Math 104A - Homework 2 Due 6/30

Section 1.3 - 1, 7a, 7d, 11 Section 2.1 - 6, 8, 20 Section 2.2 - 5, 8, 14 Section 2.3 - 5, 33

1.3.1a Use three-digit chopping arithmetic to compute the sum $\sum_{i=1}^{10} \frac{1}{i^2}$ first by $\frac{1}{1} + \frac{1}{4} + \cdots + \frac{1}{100}$, and then by $\frac{1}{100} + \frac{1}{81} + \cdots + \frac{1}{1}$. Which method is more accurate, and why?

Using three-digit chopping arithmetic,

$$\frac{1}{1} + \frac{1}{4} + \frac{1}{9} + \dots + \frac{1}{100} = (\dots ((1.00 + 0.250) + 0.111) + \dots) + 0.0100) = 1.53,$$

while

$$\frac{1}{100} + \frac{1}{81} + \frac{1}{64} + \dots + \frac{1}{1} = (\dots ((0.0100 + 0.0123) + 0.0156) + \dots) + 1.00) = 1.54.$$

The actual value is 1.5498. The first sum is less accurate because the smaller numbers are added last, resulting in significant round-off error.

1.3.1b Write an algorithm (pseudocode) to sum the finite series $\sum_{i=1}^{N} x_i$ in reverse order. (Here, the input is N, x_1, \ldots, x_N , and the output is the sum).

INPUT: N, x_1, \dots, x_N OUTPUT: $\sum_{i=1}^N x_i$ Step 1: Set i = N, s = 0. Step 2: While i > 0 do Steps 3-4 Step 3: Set $s = s + 1/i^2$. Step 4: Set i = i - 1. Step 5: OUTPUT s.

1.3.7a Find the rate of convergence of $\lim_{h\to 0} \frac{\sin h}{h} = 1$ (Hint: use Taylor series).

$$\left|\frac{\sin(h)}{h} - 1\right| = \left|\frac{h - \frac{h^3}{6}\cos(\xi)}{h} - 1\right| = \left|-\frac{h^2}{6}\sin(\xi)\right| = O(h^2).$$

1.3.7b Find the rate of convergence of $\lim_{h\to 0} \frac{1-e^h}{h} = -1$.

$$\left|\frac{1-e^{h}}{h}+1\right| = \left|\frac{1-1-h-\frac{h^{2}}{2}e^{\xi}}{h}+1\right| = \left|-\frac{h}{2}e^{\xi}\right| = O(h).$$

1.3.11 Construct an algorithm (pseudocode) that has as input an integer $n \ge 1$, numbers x_0, x_1, \ldots, x_n , and a number x that produces as output the product $(x - x_0)(x - x_1) \cdots (x - x_n)$.

```
INPUT: n, x_0, \dots, x_n, x.

OUTPUT: \prod_{i=0}^{n} (x - x_i).

Step 1: Set i = 0, p = 1.

Step 2: While i \le n do Steps 3-4

Step 3: Set p = p * (x - x_i).

Step 4: Set i = i + 1.

Step 5: OUTPUT p.
```

- **2.1.6** Use the Bisection method to find solutions accurate to within 10^{-5} for the following problems:
 - **a** $3x e^x = 0, x \in [1, 2].$

Using the attached code (bisection_method.m), we got

```
>> bisection_method('3*x-exp(x)',1,2,1000,10^-5)
ans =
    1.512138366699219
```

b $x + 3\cos x - e^x = 0, x \in [0, 1].$

```
Using the attached code (bisection_method.m), we got
```

c $x^2 - 4x + 4 - \ln x = 0, x \in [1, 2]$ and $x \in [2, 4]$.

```
Using the attached code (bisection_method.m), we got
```

```
>> bisection_method('x^2-4*x+4-log(x)',1,2,1000,10^-5)
ans =
    1.412391662597656
>> bisection_method('x^2-4*x+4-log(x)',2,4,1000,10^-5)
ans =
    3.057106018066406
```

d $x + 1 - 2\sin(\pi x) = 0, x \in [0, 0.5]$ and $x \in [0.5, 1]$.

```
Using the attached code (bisection_method.m), we got
>> bisection_method('x+1-2*sin(pi*x)',0,0.5,1000,10^-5)
ans =
        0.206031799316406
>> bisection_method('x+1-2*sin(pi*x)',0.5,1,1000,10^-5)
ans =
        0.681968688964844
```

2.1.8a Sketch the graphs of y = x and $y = \tan x$.



2.1.8b Use the bisection method to find an approximation to within 10^{-5} to the first positive value of x with $x = \tan x$.

From the sketch, we see that the first positive fixed-point occurs somewhere between 4 and 5. Using the attached code (bisection_method.m), we got

2.1.20 A particle starts at rest on a smooth inclined plane whose angle θ is changing at a constant rate $\frac{d\theta}{dt} = \omega < 0$. At the end of t seconds, the position of the object is given by

$$x(t) = -\frac{g}{2\omega^2} \left(\frac{e^{\omega t} - e^{-\omega t}}{2} - \sin(\omega t) \right).$$

Suppose the particle has moved 1.7 ft in 1 s. Find, to within 10^{-5} , the rate ω at which θ changes. Assume that g = 32.17 ft/s².

Substituting the appropriate values, we find ω by finding the root of

$$f(x) = -\frac{32.17}{2x^2} \left(\frac{e^x - e^{-x}}{2} - \sin(x)\right) - 1.7.$$

Using the attached code (bisection_method.m), we got

>> bisection_method('-32.17/(2*x^2)*((exp(x)-exp(-x))/2... -sin(x))-1.7',-1,-0.1,1000,10^-5)
ans =

-0.317055511474609

2.2.5 Use a fixed-point iteration method to determine a solution accurate to within 10^{-2} for $x^4 - 3x^2 - 3 = 0$ on [1, 2]. Use $p_0 = 1$.

After first rearranging the equation to get $(3x^2+3)^{1/4} = x$, we use attached code (fixed_point_method.m) to get

```
>> fixed_point_method('(3*x^2+3)^(1/4)',1,1000,10^-2)
Took 6 iterations.
ans =
    1.943316929898677
```

2.2.8 Use theorem 2.2 to show that $g(x) = 2^{-x}$ has a unique fixed point on $[\frac{1}{3}, 1]$. Use fixed-point iteration to find an approximation to the fixed point accurate to within 10^{-4} . Use corollary 2.4 to estimate the number of iterations required to achieve 10^{-4} accuracy, and compare this theoretical estimate to the number actually needed.

Since g is decreasing, we know that

$$\max g(x) = g(\frac{1}{3}) \approx 0.793700526 < 1,$$

$$\min g(x) = g(1) = 0.5 > \frac{1}{3},$$

and so $g(x) \in [\frac{1}{3}, 1]$. Since $g'(x) = -2^{-x} \ln(2)$ is negative and increasing, we know that $|g'(x)| \leq |g'(\frac{1}{3})| \approx 0.550151282 = k < 1$. Then g satisfies the conditions of theorem 2.2, and so g has a unique fixed point on the interval $[\frac{1}{3}, 1]$.

Using the attached code (fixed_point_method.m), we get

so 8 iterations are necessary to be within 10^{-4} of the true fixed point p = 0.641185744504986. By corollary 2.4, $|p_n - p| \le \frac{k^n}{3}$, and so

$$\frac{k^n}{3} \le 10^{-4}$$
$$\ln(k^n) \le \ln(3 \cdot 10^{-4})$$
$$n \ge \frac{\ln(3 \cdot 10^{-4})}{\ln(k)} \approx 13.5747058.$$

2.2.14 Use a fixed-point iteration method to determine a solution accurate to within 10^{-4} for $x = \tan x$, for $x \in [4, 5]$.

Rearranging the equation so that $g(x) = \frac{1}{\tan(x)} - \frac{1}{x} + x$ and using the attached code (fixed_point_method.m), we get

- **2.3.5** Use Newton's method to find solutions accurate to within 10^{-4} for the following problems:
 - **a** $x^3 2x^2 5 = 0, x \in [1, 4].$

Using the attached code (newtons_method.m), we get

```
>> newtons_method('x^3-2*x^2-5','3*x^2-4*x',2.5,1000,10^-4)
Took 4 iterations
ans =
        2.690647448028615
```

b $x^3 + 3x^2 - 1 = 0, x \in [-3, -2].$

Using the attached code (newtons_method.m), we get

```
>> newtons_method('x^3+3*x^2-1','3*x^2+6*x',-2.5,1000,10^-4)
Took 5 iterations
ans =
    -2.879385241571822
```

c $x - \cos x = 0, x \in [0, \pi/2].$

Using the attached code (newtons_method.m), we get

```
>> newtons_method('x-cos(x)','1+sin(x)',pi/4,1000,10^-4)
Took 3 iterations
ans =
        0.739085133215161
```

d $x - 0.8 - 0.2 \sin x = 0, x \in [0, \pi/2].$

Using the attached code (newtons_method.m), we get

```
>> newtons_method('x-0.8-0.2*sin(x)','1-0.2*cos(x)',pi/4,1000,10^-4)
Took 3 iterations
ans =
        0.964333887695271
```

2.3.33 Player A will shut out (win by a score of 21-0) player B in a game of raquetball with probability

$$P = \frac{1+p}{2} \left(\frac{p}{1-p+p^2}\right)^{21},$$

where p is the probability that A will win any specific rally (independent of the server). Determine, to within 10^{-3} , the minimal value of p that will ensure that A will shut out B in at least half the matches they play.

From a sketch of the graph, we see that p is close to 0.8, so we use the bisection method (bisection_method.m) with an initial interval [0.7, 0.9] with function $f(x) = \frac{1+x}{2} \left(\frac{x}{1-x+x^2}\right)^{21} - 0.5$:

```
>> bisection_method('(1+x)/2*(x/(1-x+x^2))^21-0.5',...
0.7,0.9,1000,10^-4)
```

ans =

0.84296875000000

Code

```
%%% bisection_method.m %%%
```

```
function p = bisection_method(fstring,a,b,N,TOL)
```

```
i=1;
    f = inline(fstring);
    FA = f(a);
    while ( i <= N )
        p = (a+b)/2;
        FP = f(p);
        if( FP == 0 || (b-a)/2 < TOL)
            return;
        end
        if( FA*FP > 0 )
            a = p;
            FA = FP;
        else
            b = p;
        end
        i = i+1;
    end
end
%%% end of bisection_method.m %%%
%%% fixed_point_method.m %%%
function p = fixed_point_method(fstring,p0,N,TOL)
    i = 1;
    f = inline(fstring);
    while i < N
        p = f(p0);
        if ( nargin == 4 \&\& abs(p-p0) < TOL )
```

```
fprintf('Took %i iterations.',i);
            return;
        end
        p0 = p;
        i = i+1;
    end
end
%%% end of fixed_point_method.m %%%
%%% newtons_method.m %%%
function p = newtons_method(fstring,fpstring,p0,N,TOL)
    i = 1;
    f = inline(fstring);
    fp = inline(fpstring);
    while( i <= N )</pre>
        p = p0-f(p0)/fp(p0);
        if( abs(p-p0) < TOL )</pre>
            fprintf('Took %i iterations',i);
            return;
        end
        i = i+1;
        p0=p;
    end
end
```

```
%%% end newtons_method.m %%%
```