Name: Key

Mathematics 108A: Quiz 3

July 24, 2008

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Part I. True-False. Circle the best answer to each of the following questions. Each question is worth 2 points.

1. The function $T: \mathbb{R}^3 \to \mathbb{R}^2$ defined by

$$T\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 3 & 1 & 5 \\ 2 & 4 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

is a linear map

TRUE

FALSE

2 Let \mathbb{R}^{∞} be the set of infinite sequences $(x_1, x_2, \dots, x_i, \dots)$, where each x_i is a real number The function $T: \mathbb{R}^{\infty} \to \mathbb{R}^{\infty}$ defined by

$$T(x_1, x_2, x_3, \dots) = (1, x_1, x_2, x_3, \dots)$$

is a linear map

TRUE

FALSE

3 Let $C^0(\mathbb{R})=\{$ continuous functions $f:\mathbb{R}\to\mathbb{R}$ $\}$, a vector space over \mathbb{R} with addition and scalar multiplication defined by

$$(f+g)(t)=f(t)+g(t), \quad (af)(t)=a(f(t)), \quad \text{for } f,g\in V \text{ and } a\in\mathbb{R}.$$

Then

$$T:C^0(\mathbb{R}) \to \mathbb{R}, \quad \text{defined by} \quad T(f)=5\int_0^1 f(t)dt,$$

is a linear map



FALSE

4. Let A be an $m \times n$ matrix with real coefficients. The range of the linear map $T_A : \mathbb{R}^n \to \mathbb{R}^m$, defined by $T_A(\mathbf{x}) = A\mathbf{x}$, is the space spanned by the rows of A.

TRUE



5. Let $V=\{$ infinitely differentiable functions $f:\mathbb{R}\to\mathbb{R}$ $\}$, a vector space over \mathbb{R} , and if t denotes the variable in the range, let

$$T:V\longrightarrow V$$
 be the linear map defined by $T(f)=rac{df}{dt}+5f$

Then the null space of T is the space of solutions to the differential equation

$$\frac{df}{dt} + 5f = 0.$$

TRUE

FALSE

Part II. Give complete answers to each of the following questions

1. (7 points) Find a basis for the null space of the linear transformation $T: \mathbb{R}^5 \to \mathbb{R}^3$, defined by

$$T\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix}) = \begin{pmatrix} 1 & -1 & 0 & -2 & -3 \\ 0 & 0 & 1 & -5 & -4 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix}$$

$$x_1 - x_2 \qquad -2x_4 - 3x_5 = 0$$

$$x_3 - 5x_4 - 4x_5 = 0$$

$$\begin{cases} x_1 = x_2 + 2x_4 + 3x_5 \\ x_2 = x_2 \\ x_3 = 5x_4 + 4x_5 \\ x_4 = x_4 \end{cases} = \begin{cases} x_1 \\ x_2 \\ x_3 \\ x_4 = x_5 \end{cases} = \begin{cases} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{cases} = \begin{cases} x_2 \\ 0 \\ 0 \\ 0 \end{cases} + \begin{cases} x_4 \\ 0 \\ 0 \\ 0 \end{cases} + \begin{cases} x_5 \\ 0 \\ 0 \\ 0 \end{cases} = \begin{cases} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{cases} = \begin{cases} x_2 \\ 0 \\ 0 \\ 0 \end{cases} + \begin{cases} x_4 \\ 0 \\ 0 \\ 0 \end{cases} + \begin{cases} x_5 \\ 0 \\ 0 \\ 0 \end{cases} = \begin{cases} x_5 \\ 0 \\ 0 \\ 0 \end{cases} + \begin{cases} x_5 \\ 0 \\ 0 \\ 0 \end{cases} + \begin{cases} x_5 \\ 0 \\ 0 \\ 0 \end{cases} = \begin{cases} x_5 \\ 0 \\ 0 \\ 0 \end{cases} + \begin{cases} x_5 \\ 0 \\ 0 \\ 0 \end{cases} = \begin{cases} x_5 \\ 0 \\ 0 \end{cases} = \begin{cases} x_5 \\ 0 \\ 0 \\ 0 \end{cases} = \begin{cases} x_5 \\ 0 \\ 0 \\ 0 \end{cases} = \begin{cases} x_5 \\ 0 \\ 0 \end{cases} = \begin{cases} x_5 \\ 0 \\ 0 \\ 0 \end{cases} = \begin{cases} x_5 \\ 0 \\ 0$$

2. (7 points) Suppose that $T:V\to W$ is a linear transformation. Show that

$$Null(T) = \{ \mathbf{v} \in V : T(\mathbf{v}) = \mathbf{0} \}$$

is a (linear) subspace of V.

- 1. $T(\vec{o}) = T(\vec{o} + \vec{o}) = T(\vec{o}) + T(\vec{o})$ $\Rightarrow \vec{o} = T(\vec{o}) \Rightarrow \vec{o} \in Null(T)$
- 2. If $\overrightarrow{\nabla}$, $\overrightarrow{\nabla} \in \text{Null}(T)$, $\overrightarrow{T}(\overrightarrow{\nabla}) = \overrightarrow{O}$, $\overrightarrow{T}(\overrightarrow{N}) = \overrightarrow{O}$.

 Hence $\overrightarrow{T}(\overrightarrow{\nabla} + \overrightarrow{N}) = \overrightarrow{T}(\overrightarrow{\nabla}) + \overrightarrow{T}(\overrightarrow{N}) = \overrightarrow{O} + \overrightarrow{O} = \overrightarrow{O}$ $\overrightarrow{\nabla} + \overrightarrow{N} \in \text{Null}(T)$.
- 3. If $\vec{V} \in \text{Null}(T)$, $\alpha \in \vec{F}$, then $T(\vec{V}) = \vec{O}$ Nence $T(\vec{OV}) = \alpha T(\vec{V}) = \alpha \cdot \vec{O} = \vec{O}$ $\vec{A} = \vec{V} \in \text{Null}(T)$.

3. (7 points) Recall the basic lemma from Chapter 2 of the text by Axler:

Linear Dependence Lemma. Suppose that $(\mathbf{v}_1, \dots, \mathbf{v}_m)$ is a linearly dependent list of vectors in a finite-dimensional vector space V and that $\mathbf{v}_1 \neq \mathbf{0}$. Then there exists $j \in \{2, \dots, m\}$ such that $\mathbf{v}_j \in \operatorname{span}(\mathbf{v}_1, \dots, \mathbf{v}_{j-1})$. Moreover,

$$\text{span}(\mathbf{v}_1,\ldots,\mathbf{v}_{j-1},\mathbf{v}_{j+1},\ldots\mathbf{v}_m) = \text{span}(\mathbf{v}_1,\ldots,\mathbf{v}_m)$$

Use the Linear Dependence Lemma to prove the following:

Theorem. Every spanning list in a vector space V can be reduced to a basis

Hint: The idea of the proof is to start with a spanning list and throw away elements until you have a basis $\frac{1}{2}$

Suppose that $V = \text{Span}(\vec{V}_1, ..., \vec{V}_n)$ Start with the list $L_0 = (\vec{V}_1, ..., \vec{V}_n)$

For each j, I s j s n, ask whether V; is in the span of the list bijn. If so, throw it away obtaining a new list Lj. If not, let Lj = bull

Repeat this process in times obtaining a list Ln which spans V.

If the list Ln were linearly dependent, one of the Vira in Ln would be in the spon of the previous elements by the Linear Dependence Lemma.

This is not the case, so Ln is linearly independent in Ln is a basis for V.