenever  $A\vec{x} = \vec{0}$  we have  $A\vec{x} = \vec{0} = A\vec{0}$ ). But injectivity then implies  $\vec{x} = \vec{0}$ .

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Quick review

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$$A(\vec{u} - \vec{w}) = A\vec{u} - A\vec{w} = \vec{0}.$$

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$$A(\vec{u}-\vec{w})=A\vec{u}-A\vec{w}=\vec{0}.$$

The only solution to this equation is assumed to be 0. So  $\vec{u} - \vec{w} = \vec{0}$ , which means  $\vec{u} = \vec{w}$  and  $\vec{u}$ ,  $\vec{w}$  are not different.